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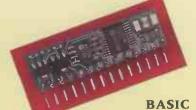
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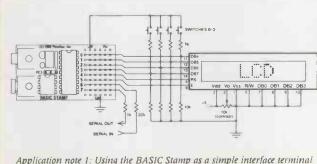
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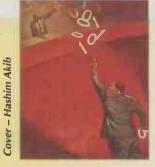
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#### **Combined July-August issue** Watch out for the next issue of *Electronics World*

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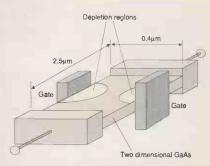


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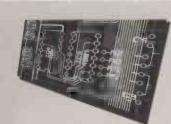




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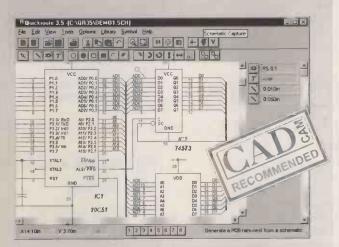
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CADCAM, March 1996

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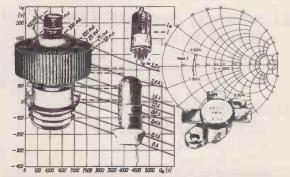


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### Thanks – but no thanks

Over many years, I have watched in horror as electronics companies launched products which seemed to have been designed without any thought for the paying customer. Even as they hit the market, we just knew they were going to fail.

This represents a tricky dilemma journalists covering electronics. Should we write off the product as a flop, and thereby help to make it one? Or should we try to give it a helping hand, thereby putting consumers at risk of buying something that will later become obsolete?

In the case of Sir Clive Sinclair's C5 trike, it was an easy call. No matter that the battery went flat as quickly as anyone who has flattened a car battery with the starter could have predicted. Had Sir Clive ever actually tried taking one out on a busy road, and seen how it felt to be next to the wheels of a lorry?

Last year ICL and Fujitsu joined forces to launch the Indiana range of PCTVs. Soon after Olivetti followed suit with Envision. These three companies had one thing in common; no experience in consumer electronics. Even so it is hard to imagine how their designers could have made such a basic mistake.

Although the idea of using one tv screen for both a pc and tv is superficially seductive, there is an obvious and fatal flaw. Television screens are intended to display relatively low resolution tv transmissions. They look fine from across the room. Move close to a tv set you see interlace jitter; horizontal lines flicker vertically as the fields change. On 50Hz PAL sets, there is the added problem of wide area flicker on bright white images. The colour shadow-mask pitch is coarse, to match the tv scanning raster. So PC text and graphics look coarse too.

A tv screen makes a rotten pc display. That is why, after the era of Sinclair Spectrums and Amstrads, the pc industry moved away from tv standards, to higher refresh rates, and started to sell pcs with dedicated monitors.

Did anyone inside ICL, Fujitsu and Olivetti ever sit down in front of their own PCTVs and actually try some serious word processing, database building or spread sheet design? Apparently not.

Like blood from a stone I have now squeezed the admission that production of Indiana and Envision stopped

last winter, and neither ICL/Fujitsu or Olivetti has any firm plans for the future.

Philips developed Laservision, the 12in optical video disc, in the seventies. Rival electronics companies all round the world very quickly saw the elegance of laser read-out and gave up their research on alternative systems. Never mind that Laservision was launched later than promised, and was thus faced with competition from the vcr. The technology spawned CD, CD-ROM and recordable disc.

Stubbornly, RCA pressed ahead with CED Selectavision, a 12in grooved capacitance disc that needed a caddy. It was launched in the US and UK, but plain as pikestaff never had a chance. Hardly a disc played without skipping and the player had to incorporate a 'nudge control' to knock the stylus when it stuck in the groove. RCA's blinkered vision cost the company so much in hard cash that its name and trade infrastructure were bought by Thomson of France.

Commodore once had a healthy share of the computer and games market. Seeing Philips preparing for the launch of CD-interactive, Commodore dreamed up the idea of CDTV – an Amiga-based interactive CD that was incompatible with the Philips format. Commodore hoped that by rushing to the market ahead of Philips, CDTV would become the *de facto* standard.

One selling point was that the CDTV player was also a CD player. So how could Commodore have made the basic mistake of using a computer CD-ROM drive that played discs only when loaded into a caddy? Commodore's answer was that CD data discs need protection from finger marks.

With caddies costing around £5 a time, it was impractical to give one away with each CDTV disc. Audio CDs come in jewel boxes, anyway. So Commodore gave away one free caddy with each player and the owner had to load each disc in the caddy before playing it.

Instead of taking a CD out of its jewel box and loading it into a CD player tray, the owner had to take the CD out of the jewel box, and load it in the caddy before loading the caddy in the player. There was no less handling of the disc, just extra inconvenience.

The caddy issue raises its ugly head again later this year, but from the opposite direction. Toshiba, Thomson and Time-Warner are promising to launch high density DVD movie players, with Philips, Sony and others following next year, in less of a rush. By early May there was still no final agreement on vital standards issues, such as copy protection to prevent people dubbing high quality movies from disc to tape, and regional control, to stop movies released in the USA playing on European players.

But there is one issue on which the DVD Alliance is solid. Having learned from Commodore's mistake on CDTV the hardware and software companies have pledged that the DVD system will not need a caddy. Discs will be packaged like ordinary CDs and loaded direct into a tray in the player.

How strange then that some prototype DVD players still use caddies. Although the more modern prototypes use caddy-less tray loading, it pays to watch any DVD display and see how the demonstrator handles the discs – with extreme care, at the extreme edges.

No-one grabs a DVD disc with sticky fingers. But unfortunately this is exactly how the public treats CDs. They will treat DVDs that way too. Will the error correction cope? We are assured it will, even though the capacity of the new disc is so much greater, thanks to pits that are so much smaller.

If the DVD Alliance launch their system without first giving players and discs to sticky fingered next door neighbours, they could pay the same price paid by Sir Clive, RCA, ICL, Fujitsu, Olivetti and Commodore. That price is horrendously expensive failure thanks to the public's reluctance to pay money for neatly packaged inconvenience. Barry Fox

Electranics World is published monthly. By post, current issue £2.35, back issues (if available £2.50. Orders, payments and general correspondence to L333, Electronics World, Quadrant House, The Quadrant, Sutton, Surrey SM2 5AS. TIx:892984 REED BP G. Cheques should be made payable to Reed Business Publishing Group Newstrade: Distributed by Marketforce (UK) Ltd, 247 Tottenham Court Road Londan WIP OAU 0171 261-5108.

Subscriptions: Quadrant Subscription Services, Oakfield House Perrymount Road, Haywards Heath, Sussex RH16 3DH. Telephone 01444 445566. Please natify change af address. Subscription rates 1 year £30 UK 2 years £48.00 3 years £70.00. Surface mail 1 year £35.00 2 years £56 00 3 years £80.00 Air mail Europe/Eu 1 year £43.00 2 years £68.00 ROW 1 year £52.00 2 years £83.00 Overseas advertising agents: France and Belgium: Pierre Mussard, 18-20 Place de la Madeleine, Paris 75008. United States of America: Ray Barnes, Reed Business Publishing Itd, 475 Park Avenue South, 2nd Fl New York, NY 10016 Tel; (212) 679 8888 Fax; (212) 679 9455 USA mailing agents: Mercury Airfreight International Itd Inc, 10(b) Englehard Ave, Avenel NJ 07001. 2nd class postage paid at Rahway NJ Postmaster. Send address changes to above. Printed by BPCC Magazines (Carlisle) Itd, Newtown Trading Estate Carlisle. Cumbria, CA2 7NR Typeset by Wace Publication Imaging 2-4 Powerscrott Rood, Sidcup, Kent DAt 4 SDT,

Reed Business Publishing Ltd 1995 ISSN 0959 8332



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Wireless LAN technology connecting handheld pcs including one from SAIC the UK ruggedised computer supplier - is being tested for electromagnetic compatibility in Russia's Mir space station. A 2.45GHz spread spectrum wireless LAN from US company Proxim was taken up to the space station on the space shuttle Endeavor in March. According to Yuri Gawdiak, a NASA computer engineer: "Today's astronauts are surrounded by miles and miles of cable. Wireless networks eliminate their need." One important aspect of the emc tests will be the system's susceptibility to the impact of cosmic particles on processors and memory devices.

d memory devices. The remarkable characteristic of this 2D Mesfet is that it functions with only 200

# EMC all over again?

ast year's panic over the introduction of CE marking for the EMC Directive is set to be repeated when the net technical harmonisation standard rears its head. If industry thought emc compliance caused problems, then enter the Low Voltage Directive, or LVD.

According to industry experts, many electronics engineers and manufacturing companies have little understanding of the LVD.

Andrew Perkins, instrument sales manager for Schaffner EMC, involved in conducting seminars said: "People's knowledge of the LVD is akin to that of the EMC Directive this time last year. Less than 5% of people attending the seminars are doing the tests correctly."

The lack of understanding is also resulting in few companies conforming to the Directive.

As of January 1, 1997, the LVD attains the same status as the EMC Directive, with manufacturers being required to CE mark for LVD conformity. This means that someone will have to sign a declaration of conformity and will be held accountable in law.

Safety divisional manager at TRL EMC is Simon Barrowcliff. "Small and medium sized companies are exhibiting good engineering practice in most cases", he said. "They are designing for safety but they are not conforming to the LVD."

While the DTI has provided information on the LVD, its spread over several years has resulted in it lacking the profile of the successful emc campaign. This, however, is likely to change in the coming eight months.

Richard Ball, Electronics Weekly

#### What is the Low Voltage Directive?

• The LVD is the standard specifying design and testing of equipment connected to the mains. The 'Low' refers to voltages below 1kVac and 1.5kVdc. It differs from the EMC Directive in several significant respects:

• The LVD dates from 1973 and is one of the first technical harmonisation standards. This has given companies ample time to prepare for LVD-day. Unlike the EMC Directive, there is no excuse for ignorance and little or no leniency will be allowed.

• Harmonised European standards for the LVD are much more complex. Longer design and testing time will be necessary to ensure total compliance by 1997. One route to compliance is via approval schemes such as the BABT scheme for telecoms and the BEAB for consumer and white goods. These specify third party type testing and formal quality systems such as ISO9001. Smaller companies with less funds and manpower may find these schemes prohibitive in cost and time.

• More information: DTI booklet, Tel: 01179 444 888.

### **EMC amnesty for UK manufacturers**

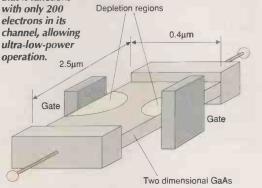
British electronics manufacturers have been given an 'unofficial' emc breathing space by the government.

The DTI has told local trading standards officers, who have been officially policing the EMC Directive since January, to take a lenient approach to enforcement at least for this year. "There has been guidance to local authorities to allow a period of grace," said David Roderick, director of the safety committee for the Institute of Trading Standards.

In a move, which seems to be out of step with the rest of Europe, the DTI appears to be responding "sympathetically" to those suppliers waiting to have their products qualified in test houses. "There is concern about the test houses not being able to cope, so where people have made attempts to get things done, we will look upon it sympathetically," said Roderick. No one in the UK has yet been prosecuted under the EMC Directive, and Roderick believes any prosecutions are unlikely in the near future.

#### Ultra-low power 2D mesfet nearer production

University of Virginia's research group that recently demonstrated an ultra-low power two dimensional



mesfet has moved a step closer towards a production version.

The remarkable characteristic of the original device is that it operates properly with only 200 electrons in its channel. Conventional fet structures are swamped by second order effects at such low currents.

The advance is in the construction of the device. The developmental fet was made using a

AlGaAs/InGaAs/GaAs heterostructure, built up layer by layer on the substrate and patterned using an electron beam. Bill Peatman, a member of the team said: "This technique is not at all suited to mass production." The newest version is constructed using ion implanted bulk n-doped GaAs – a conventional technique and material.

Peatman said: "We made two transistors with the same geometry, one with the original construction and one by ion implanting bulk GaAs. The two behave very similarly, and were closely predicted by our theoretical models."

The channel of the 2D mesfet is a 0.4µm wide strip connecting the drain and source. The strip is only a few nanometres thick, hence the 2D label. Gates on either side of the channel control the width of the conduction region within.

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## **Plastic lights**

**C**ambridge Display Technology, CDT, is to give the first public demonstration of its light emitting polymer display in San Diego.

The forum is the Society for Information Display's annual conference and the device is a 60 column by 16 row photo-emissive dot matrix.

The display is said to combine characteristics of leds and leds. Mark Gostick, a spokesman for CDT, said: "The technology has the emissivity of leds, with the patternability of leds. Light is emitted wherever activated electrodes cross one another."

Although the demonstration is a dot matrix display, the first commercial use is likely to be as a backlight. Gostick said: "The life to 50% brightness is currently 3000 hours. This is perceived to be a bit short for a display, but easily long enough for a backlight." Light emitting polymer backlights offer similar advantages to electro luminescent materials. They are extremely thin, with the same emissivity and a similar lifetime.

The stated advantage of light emitting polymers is that they only require several volts, eliminating the inverter normally associated with electroluminescent lights. Gostick said: "The lack of an inverter makes a light emitting polymer backlight cost less to produce than the equivalent electroluminescent panel."

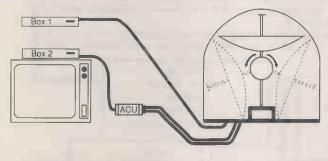
Most of the development displays made by CDT so far have been green and on glass substrates, but other types have been made. Gostick said: "We have made red and blue versions, the blue ones are the most difficult to produce. We have also made some flexible displays on plastic film, but the lifetime is not as good as the glass ones yet." Steve Bush, *Electronics Weekly* 

### Satellite tracker handles big waves

Receiving satellite transmissions at sea presents difficulties, with the signal being lost when the boat turns, pitches and rolls. This can be overcome by gyroscopically directed dishes; but the comparatively low power of satellites has meant that these have had to be large.

The launch of three high power digital satellites by GM Hughes Electronics has enabled KVH Industries of Rhode Island to produce a compact system capable of operating up to 200 miles off the US coast.

The *TracVision* actively stabilised antenna has an 18in carbon fibre dish guided by a robotic arm to maintain tracking accuracy to within 1°. It uses a digital, Earth-referenced compass and attitude sensors to hold



This marine satellite tracker can move at 18°/s. It has a 110° elevation range and can rotate through 360°.

directional information over long periods of time, with digital gyroscopes to provide instant directional information.

Measurements are relayed to the cpu, where software calculates the rate of the movements and translates them to stable, land-based coordinates. These are then converted to commands in the motor control unit to guide the robotic arm.

Two motors power the arm and antenna in the opposite direction to the movement of the vessel. It is capable of locating the target satellite with or without GPS information. The elevation range is  $\pm 110^{\circ}$  from vertical, azimuth range is 360° continuous, and the tracking rate is 18°/s at horizontal.

Received video signals are passed to a set-top receiver box. A patented robotics gimbal joint system prevents cables from wrapping around the antenna pedestal and causing transmission breaks.

A smaller *Tracphone* version has also been produced. It has an 11.5in dish for satellite phone and fax communications. With this version, internal sensors measure the heading, pitch and roll of the vessel relative to the satellite. These are then transmitted to a microprocessor that directs the motors controlling the arm and dish.

#### IN BRIEF

# Power fet resistance lowered to 260m $\Omega$

Motorola has announced its next generation of power fet technology – hdtmos-2 – which gives a 30% reduction in  $R_{DSon}$  compared with the original hdtmos process.

Significant structural changes have bought the resistance of a 2mm×2mm chip down from  $800m\Omega$  to  $260m\Omega$ . Sample devices are expected in the second quarter of this year.

#### Chip prices softening

Softening chip prices could be hit further as 14 new fabs come on stream before the end of June, and at least 16 more are due to start up in the second half of the year. The total for the year could be as many as 40 new fabs.

These are in addition to 60 fabs which, according to US analysts, came on-stream last year: 19 in America, 12 in Japan, 11 in Europe and 18 in Asia.

#### FCC considers Internet radio band

The US Federal Communications Commission is considering setting aside a band of radio frequencies for high speed Internet access over short distances. The FCC says it may set aside two bands of frequencies in the 5.15-to-5.35GHz and 5.725-to-5.875GHz bands for use by wireless computer devices that would send and receive data over a 0.25 mile range at rates as high as 25Mbits/s.

"Low-power radio technology can serve as a low-cost, high-bandwidth on-ramp to the information superhighway," said FCC Commissioner Susan Ness. The FCC has been petitioned by Apple Computer and the Wireless Information Networks Forum to set aside the frequencies.

Apple and other supporters say that these radio frequencies could be used for campus style local area networks. These would operate over a university or corporate campus linking computer users, and would be a cheap alternative to cellular phone or PCS networks.

Apple is also proposing a related technology that would allow high speed wireless data communications over a 9.6 mile range at 1.5Mbits/s. Using wireless technology could prove popular within corporate offices and save on the considerable expense of rewiring offices for high speed networks.

Trac Vision



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interested in to see how easy it is to build your dwn equipment the HART way. The FULL cost can be credited against your subsequent

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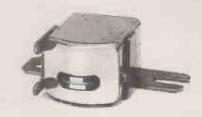
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# **RESEARCH** NOTES

**Jonathan Campbell** 

### Energy technology is truly green

P lants can exploit virtually every photon they absorb to create a working electron that is efficiently taken up into chemical processes. Our own efforts in making electricity from the Sun using solid state devices are a lot less efficient. But a team from University of California and Princeton University looks to have taken a step towards developing a technology that uses a mechanism much closer to that used in nature.

The technology is based on materials given the name 'chemophylls' because of the way they mimic the chlorophyll process. A prototype chemophyll is a stable preparation that binds a layer of electron-donor substance (papd) to a layer of an electron acceptor substance (pv). The donor papd can be grown as true film, without crystalline structure, while the acceptor pd forms extremely small crystals that can be neatly arrayed in layers one molecule deep.

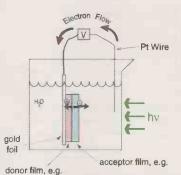
Both papd and pd consist of an active core sandwiched between structures called phosphonates. Atoms of zirconium bind to the phosphonates, tying the assembled 'sandwiches' to one another. The structure resembles a stack of papd and pd sandwiches piled on an ultrathin sheet of gold foil. Sandwiches with papd 'filling' alternate with sandwiches with pd filling, and zirconium atoms hold them together. When illuminated with light,

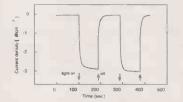
electrons move from the papd to the pd, creating an electrical potential. By providing an appropriate receptor material to accept the electrons on the other side of the surface, a continuing, one-way flow is set up.

University of Southern California chemist Mark E Thompson, leader of the scientific group responsible for the prototype's creation, explains the possible application of the chemophyll: "While this material would be inefficient at powering a device, like a radio or a hair dryer, that runs on electric current, it could be an extremely effective power source for light-induced chemical reactions, such as breaking down water into oxygen and hydrogen or making natural gas out of the carbon in carbon dioxide to create clean-burning fuels."

Three characteristics make it particularly interesting. It is produced in extraordinarily uniform layers and can deliver its energy evenly throughout an entire surface of arbitrarily large size. It can also be applied as a coating to an irregular surface.

Like chlorophyll – and unlike silicon cells – its photovoltaic action is a wet process, working in an electrolyte solution conducive to chemical reactions. It might even float on top





of a liquid that would form the raw material for the chemical reaction.

Finally, although the conversion efficiency of the material so far prepared is low, the team is confident that materials of similar structure with much higher efficiencies can be made.

More information from Mark Thompson, Associate Professor, Department of Chemistry, University of Southern California, Los Angeles, CA 90089-0744, USA. Tel: (213) 740-6402 Fax: (213) 740-0930 email: mthompso@chem1.usc.edu

### Micromachines get a little intelligence

Several research teams have recently made breakthroughs in the manufacture of micromachines. Now researchers at Sandia National Laboratories, Albuquerque have taken the next step by giving their micromachines built in intelligence.

Unlike previous machines, an intelligent micromachine can signal for more power, communicate that it is operating too fast or slow, or even perform actions on an automated basis. But using standard fabrication techniques, machines consisting of tiny motors with integrated circuit 'brains' on individual silicon chips – are now being mass produced by Sandia researchers.

Compact design, made possible by

sinking the motors in tiny etched trenches, enables the fabrication of entire electromechanical systems on a chip.

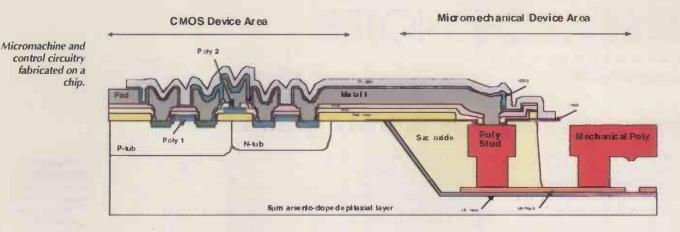
In the past, the difficulty with joining a microcircuit to a micromachine on a silicon chip has been that aluminum circuit interconnectors, if formed first, melt when the micromachines are heattreated. But if the micromachines are fabricated first, their elevation above the chip surface creates bumps that distort the delicate process of etching accurate microcircuits.

In the Sandia process tiny trenches are etched in silicon chips and the machines are fabricated within these depressions. The machines, heattreated, are then submerged in a tiny hardening sea of silicon dioxide. The hardened silicon dioxide re-creates a level chip surface upon which circuitry is fabricated by

A dust mite puts the new generation of micromachines in perspective.



Chemophyll's photovoltaic action is a wet process, working in an electrolyte solution, and could even float on top of a liquid that would form the raw material for the chemical reaction itself. The graph shows cathode photocurrents produced by an Au.papd/pv electrode with an electron acceptor in solution.



photolithography. Removal of the silicon dioxide at the end of the process frees the microengines. Working systems are manufactured with a 78% success rate -a reasonably high measure of production yield.

The micromachines are approximately 1mm square embedded in chip trenches 6µm deep, producing a single level structure suitable for

accelerometers and other sensors.

Three-level structures have been fabricated to a depth of 18µm.

Circuits fabricated only microns from a machine also eliminate ghost signals – parasitic currents – created by excess electrical capacitance in long connecting wires.

"Without this interference, by applying a mechanical load you can measure the capacitance change in the drive gear teeth as they move in and out," says Sandia engineer Ernest Garcia. "Then you know how fast the machine is moving. The sequence allows you to understand velocity."

Analog Devices, the largest producer of automated airbag sensors in the US, says it is already having preliminary talks with Sandia to use its technology in prototype devices. More information from Ernest Garcia, Sandia National Laboratories, Albuquerque, New Mexico, 87185-0167

### **Optical switch polarises arguments**

A light-activated optical switch under development at the Georgia Institute of Technology could be the basis for a new type of rewritable three-dimensional data storage system. By making use of a small number of 'trigger molecules' to induce a phase transition in liquid crystal materials, the system would write, read and erase information using different forms of polarised and unpolarised light.

Such an optical storage system could offer significant advantages over conventional computer floppy disks, magnetic tape and compact disks, which use two-dimensional media to store data. The optical switch materials could also be used in spatial light modulators, and in active coatings for optical fibres.

The idea is that the liquid crystal could be written to, with circularly-polarised light, read from, with linearly-polarised light, and erased, with unpolarised light.

Operation of the new optical switch is based on chiral molecules that Gary Schuster, professor of chemistry at Georgia Tech, and co-



Georgia Tech researchers have been making microscope studies of liquid crystals suspended in glycerol, which helps to provide information about key properties.

workers are using to trigger changes in the liquid crystal. Chiral molecules exist in right-handed and left-handed forms. Each form is affected differently by circularly-polarised light – which also exists in right-handed and left-handed versions.

When right-handed trigger molecules are struck by left-handed light they may be converted preferentially to left-handed molecules. If the chiral molecules are dissolved in a liquid crystal material, this structural change can be used to prompt a phase transition in the crystal, altering the optical properties of the liquid crystal material.

Multiple phase transition 'switches' could therefore be used together to store digital information.

Returning the storage material to its original state would make the system truly rewritable — and of significant potential value as a computer data storage media, for example.

Schuster believes the system is an improvement over earlier optical switches not only because it is rewritable, but also because a small number of photons can trigger the phase transition. This makes the liquid crystals amplifiers for the photonic signal.

Before the switches become useful for optical data storage, they must be converted from two-dimensional layers to a true threedimensional system, perhaps written by three-dimensional holograms.

Development of practical optical switches has long been frustrated by the lack of suitable materials. Optical materials studied earlier used irreversible photochemical changes to store information. That meant data could be written to them only once, limiting their practical value for computer information storage.

Though the Georgia Tech system shows promise, Schuster emphasises that much work remains to be done before it could reach practical application.

"From a scientific point of view, looking off into the future, this is what we hope to do with these materials," he said. "Our grandchildren might see the first computers based on this system." More information from Gary Schuster at Georgia Institute of Technology Atlanta, Georgia 30332-0828

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45

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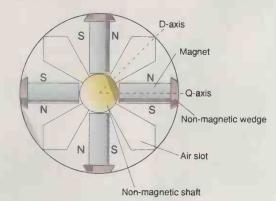
achieved.

densities to be

enabling greater

#### Researchers pack more power into electric motor

Two researchers in the Department of Electrical and Electronic Engineering, University of Hong Kong, claim to have invented a new design of permanent magnet motor that promises much higher power densities and efficiencies than other similar units. The permanent magnet synchronous motor drive has been developed for electric vehicle applications, with the greater power



density resulting in savings in energy and space.

Improvements in the motor's performance have been bought about by developing a special rotor geometry and using new neodymiumiron-boron magnets that have only recently become available.

In the past, efforts to boost the power density of pmsms have relied on increasing the flux density in the air gap – resulting in a smaller effective gap and leading to a strong armature reaction which limits the force density of the motor.

But the Hong Kong researchers say they have reduced this armature reaction considerably by making air slots along the D-axis within the motor ('An advanced permanent magnet motor drive system for battery-powered electric vehicles', CC Chan and KT Chau, *IEEE Transactions on Vehicular Technology*, Vol 45, No 1). According to Chan and Chau the improvement is possible because in the new design, the air slot at each pole centre has to be bridged by the armature field while the flux path for the excitation field experiences only an insignificant change. Power density of the experimental motor is 2009kW/m<sup>3</sup>.

So far a prototype of the 3.2kW battery powered drive system has been designed and built for an experimental vehicle. Specifications for the vehicle are a top speed of 30km/h, an acceleration of 0-20km/h in 8s and a payload rating of 200kg, able to be carried up a 15° gradient.

In principle, the proposed pmsm could be scaled up to fit the needs of a regular on-road electric vehicle with a 50kW motor. But the researchers warn that any economic advantages would be diminished because of the need for bigger quantities of the relatively expensive magnetic material. More information from the authors at University of Hong Kong, Pokfulam Road, Hong Kong.

#### How to take in twice as much information?

n the stimulus-overload world of the multimedia '90s, with the amount of data squeezed on to a computer screen nearing saturation point, we plainly need some new thinking on how to cope with this out-pouring of information. Now a team of Japanese researchers have come up with an answer – simply add another screen!

According to the researchers from Hitachi's Central Research Laboratory, conventional display systems are simply not capable of coping with the abundance of information being presented.

"Multi display systems, rather than single-display systems, may be more suitable for taking advantage of a multimedia environment," is the conclusion.

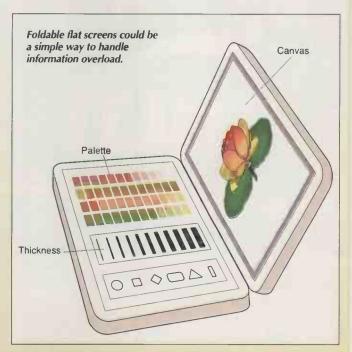
Fortunately, that doesn't mean we have to worry about our brains – and necks – seizing up as we twitch from screen to screen (to screen) surrounding our desks. Well not yet anyway. Because the solution proposed is an altogether friendlier foldable flat-screen display that looks as much like a book as a computer peripheral.

The prototype foldable display system built by the team ('Foldable-display systems as a standard platform for multimedia use', Y Kaneko *et al*, 'IEEE Transactions on Consumer Electronics', Vol 42, No 1.) is based on connecting two or more active matrix lcds mechanically and electrically. The resulting system can be opened up and laid on a table.

Possible applications suggested by the researchers are by using one screen as the palette space with details on brushes etc, and the other as the canvas. In more general terms, the system could be useful wherever information needs to be manipulated and data, tools and a work space are all needed. Another application being tested is in an electronic translator. Two people sit with the display between them, looking at equivalent text, inverted towards them, in their respective languages.

Pointing to a phrase by touching the screen by one person causes the equivalent phrase to be displayed on the other screen in the foreign language.

There could be economic advantages as well, as two 250mm active-matrix lcds are much cheaper to produce than a single display



#### with the same area, about 355mm diagonally.

If the Hitachi prototype makes it into production, it looks as though we may have a route to turbo-charging the output of information from our computers – but what about the input? We already use a keyboard and mouse together, and can even talk to some machines. But don't you feel a little frustrated that your feet have nothing to do?

More information from Yoshiyuki Kaneko at the Central Research Laboratory, Hitachi Ltd, Kokubunji, Tokyo 185, Japan.

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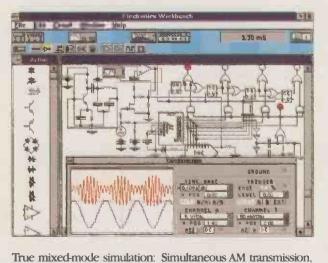
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digitization and pulse-code modulation of a signal.



INTERÁCTIVE

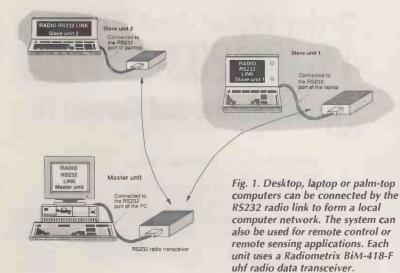
# Computer RS232 wireless link

Covering distances of up to 120m, Pei An's wireless RS232 link hardware operates at up to 9600 baud via type-approved transmitter/receiver modules.

This article introduces a radio communication system which allows two or more computers to communicate with each other over a wireless link via their RS232 interfaces. Reliable communication can be achieved over a distance of 30 metres in buildings or 120 metres on open ground.

The radio link uses Radiometrix low power 418MHz uhf fm data transceiver modules which are type-approved to the Radio-communication Authority Specification MPT1340 in the U.K. This avoids the need to submit the final product for further approval.

By implementing suitable software, this system can form a local computer network. It can also be used for remote sensing or remote control applications.



#### How the system works

The system consists of a number of identical radio transmitter/receiver units, each connected to the RS232 interface of the various computers, Fig. 1. Each unit can be configured as a transmitter or a receiver. When it is configured as a transmitter, serial data from the RS232 interface is fm modulated by a uhf radio-frequency carrier signal and is transmitted to the surroundings. If it is configured as a receiver, radio signals picked up by the antenna are demodulated. Demodulated data – the serial data put into the transmitter – is fed into the RS232 interface.

A system may include one master unit and several slave units. By using appropriate software, half-duplex data transmission can be achieved between the master unit and the other units, Fig. 1.

#### **RS232** interfacing

The RS232 is an industrial standard bi-directional asynchronous serial data communication interface for data communication between two devices. With computers, it is frequently used for connecting peripherals such as printers, modems and mice.

A pc's parallel port comprises eight data lines and information is conveyed one byte at a time. Unlike the parallel i/o port, the serial COM port has only one line for data transfer in either direction. Each eight-bit byte is transmitted or received serially, one bit at a time.

With asynchronous data transmission, the transmitted signal contains both data and synchronisation information. This synchronisation information enables the receiver to reassemble, or 'frame', the serially transmitted words correctly back into parallel form.

The format of the transmitted serial data includes a start bit, 7 or 8 serial data bits, a parity check bit and 1 or 1.5 stop bits. Figure 2 shows a typical serial data format. The receiver device, which runs at the same clock frequency as

Contains the current status of DCD, RI, DSR and CTS.

Acts as one-byte memory

(useful register)

RITY STOP

the transmitter, detects the start bit and receives the data bits. It checks the parity bit and upon receiving the stop bit it terminates the data receiving cycle and waits for the next transmission. The rate at which data bits are sent is measured by baud rate.

In practice, the asynchronous communication is facilitated by a family of industrial standard computer peripheral ICs known as uarts, or universal asynchronous receiver and transmitters. Most computers use a 8250 or 16450 uart. These devices operate at ttl voltage levels but RS232 operates at higher, bipolar voltages. For this reason, ttl-to-RS232 and RS232-to-ttl converters are needed.

#### The pc's RS232 interface

A standard RS232 interface is a 25-pin interface, which is housed in a 25-pin D-type male connector. A 9-pin version is also used on pcs. Figure 3 gives the pin layout and functions of the RS232 connectors viewed from the back of the computer. The functions of the pins are briefly described as follows:

- Prot protective ground line. This pin connects the metal screening of the cable to the chassis of the equipment.
- GND Ground line provides a common voltage reference for all signals.
- TD Transmitting data output. Serial data is transmitted on this line.
- RD Receiving data input receives serial data.
- RTS Request to send is a handshake output indicating that a transmitting device is ready to send data. If handshake is not required, it can be used as an output.
- CTS Clear to send is a handshake input from which a receiving device is informed to receive data. If handshaking is not used, it could be used as an input.
- DTR Data terminal ready is a handshake output and indicates that a transmitting device is ready. If handshaking is not used, it can be used as an output.
- DSR Data set ready is a handshake input from which a receiving device is informed that the data set is ready. If handshaking is not used, it could be used as an input.

An pc-compatible computer can have up to four RS232 interfaces. They are labelled COM1 to COM4. Each COM port is associated with a uart chip inside the computer. Operations of the COM port are controlled by internal registers of the uart. For register functions, see Table 1.

The i/o addresses of each internal register is calculated by adding the offset to the base address of a COM port. Table 1 shows the i/o address for COM port 1 which has a base address of 3F816.

Some registers are used for the wireless link described here. Register 0016 (data buffer register) stores the received data and the data to be transmitted. Register 0416, the modem control register, controls the status of RTS and DTR of the port. When handshaking is not required, the two lines can be used as outputs. Register 0616, the modem status register, stores the status of CTS and DSR, which, when handshaking is not used, can be used as two inputs.

Base i/o addresses for COM1 to COM4 are summarised in Table 2.

Table	1. Functi	ions of the pc uart's inte	rnal registers.
Offset	Address	Function	Description
0016	3F8 <sub>16</sub>	Receiver buffer register	Store received data
		Transmitter buffer register	Store data to be transmitted
			(useful register)
0116	3F9 <sub>16</sub>	Interrupt enable register	Set the mode of interrupt reques
0216	3FA16	Interrupt identification register	Check mode of interrupt request
0316	3FB <sub>16</sub>	Data format register	Set the format of serial data
			transmission (useful register)
0416	3FC16	Modem control register	Set modem controls
			(RTS, DTR, etc) (useful register)
0516	3FD16	Serialisation status register	Contains information on status
			of receiver and transmitter

3FF<sub>16</sub> Scratch-pad register

Modem status register

#### Table 2. Base i/o addresses for the pc's COM ports.

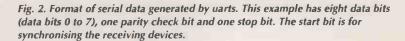
3FE16

0616

0716

Interface	Base address	Addresses for	
COM1 COM2 COM3	3F8 <sub>16</sub> 2F8 <sub>16</sub> 3E8 <sub>16</sub>	internal registers 3F8-3FF <sub>16</sub> 2F8-2FF <sub>16</sub> 3E8-3EF <sub>16</sub>	
COM4		2E8-2EF <sub>16</sub>	PA
STACE		BIT-2 BIT-3 BIT-4 BIT-5 BIT-6 BIT-7	

STAGE	BII	011-0	DII-I	DIFE	DIT-3	011-4	011+5	DI1-0	D11+7	DIT	ыт	
					1						_	
		1	0	0	1	1	0	0	1	0		
								_				
										-		



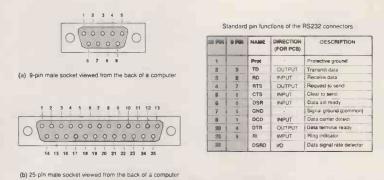


Fig. 3. Pin layout and functions of the pc's RS232 connector.

#### **Connecting devices using RS232**

Two types of RS232 link are shown in Figure 4. The arrows show the direction of data flow. Figure 4a) is known as a null modem. Some lines of the two RS232 interfaces are used as handshakes between the two devices.

Figure 4b) shows a connection using only three lines. One line is for transmitting data and the other for receiving data. The connection is arranged so that the transmitting line of the first device, TD, is connected to the receiving line of the second device, RD.

#### Software control

Before a COM port can be used, it must be configured. This configuration includes setting of the following: the bit rate, length of data bits, number of stop bits and the parity check bit. Two computers communicating with each other must have the same configuration. There are three methods of carrying out the configuration.

• The first method is to use DOS command 'MODE' under DOS prompt. The syntax of the command is:

MODE COMm: baud=b, parity=p, data=d, stop=s, retry=r

#### or

#### Table 3. BIOS initialisation bit functions.

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Define bit	rate bits		Define p	arity check	Stop Bit	Data len	gth
111= 960	0 011= 60	00	00= No p	oarity	0= 1	10= 7 bi	t
110= 480	0 010= 30	00	10= No p	parity	1= 2	11= 8 bi	t
101= 240	0 001=15	50	01= Odd				
100= 120	0 000= 11	10	11= Ever	1			

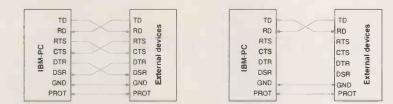


Fig. 4. RS232 pin connections between pcs and external devices.

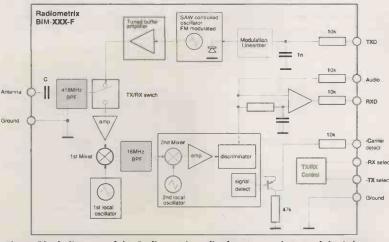


Fig. 5. Block diagram of the Radiometrix radio data transceiver module. It has a transmitter, receiver and other circuits integrated in one module.

MODE COMm: b, p, d, s, r

Functions of specifiers in the command can be found in any DOS handbook<sup>1</sup>. For example 'MODE COM1: 96,n,8,1' configures COM port 1 to have a baud rate of 9600, no parity check, 8 bit data length and 1 bit stop bit. This command can be included in the autoexec.bat file.

• The second method is to use a basic-input-output-system, or BIOS, interrupt. This allows the interface to be configured from within the user's program. It requires that register AH is loaded with 0, DX is loaded with a number 0 to 3 representing COM1 to COM4 to be configured, and AL is loaded with an 8-bit initialisation code. The bit function of this code is shown in Table 3.

The following Turbo Pascal program shows how to achieve the same function as the DOS command 'MODE COM1: 96,n,8,1'. The initialisation code is 11100011B.

Procedure initialise; {COM1: 9600, no parity check, 8 bit data and 1 stop bit} var register:registers; begin with register do begin ah:=0; {load interrupt function number} al:=128+64+32+0+0+0+2+1; {load initialisation code, 11100011B} dx:=0; {COM1 is to be initialised} intr(\$14, register); {Call the BIOS interrupt} end; end;

• The third method configures the COM port by writing data directly into the data format register, at offset= $03_{16}$ , of the uart. This method is slightly involved and outside the scope of this article. Details can be found however in other pc hardware books<sup>2</sup>.

#### Sending and reading serial data

There are several ways to read and send serial data via the RS232 interface. The following method is the most flexible one as far as pc interfacing is concerned. The method is known as direct port access.

To send data out of the COM1 interface, you can write data directly to the data buffer register,  $3F8_{16}$  – the base address of COM1. The following instructions can be used:

```
OUT 3F8h, X in BASIC, and
PORT[$3F8]:=X in Turbo Pascal
```

X is the data in decimal. To read data from the COM1 port, we can read data from the data buffer register,  $3F8_{16}$  and the following commands can be used:

Y=INP[3F8h]in BASIC, and Y:=PORT[\$3F8] in Turbo Pascal

where Y is the input byte in decimal.

#### Reading and writing data via handshake lines

To output data from the RTS and DTR lines, you should write to the modem control register at offset 04<sub>16</sub>. Data bits DB0 and DB1 correspond to RTS and DTR. The following Turbo Pascal command makes the RTS and DTR lines of port COM1 go low. Note that both lines are inverted by ttl-RS232 transceivers inside the pc.

#### PORT[\$3F8+4]:=2+1

To read data from DSR and CTS lines, you should read the modem status register at offset  $06_{16}$ . Data bits DB5 and DB4 correspond to the DSR and CTS lines of the port. Again, these two lines are inverted by ttl-RS232 transceivers.

#### COM port base addresses

The base addresses for different COM ports have been shown earlier. A convenient way to find the addresses automatically is to use software commands.

When the computer is switched on or reset, the BIOS checks all possible RS232 addresses. If it finds an installed one, it writes the addresses of the port, in a two-byte word, to specific memory locations. For COM1, the locations are  $0000:0400_{16}$  and  $000:0401_{16}$ . By peeking these locations, the base address can be obtained. Memory locations for COM1 to COM4 are listed below.

Port	Memory address
COM1	0000:0400 - 0000:040116
COM2	0000:0402 - 0000:040316
COM3	0000:0404 - 0000:040516
COM4	0000:0406 - 0000:040716

Another useful one-byte memory location is  $000:4011_{16}$ . It stores the total number of installed COM ports. The information is contained in bits 3, 2 and 1 of the byte. Data bits 7 to 4 and 0 are used for other purposes.

DB3	DB2	DB1	Number of RS232 ports installed
0	0	0	0
0	0	1	1
0	1	0	2
0	1	1	3
1	0	0	4

The following example in Turbo Pascal 6 first detects the number of RS232 interfaces installed on the pc and assigns the number to a variable, namely 'Number\_of\_COM'. It then reads from the memory locations holding the base address of COM1 and assigns the address to the variable 'COM1\_address'.

```
Procedure detect_COM1;
var
```

COM1\_address,number\_of\_COM:integer;
begin

```
number_of_COM:=mem[$0000:$0411]; {read
number of parallel ports}
```

```
number_of_COM:=(number_of_COM and
(8+4+2)) shr 1; {DB3, DB2 and DB1
```

```
extracted from the byte}
COM1_address:=memw[$0000:$0400]; {Memory
```

```
read procedure}
writeln(`Number of COM installed :
```

```
`,number_of_COM:2);
writeln(`Addresses for COM1 :',
```

```
COM1_address:3);
end;
```

#### Data transceiver module details

This wireless link uses wireless data transceiver modules supplied by Radiometrix. I recommend that you obtain a full descriptions of the modules before you try to implement them<sup>3</sup>.

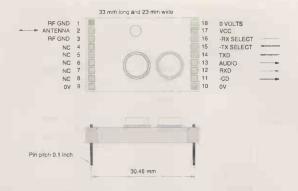
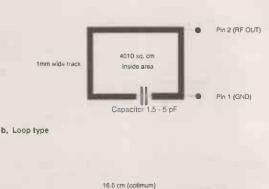


Fig. 6. Mechanical dimension and pin functions of the BiM transceiver.



26 turns of 0.5mm diameter enamelled copper wire coils wound on 2.5mm dia former



Pin 2 (RF OUT)
 Wire, rod pcb track or combination

c, Whip type

a. Helical type

Antenna performance chart

	Helical	Loop	Whip
Ultimate performance	22	1	555
Ease of set-up	22	1	555
Size	111	11	1
Immunity to proximity de-tuning	22	111	5

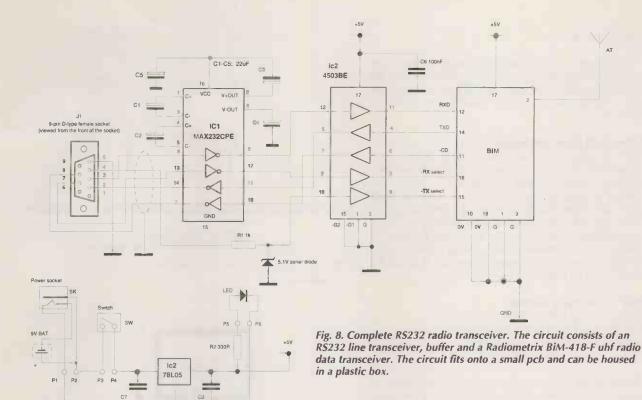
#### Fig. 7. Comparison of antenna options for BiM transmitter/receiver modules.

The modules are available in two types, namely *BiM*-418-F and *BiM*-433-F. The first operates at 418MHz and is type-approved to MPT1340 of the Radio Communication Authority in the UK. The latter is for European use in the 433.92MHz band.

Both modules provide a low-cost solution for a bi-directional half duplex data transmission at speeds up to 40kbit/s over a distance of 30 metres inside buildings and 120 metres on open ground. The block diagram of the module, its mechanical dimensions and pin functions are shown in Figs 5&6.

The module consists of a uhf fm transmitter and a matching superheterodyne receiver. For the transmitter, digital data is fed into a modulation lineariser via an R/C low-pass filter. This filter restricts the bandwidth of the modulation signal.

Output of the lineariser drives a varicap diode, the changing capacitance of which modifies the frequency of a uhf



oscillator. The centre frequency of the oscillator is derived from a surface acoustic wave (SAW) resonator. The modulated uhf signal is amplified by a tuned buffer amplifier and fed to a Tx/Rx switch.

C7, C8: 100r

After passing through the switch, the signal is emitted to the surroundings via the antenna. For the receiver, the uhf signal picked up by the antenna is switched to the receiver section. It is amplified and fed into the first mixer. As a result, a modulated signal at an intermediate frequency of 16MHz is produced. This IF passes through a 16MHz band pass filter and enters the second mixer. After that the signal is amplified and fed into the discriminator, where an audio signal is produced. The signal then passes through a data slicer, converting the analogue signal to digital form.

The antenna is used by both the transmitter and by the receiver. Switching is controlled by the Tx/Rx analogue switch and the operation of it is controlled by a transmit/receive selection circuit.

#### **Pin-functions of the Tx/Rx module**

Pin functions of the module are briefly described as follows. Pins 9, 10 and 18 are the ground pins, i.e. 0V, which are connected to the negative rail of the power supply. Pin 17 is the positive supply pin,  $V_{\rm cc}$ .

A dc supply voltage between 4.5V to 5.5V should be

#### Table 4. BiM and RS232 port pin relationships.

#### **R5232 interface pin** RD, receive data, pin 2 CTS, clear to send, pin 8, used as an input

TD, transmit data, pin 3
RTS, request to send, pin 7, used as an output
DTR, data terminal ready,pin 4, used as an output
GND, signal ground, pin 5

Pin of the BiM module TXD, transmit data --CD, carrier detect RXD, receive data --RX, receive select --TX, transmit select GND, ground connected. Applying a voltage above 5.5V or reversing the polarity of the power supply will cause permanent damage to the module. When the module is in transmit and receive modes, current assumption is about 12mA. In the stand-by mode, current reduces to about  $1\mu A$ .

Piñ 14 is the transmit data input pin (TXD). It can be driven directly by cmos logic running on the same supply voltage as the module. Analogue signals generated by modems or dtmf encoders can also be fed into this pin.

Pin 12 is the output of the received data. It can be connected directly to cmos logic. Pin 13 is the output of the analogue signals. It can be used with modems or dtmf decoders. Carrier detect is output on pin 11, -CD. When the module is in receive mode, a low state on -CD indicates a signal above the detection threshold is being received. This output can only drive one COM ports logic input.

Pins 15 (-TX) and 16 (-RX) are used for selecting operation modes of the modules. They could select one of the four modes listed below.

Pin 15 (–TX)	Pin 16 (RX)	Modes
1	1	Stand-by
1	0	Receive
0	1	Transmit
0	0	Self test loop

Pins 1 and 3 are the rf ground. They are internally connected to Pins 9, 10 and 18 and should be connected to the ground plane of user's pcb board against which the antenna radiates. Pin 2 connects to the antenna.

#### Antenna

Three types of integral antenna are recommended and approved for use with these modules. The configuration of the antenna and selection chart are given in Fig. 7. The present system utilises a helical type antenna.

#### Type approval

The BiM-418-F is type-proved to the RA MPT1340 for license exempt use within the UK for telemetry, telecommand and in-building security – but only provided that the following requirements are met<sup>4</sup>.

• The transmitting antenna must be one of the three variants given above.

• The transmitter module must be directly and permanently connected to the transmitting antenna without the use of an external feed. Increasing the rf power level by any means is not permitted.

• The module must not be modified nor used outside its specification limits.

• The module may only be used to send digital data. Speech or music is not permitted.

• Equipment in which the module is used must carry an inspection mark located on the outside of the equipment and clearly visible, the minimum dimensions of the inspection mark must be 10 by 15mm and the letter and figure height must be not less than 2mm. The wording must read: "MPT 1340 W.T. LICENSE EXEMPT".

• The trimmer control on the module must be inaccessible to the end user. This control is factory set and must never be adjusted.

Failure to meet the above conditions invalidates the modules' type approval. Further information on MPT1340 specification issued by the RA (DTI) may be obtained from the RA's library service on +44-(0)171-211-0211.

#### Requirement for digital data transfer

The data path through a pair of BiMs is ac coupled and there are several requirements for successful data transfer. Pulse width time – the time between two consecutive transitions in the serial code – must be between  $25\mu$ s and 2ms.

Receiver BiMs require at least 3ms of 10101010 bitsequence preamble to be transmitted before the actual data is transferred. The receiver is optimised for data waveforms with 50:50 mark-to-space averaged over any 4ms period. It will work reliably for sustained asymmetry up to 30/70 either way. But this will result in pulse-width distortion and decreased noise tolerance.

#### RS232 radio link hardware

The system consists of a number of identical units which are connected to computers via the RS232 interface. The transmission rate of the system is 9600 baud.

Figure 8 is the complete circuit diagram. It consists of three blocks, namely, the RS232/COM driver unit, the BiM-418-F module and the power supply system. The first unit is built around the TC232 RS232 driver,  $IC_1$ . This IC requires a single 5V power supply and converts the right voltage levels for the RS232 standard and COM port logic.

One of the RS232 output lines, DTR, is converted to the COM-port logic level using a simple voltage clamp circuit using a 5.1V zener diode. All the signal lines between the *TC232* and the *BiM-418-F* are buffered by the 4503BE, *IC*<sub>2</sub>. The pins of the BiM and RS232 are connected as shown in Table 4.

The 78L05 5V voltage regulator requires between 8 and 15V dc input. Suggested component layout and assembly of the unit is shown in Fig. 9.

#### Software requirements

RS232 serial data can be transmitted at 4.8 to 38.3kbit/s between a pair of BiMs. In order to send RS232 serial data through the BiMs, the data needs to be packetised to meet the Tx/Rx module requirements. The packetised data includes the following parts:

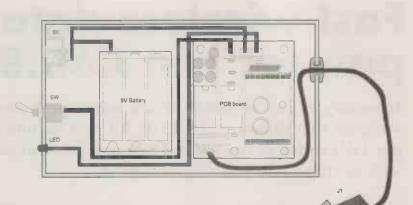


Fig. 9. Assembled unit of the RS232 radio link. Circuit board and batteries are housed in a plastic box. A lead connects the pcb and the RS232 connector.

- 3ms of preamble data of 55<sub>16</sub> or AA<sub>16</sub> to allow the receiver BiM to settle.
- one or two bytes of FF<sub>16</sub>.
- one byte of  $01_{16}$  to show the start of data.

• data bytes and

• check bits.

In practice, the format of the packetised data may vary according to the users' needs.

There are three methods of improving the mark-space ratio of the serial data to be transferred.

Method 1. Each byte is divided in half. The first half is the bit to be sent and the second half is its complement. Each byte has a guaranteed mark-to-space ratio of 50:50.

Method 2. Amongst the 256 possible eight-bit codes, 70 codes contain four zeros and four ones, which have a 50:50 mark-to-space ratio. Examples of these are,  $17_{16}$ ,  $1B_{16}$ ,  $27_{16}$ , and  $E8_{16}$ . They can be transferred between two RS232 ports using a data format of one start bit and one stop bit with no parity check bit. The actual data to be sent will be translated using these codes and then transferred. This also allows byte checking on receipt as all received codes must contain exactly four ones and four zeros.

Method 3. Each byte is sent twice. The first one is the true data and the other is its complement. This will again give a 50:50 mark-to-space ratio.

Control software in Turbo Pascal has been written to demonstrate data communication between two computers via the system.

#### **Technical support**

Designers' kits and assembled units together with demonstration software are available from the author. Please direct your enquiry to Dr Pei An, 58 Lamport Court, Lamport Close, Manchester M1 7EG. Tel: Ans/Fax: +44-(0)161-272-8279. If you would like to obtain more information on the BiMs, contact Radiometrix Ltd, Tel: +44-(0)181-810 8647, Fax: +44-(0)181-810-8648.

#### References

- 1. Microsoft DOS 6.0 manual.
- 2. Hans-Peter Messmer, The indispensable PC hardware book,
- Addison-Wesley publishing company, ISBN 0-201-62424-9.
- 3. Radiometrix Ltd. Low power UHF data transceiver module.
- 4. Radiocommunication Agency (RA), MPT1340, obtained from RA library service, Tel 0171-211 0211.

# Fast wireless data transceiver pair for just £60.80

Normally, a pair of BiM418F uhf transceiver modules, as used in Pei An's wireless R5232 link, costs £105.84. But Radiometrix is offering one pair only per *EW* reader at the special discount price of just £60.80 – fully inclusive of VAT, postage and packing and data.

Operating at 418MHz, these modules are capable of halfduplex data communication at speeds to 40kbit/s over distances of 30m inside buildings or 120m over open ground.

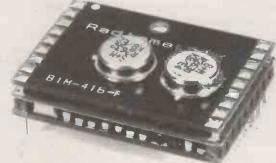
tances of 30m inside buildings or 120m over open ground. The modules integrate a low-power uhf transmitter and matching dual-superheterodyne receiver together with data recovery and Tx/Rx changeover switching. Requiring a single 4.5 to 5.5V supply, the modules interface directly to 5V c-mos logic.

High data rates and fast Tx/Rx changeover of less than 1ms make the BiM transceiver ideal for high integrity one to one links/multi-node packet switch networks. Rapid Rx power up – also less than 1m – allows effective duty cycle power saving of the receiver for battery powered applications. For example, current flow is on average 15µA for 1ms on and 1s off cycling.

Typical applications of the transceivers are:

- Medium speed computer networks
- Laptop to pc to printer links
- High integrity wirefree fire/security alarms
- Building environment control/monitoring
- Vehicle alarm systems
- Remote meter reading
- Authorization/access control

UK Version - BiM-418-F Euro Version - BiM-433-F



Operating at 418MHz, these modules are capable of half-duplex data communication at speeds to 40kbit/s over distances of 30m inside buildings or 120m over open ground.

#### Features of the BiM transceivers

- Miniature pcb mounting module
- Licence exempt operation in UK on 418MHz, MPT 1340 (BiM-418-F)
- ETS 300-220 tested for European use on 433.92MHz (BiM-433-F)
- SAW controlled fm transmission at -6dBm erp.
- Double conversion Superhet receiver
- -107dBm receive sensitivity
- Single 4.5 to 5.5∨ supply <15mA Tx or Rx
- Half duplex data at upto 40kbit/s
- Reliable 30 metre in-building range
  Direct interface to 5V c-mos logic
- Fast 1ms power up enable for duty cycle power saving
- On board data slicer, supply switches and antenna change over

#### **Order form**

To receive your BiM418F transceiver pair with full data sheet, fill in this coupon and send it to Radiometrix Ltd at Clausen House, Perivale Industrial Park, Horsenden Lane South, Greenford, Middlesex UB6 7QE, together with a cheque or postal order. Please note that this offer closes on Friday 30 August. For further information, write to or call Radiometrix on 0181 810 8647, or fax on 810 8648.

Please send one pair, BiM4128F 🗆 or one pair, BiM433F (433.92MHz) 🗅

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Exactly a century ago, Marconi filed a patent representing the beginning of a new era in communication. Tom Ivall looks at that patent and events surrounding it.

# The first radio patent

hen Guglielmo Marconi applied for a patent on his wireless telegraphy apparatus exactly a hundred years ago he was in effect announcing the start of an era. Electromagnetic radiation outside the visible spectrum could now be utilised as an aid to human communication. It was the beginning of a new technology and commercial enterprise.

British Patent No. 12039, 'Improvements in transmitting electrical impulses and signals and in apparatus therefor', application date 2 June 1896, was the world's first radio patent. Queen Victoria was still on the throne.

It wasn't a discovery and Marconi was more inventor than scientist. Physicists and others had already been experimenting with this form of radiated energy for a decade or more, though without fully understanding what they were dealing with. They certainly had no practical applications in mind. Branly in France, Hughes and Lodge in England, Popov in Russia and Thomson in America, among others, had all detected apparent radiation from electrical discharges – some natural, some artificially generated – but it was not explored much further. The electron was as yet unknown.

Certainly Maxwell had defined the conditions for the propagation of electromagnetic waves – calculating their speed and inferring that light might be one form of them – as early as the years 1861-1865. His Royal Society paper 'A dynamical theory of the electro-magnetic field' was to become a scientific classic. But the experimental physicists of the time were either unaware of it or sceptical of what they considered a dubious concept.

Helmholtz in Germany, however, eventually understood the importance of this mathematically-based theory. It was under him, in Berlin, that Heinrich Hertz was then working as an assistant professor. Helmholtz realised that the theory needed experimental verification and invited Hertz to attempt it.

After several years this challenge resulted in the famous series of experiments of 1886 at Karlsruhe technical high school – described in Annalen der Physik of 1887 and 1888.



Marconi – 1874-1937 – was a resourceful and determined experimenter. Combining manual skills with a huge capacity for sustained hard work, he became a highly successful developer and entrepreneur.

#### Hertz's experiments

Hertz generated electromagnetic radiation with an induction coil, a spark gap and what we now call a dipole aerial. He detected it with a tuneable loop resonator containing another, very small, spark gap. He demonstrated that the radiation had the characteristics of waves and, like light, could be reflected, refracted, diffracted, polarised and made to produce interference patterns. His method was to set up standing waves with a sheet metal reflector and locate their nodes with the loop resonator. Thus he validated Maxwell's theory.

It was Hertz, incidentally, who pointed out the irrelevance of Maxwell's original notion, derived from analogies, that there had to be some kind of physical medium which the electric and magnetic forces acted upon - an aether. The essential relationships, he said, were in the equations themselves.

Hertz's laboratory experiments were recog-

nised everywhere. Branly, Lodge and Popov among others immediately repeated them and gave demonstrations to scientific and nontechnical audiences. Yet despite the fact that telegraphy existed and some of its pioneers like Morse and Preece had long been seeking a wire-less version, few seemed to realise that the Hertzian waves, as they became known, were offering them a potent new means of electrical signalling. The exceptions were Crookes, who predicted this possibility in 1892, and Lodge, who demonstrated in 1894 that it could be done.

#### Marconi's interest piqued

One of the scientists who followed up Hertz's experiments, however, was Righi at Bologna University. Marconi, then a teenager living near Bologna, had attended his lectures and studied his writings on e-m radiation. This was the start of Marconi's interest in Hertzian

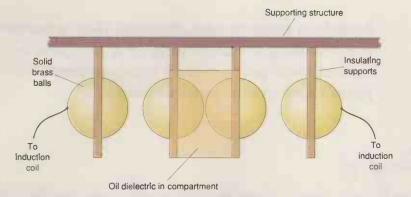


Fig. 1. Hertzian radiator formed by array of spark gaps. This is mounted at the focus of a cylindrical parabolic reflector (not shown).

waves. But it was later, in 1894, after reading more about Hertz's work, that he became fired with the idea of using these waves for communication. Then began the famous series of radio signalling experiments at his home in 1895.

These experiments at Bologna used apparatus broadly similar to that of the physicists who had followed Hertz's work. The transmitter was a keyed induction coil producing high-voltage pulses, a spark gap and a short Hertzian, or half-wave, dipole aerial. The receiver was little more than a dipole aerial with a non-rectifying detector in the form of a Branly type of coherer – though the term coherer was actually coined by Lodge.

Initially, the ranges achieved were very short – up to about 100 metres. But then Marconi had the idea, suggested by Popov's experiments in detecting distant thunderstorms, of replacing the Hertzian dipole in both transmitter and receiver with an elevated electrode, or antenna, on one side and an earthed metal plate on the other.

#### Marconi's important idea

These modifications gave a tremendous increase in range – eventually, with an 8m high antenna, to about 2.4km. Thus Marconi had devised what is now called the quarter-wave monopole, or Marconi aerial, in which a reflection or image of the quarter-wave element corresponds to the lower element of a vertical half-wave dipole. Some consider this to be his most important contribution to radio technology.

Marconi's transmitter, like those of Hertz and the other scientists, was a device for generating and radiating electrical oscillations. Henry had already observed such oscillations in a discharging capacitor (Leyden jar). The Hertzian oscillator was essentially an LCR series resonance circuit containing a spark gap which acted as a switch. The L, C and R were those distributed in the wiring, spark gap and radiating conductors. This circuit, of course, had a natural frequency.

A high-voltage pulse from the induction-coil secondary winding, initiated by interrupting the primary circuit, starts to build up charges on the metal spheres of the spark gap. The electric field within the gap increases correspondingly until the breakdown potential is reached, at which an electrical discharge takes place through the ionised air in the gap. This conduction reduces the gap resistance to a low value and closes the *LCR* circuit, which goes into natural oscillation.

Oscillation continues for as long as the spark discharge is maintained and hence the 'switch' is closed. But resistance quickly dissipates the power, reducing the oscillation amplitude and resulting in a damped oscillatory waveform. With the gap potential falling, the discharge eventually stops; thus the spark gap switch opens the *LCR* circuit and the oscillation ceases. When the next high-voltage pulse arrives from the induction coil the process is repeated.

But the R in this circuit was more than just its ohmic and spark gap resistance: it included the radiation resistance of the aerial system. A good radiator, therefore, as Lodge had pointed out, meant heavy damping and hence shortening of the oscillation and radiated wavetrain. It was a problem for effective signalling. Sustained oscillation and good radiation were conflicting requirements.

#### Syntony

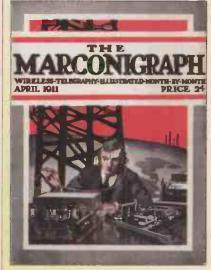
Eventually the problem was solved by the technique of syntony, or tuned coupled circuits, which also provided better selectivity.

#### The link with Electronics World

This journal, which has just completed 85 years of continuous publication, owes its existence to the wireless telegraphy company that was established with the commercial protection of the 1896 patent.

Founded as *The Marconigraph* in April 1911 (see the reproduction of the front cover), it was then mainly a house magazine, but aimed to "acquaint the lay reader with the latest possibilities in connection with this most marvellous invention" – at a price of 2 (old) pence per month.

In 1913 the magazine was sold to an independent publisher and became The Wireless World. When radio valves and components began to be utilised in other, non-communication, applications, electronics technology was born – eventually to subsume radio – and the journal started on the road to its present form.



Front cover of the first issue of The Marconigraph, which later became Wireless World and the present Electronics World.

For this the underlying resonance principle had been demonstrated by Lodge in 1889. Marconi patented his 'syntonic' transmitting and receiving system in 1900: patent No 7777.

The 1896 patent, however, describes simple, open systems without tuning. Transmitting frequency is determined solely by the dimen-

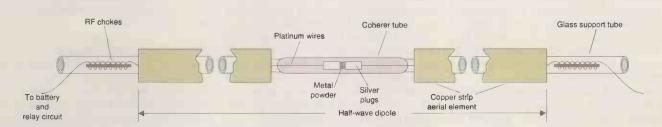


Fig. 2. Dipole receiving aerial with coherer between the elements. The coherer is connected to a battery and relay through two rf chokes.

sions of the oscillating and radiating elements. Though in practice the radiated spectrum is very wide. There are three kinds of spark transmitter, all using induction coils with vibrating interrupters pulsing the primary windings; and one kind of receiver, based on a coherer with resonating aerial elements connected to it.

Morse code signals are sent by a key in the pulsed primary circuit of the induction coil. At the receiver these are read by an ordinary telegraph instrument actuated from the coherer through a relay.

In one of the transmitters the radiator is essentially a Hertzian dipole formed by a horizontal array of metal balls providing spark gaps, as shown in Fig. 1. Other texts describe this as a Righi oscillator. The balls are solid brass, 100mm in diameter. The outer two gaps are about 25mm while the central gap is only about 1mm.

Obviously these spherical electrodes provide

much of the oscillator's capacitance as well as being radiating parts of the dipole. Capacitance and dielectric strength between the two middle balls are increased by an oil dielectric held in a compartment. This 'increases the power of the radiation'. Oscillations of 25cm wavelength (uhf) are produced.

To improve the range and directivity of this radiator, the assembly is mounted at the focus of a cylindrical parabolic reflector, made by

- Earth

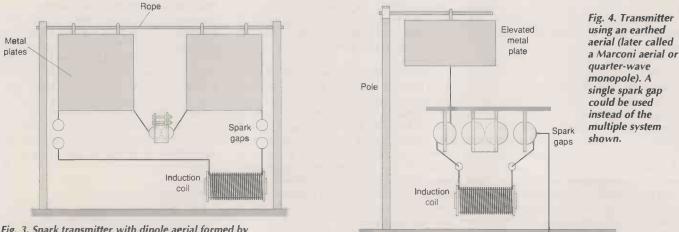
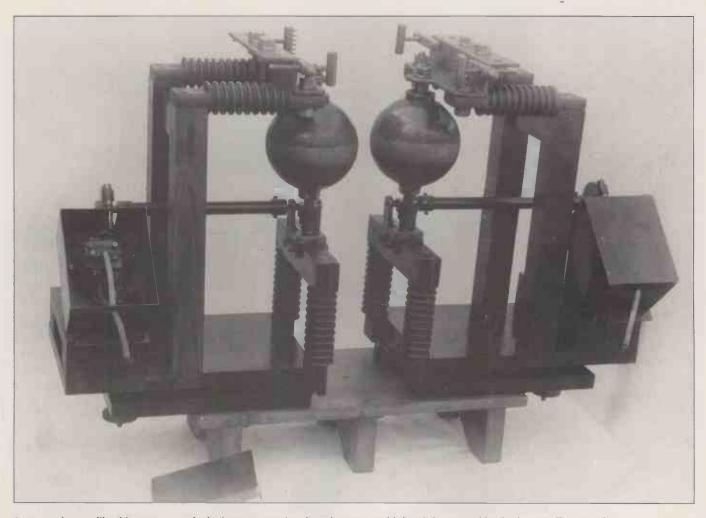


Fig. 3. Spark transmitter with dipole aerial formed by elevated metal sheets.



Later spark gaps, like this 1905 example, had motors rotating the spheres to avoid the pitting caused by discharges all at one place.

#### HISTORY

bending a sheet of brass or copper. Fed from an induction coil normally giving a 25cm spark, the system achieves a range of over 3km.

#### Tuning the receiver with tin foil

Corresponding to this transmitter is a receiver with a resonating half-wave dipole, Fig. 2, placed at the focus of a similar reflector. Here the dipole elements are 12mm wide strips of copper, cut to the required length to tune with the transmission. The appropriate lengths are found with a separate tuning aid – essentially a resonator containing a tiny spark gap, formed by strips of tinfoil which are experimentally cut to various trial lengths.

Two chokes at the outer ends of the dipole provide high impedance to rf and isolate the aerial from the electrical wiring. This was done to concentrate the received energy in the resonator and coherer.

In the middle of this receiving dipole is a coherer, or what patent calls a 'sensitive tube'. This comprises a 38mm long sealed glass tube of about 2.5mm internal diameter, containing two silver contact plugs with a gap of about 1mm between them. In this gap lies a quantity of loosely packed metal powder or filings: a mixture of 96% nickel filings and 4% silver filings is recommended. The sealed tube is preferably evacuated.

The coherer is connected in a circuit containing a 1.5V battery and a relay. Initially the loose powder has low conductivity and passes very little current. When the dipole picks up a signal, however, the rf energy causes the filings to cohere and conduct strongly. The resulting current through the coherer then operates the relay and the telegraph instrument.

#### Mark tap space

Unfortunately the filings continue to cohere after the Morse dot or dash has ceased, so a small vibrating hammer or tapper, similar to an electric bell mechanism, has to be used to unstick the grains ready for the next Morse symbol.

A different kind of transmitter is illustrated by a diagram similar to Fig. 3. Two metal plates are suspended by insulators from a rope and connected through spark gaps to the induction coil to form a Hertzian oscillator. No reflector is used. From the description, the mode of operation is not clear, though obviously the two plates not only form a dipole aerial but also provide a lot of capacitance and hence radiated power. The larger and higher they are, according to the text, the greater the signalling range.

Finally the patent reveals the use of the earthed antenna - the Marconi aerial discussed

above – in a transmitter, Fig. 4, and a corresponding coherer receiver. At both stations the single elevated metal plate is suspended from a pole, though kites covered with tinfoil are also successful. This system is advantageous where "obstacles such as many houses or a hill or mountains intervene between the transmitter and receiver."

Again Marconi reports that the higher and larger the antenna plates the greater the range achieved.

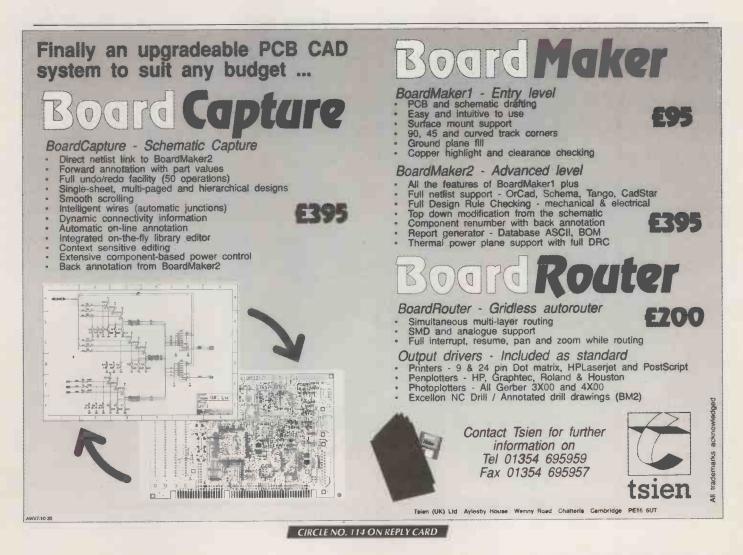
#### Start of a company and industry

Acceptance of this first patent in July 1897 provided the commercial basis for setting up a company that same month to develop and promote the Marconi apparatus. This was The Wireless Telegraph and Signal Company Limited, which eventually became The Marconi Company and finally part of GEC.

Some of the early demonstrations and communication achievements are described and illustrated in the *EW&WW* article 'Marconi Beginnings' in the January 1992 issue, on pages 74-76.

#### **Further reading**

A useful bibliography on the origins of radio is published in an article 'Guglielmo Marconi and Early Systems of Wireless Communication' by R W Simons, *GEC Review*, Vol 11, No. 1, 1996.



# Winner: best rf article '95

The article Demodulation – a new approach – on the following pages is winner of *Electronics World*'s 'Best rf article '95' award – a Hewlett Packard programmable signal generator priced at £4000. Some 30 entries were considered, representing articles both published and unpublished articles offered to *EW* during 1995 – which is why the judging took longer than planned. All were interesting and there was a healthy shortlist of contenders for first place. But Archie's work stood out in that it represents a technique that truly breaks new ground in the important area of demodulation.

Since the article's publication in the December 1995 issue, Archie has **further** developed his amplitude-locked-loop and is presenting a paper describing the technique's mathematical model at BSI 96 International at Chertsey on 4 June.

The US Army has been looking at the demodulation system for incorporation into their new pan-forces radio system called 'Speakeasy'. From their initial evaluation, they agree that the technology works "as advertised". Additionally, DRA Malvern is using the analogue-locked-loop

Additionally, DRA Malvern is using the analogue-locked-loop technique in advanced laser dopplerimetry to minimise co-channel interference. Since publication of the article, eight advances have been made to the high-performance demodulator. Among these, the system's speed has been increased by a factor of five and overall dc coupling is being used to reduce cross-modulation products.



For his rf design article, 'Demodulation – a new approach', Archie Pettigrew wins an HP 8647A synthesised rf signal generator. Fully programmable and operating from 250kHz to 1GHz, this generator is designed for a variety of general purpose applications and semi-automated receiver test. With 300 storage registers and ten user-definable sequences – accessible from a remote keypad – the HP 8647A easily adapts to any test procedure. The generator features HPIB interface, a solid-state programmable attenuator and built-in am/fm modulation capability.

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# Demodulation a new approach

Archie Pettigrew's new demodulator concept uses amplitude-locked loop techniques to produce significant improvements in the quality of fm and am reception.

The amplitude-locked loop was developed to overcome a number of fundamental difficulties which have existed since the inception of both amplitude and frequency modulation – am and fm.

With the radio spectrum becoming more crowded each year, and carrier frequencies moving inexorably higher, two basic problems with am and fm transmission become more obvious. Amplitude modulation becomes highly distorted when the carrier fades – or in certain cases, vanishes altogether. Frequency modulation becomes highly distorted and unintelligible when another fm signal arrives at the antenna at the same time as the wanted signal which is equal in amplitude and of a similar frequency.

Both these breakdown processes are caused by interference in the form of multi-path<sup>1</sup> Doppler or quasi-synchronous<sup>2</sup> reception. All these forms become worse as frequency of the carrier is increased i.e. as wavelength is shortened and/or as transmission becomes mobile<sup>3</sup>. By using an amplitude-locked loop and associated circuitry, many of these interruptions can be avoided, and more reliable communications achieved.

This article describes in detail the operation of two demodulators, one for am and the other for fm, using the amplitude-locked loop.

#### Amplitude-locked loop

The amplitude-locked loop, ALL, is the dual of the phase-locked loop, PLL. It works in the magnitude domain rather than the phase or frequency domain. It consists of a linear multiplier contained inside a high gain, high bandwidth servo loop.<sup>4,5,6</sup>

A phased-lock loop is similar in that it consists of a voltage controlled oscillator contained in a high gain, high bandwidth servo loop. Figure 1 shows a diagram of the amplitude-locked loop<sup>7</sup>.

Carrier from the intermediate frequency stage of the radio enters the ALL at the first port of the linear multiplier. The second port of the multiplier is set to a nominal value of unity. The modulated carrier passes through the multiplier to the modulus detector which accurately detects the modulus of the carrier down to white noise levels.

A dc reference voltage compares and subtracts the incoming modulus voltage and a difference or error voltage is generated, e(t). This voltage is integrated and reversed in sign. Output of the integrator is added to the restoration voltage which sets up the operating conditions – or bias conditions – of the loop.

When no carrier amplitude is present, the loop is out of lock. The integrator drifts to its maximum voltage and the multiplier is at maximum gain awaiting an input. When the carrier appears, an initial transient occurs as the loop pulls into lock. Servo feedback causes the carrier amplitude at the output of the multiplier to be fixed or locked to an amplitude defined by the loop reference voltage.

Let a simple amplitude modulated carrier  $v_1(t)$  be described as,

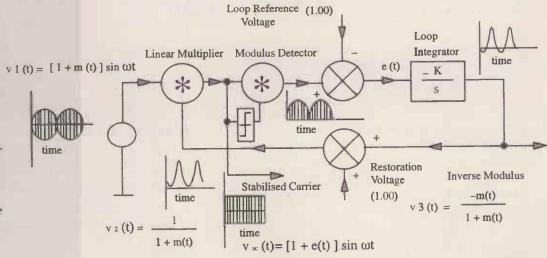


Fig. 1. Amplitude-locked loop consists of a linear multiplier, modulus detector and a high gain integrator. When the loop is closed, envelope variations of the carrier are reduced to insignificant proportions due to servo action and an error signal called the inverse modulus is produced.

#### **RF DESIGN**

#### $v_1(t) = [1+m(t)]sin\omega t$

where m(t) represents the modulating function of time and  $sin\omega t$  is the normalised carrier amplitude of  $\omega$  radians per second.

After some mathematical analyses, a number of amplitude-locked loop identities become evident. Assuming that open-loop gain is sufficiently high that servo theory is valid, ie the value of K in the integrator is greater than 100 at the maximum frequency of interest, the stabilised carrier, vsc(t), becomes,

#### $v_{sc}(t) = [1 + e(t)]sin\omega t$

where e(t) is the loop error voltage which becomes insignificant due to the high open loop gain. That is,  $v_{sc}(t)=[10]sin\omega t$ 

Voltage  $v_{sc}(t)$  represents a stabilised carrier with no envelope variations. Voltage at the second input to the multiplier must therefore be the reciprocal of the input modulation. As a result,  $v_2(t)$  is 1/[1+m(t)] and  $v_3(t)$  is -m(t)/[1+m(t)] by subtracting unity.

Three signals have been obtained – the unmodulated carrier, the inverse of the modulus and the inverse modulus with the dc term removed. Unfortunately, there is no requirement to recover the unmodulated carrier in amplitude modulation. The demodulated signal is the reciprocal of the modulation which is a highly distorted version of the original signal. The signal at the integrator output is simply the reciprocal of the modulation but with an average value of zero. At first sight, nothing scems to have been achieved by this circuit so why investigate further?

Much the same arguments were used for the PLL when it was first suggested. For example, the PLL could easily have been replaced by a piece of wire and at a much lower cost etc.

Perhaps for the above reasons the concept of the ALL has never been investigated, even in the valve or tube era of electronics. If the ALL is not directly suitable for demodulation of am, can it be used to replace the limiter-filter in the demodulation process? Indeed it can as will be explained.

#### Application to fm demodulation

When two fm carriers of equal amplitude are added, their envelope increases to twice the individual size and reduces to zero at the instantaneous difference frequency. This envelope variation will be eliminated by the servo action of the ALL. This is similar to the action of a hard limiter and a filter and fulfils the first requirement in fm demodulation – that am variations must be removed before demodulation.

A second signal is also available which is the inverse of the modulus of the two carriers. Could this second error signal be used constructively to improve fm demodulation?

#### **Operating limits**

Before continuing, it would be sensible to define the limits of operation of the first ALL unit. Starting with an intermediate frequency of 455kHz, amplitude and phase information

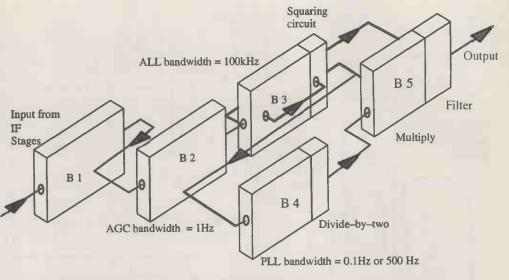


Fig. 2. ALL-PLL amplitude demodulator. The amplitude-locked loop alternates between in-lock and out-of-lock for strong and weak carrier signals. The PLL captures the carrier phase quickly but releases it slowly. A highly stable carrier is generated.

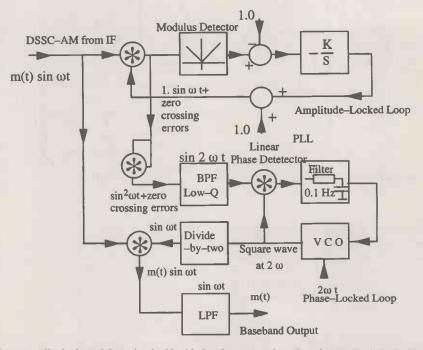


Fig. 3. Amplitude demodulator for double side-band suppressed carrier. The amplitude-locked loop generates a constant envelope from the input carrier. As the carrier approaches zero the amplitude-locked loop loses lock and the gain changes by 80dB. Phase-locked loop bandwidth is reduced by the same amount and synchronous demodulation is now feasible even in conditions of high noise.

is updated at twice the carrier frequency or 910kHz.

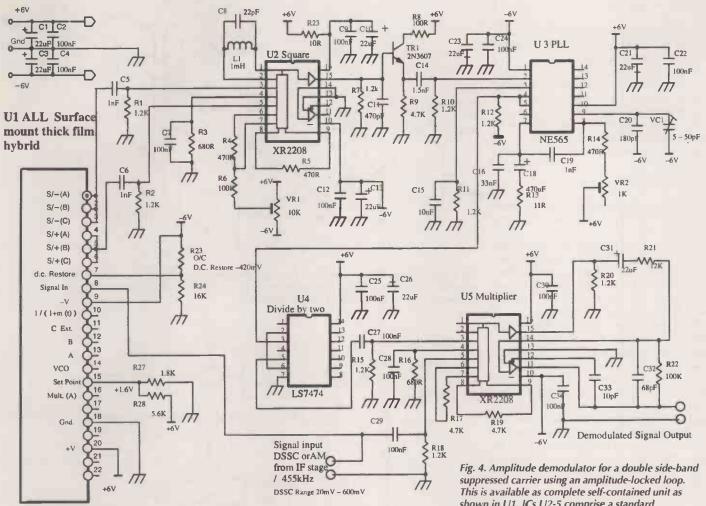
In a closed-loop feedback system, instability starts to occur at about one tenth of this frequency or 91kHz. So the ALL unity gain bandwidth was set to 91kHz giving an open loop gain at say 1kHz of 91 or 39dB. This was improved later by using a double integrator.

The dynamic range of the ALL was determined by the offsets and the characteristics of the linear multiplier, the *Exar 2208*. This was found to be to +20dB (10) to -6dB (0.5) or a linear lock range of 26 dB.

In practice, the ALL will track 26dB of amplitude variation up to a frequency of about

20kHz without significant error. This was found to be more than adequate for all narrowband fm speech channels. The lock-in transient is very short since the ALL is more linear than a PLL. Typically it was measured at about 4µs, i.e. the time required to reach 95% of the steady state value of stabilised amplitude.

Using a simulation package called *MATRIXx*, optimum circuit operation was established before any hardware was constructed. A much improved loop was designed using a double integrator with suitable phase advance for stability. This is described further in reference 8.



shown in U1. ICs U2-5 comprise a standard synchronous demodulator.

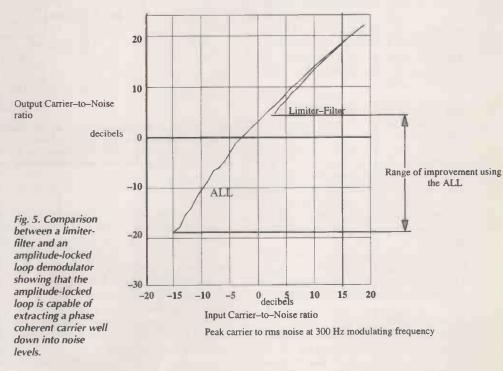
Applying the amplitude-locked loop The first application of the ALL is to improve the amplitude modulated double side-band suppressed carrier. This represents the ultimate in carrier – or Rayleigh – fading since the carrier vanishes at every silence of the speech waveform, by definition.

The core of this problem is the recovery of a stable carrier. There is no carrier present during the silence between speech. The worst case occurs at the lowest modulating frequency and lowest amplitude of the signal.

Doppler effects may cause the carrier to be shifted by say 100Hz so that high-Q filters are not permitted due to their rapid phase changes at resonance. Should the system lose lock, then reliable re-lock must occur within say one cycle of the lowest operating frequency, say 300Hz, or in about 3ms.

The carrier recovery circuit must also be able to track frequency variations up to 100Hz to an absolute phase accuracy of less than say 45° error between the modulated carrier and reference carrier. Assuming that a PLL is available to regenerate the carrier at 455kHz, then two conflicting conditions need to be met simultaneously.

Since amplitude of the DSSC signal is continuously varying, the envelope must first be



made constant. The PLL must have a wide capture and track range for fast lock-in and frequency tracking, yet it must have an extremely narrow noise bandwidth for stability during every speech silence.

The solution to these seemingly conflicting requirements is shown in Figs 2 and 3 in block diagram form and in circuit form in Fig. 4. This could be could be done by limiting and filtering which would be successful at high instantaneous amplitudes. A major problem occurs at low amplitude and low frequencies with noise. Noise captures the limiter, the voltage controlled oscillator becomes unstable and the phased-locked loop loses lock. System failure ensues. If the limiter is replaced by an ALL, a different process takes place.

At high instantaneous amplitudes, the large negative feedback of the loop flattens the amplitude variations giving a constant envelope at the output of the linear multiplier. At low instantaneous amplitudes, the ALL drops out of lock since its track range has been exceeded.

Gain of the 'loop' drops to the gain of the multiplier alone and not the combined gains of the multiplier, modulus detector and the integrator. At 300Hz, this represents a change from 80dB to 20dB. The noise level is not amplified, and in effect, the system closes itself down.

White noise is not permitted to overtake the signal, as would happen in a limiter. This is the advantage of the in-out action of servo feedback.

#### **Carrier generation**

A pure squaring device follows the analoguelocked loop to generate a coherent carrier at  $2\omega$ . When the ALL is out of lock, the PLL is being driven by a zero level carrier. Since the bandwidth of any linear PLL is a direct function of the input amplitude, its closed loop bandwidth drops to zero.

The voltage controlled oscillator free wheels

time

ference

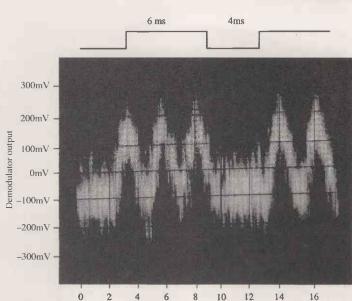
on the long open-loop time constant of the PLL since there is no significant noise energy to cause perturbations. After a divide-bytwo circuit, normal demodulation takes place.

Thus the PLL has effectively two bandwidths. The first is with signal present and the ALL in lock. With values suggested in Fig. 3 this bandwidth measures about 500Hz. When no carrier is present, i.e. with the ALL out of lock, there is no signal present at the input to the PLL.

The effective open loop gain of the PLL is reduced to zero assuming a linear phase detector.

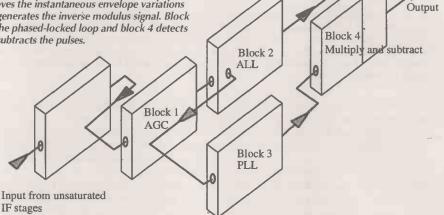
Fig. 8. Complete FM201 demodulator using an amplitude-locked loop, a phase-locked loop and an analogue signal processor. Inverse modulus from the amplitude-locked signal is multiplied by the phaselocked loop output to produce the impulse alone signal which is scaled and subtracted from the original phase-locked loop signal.

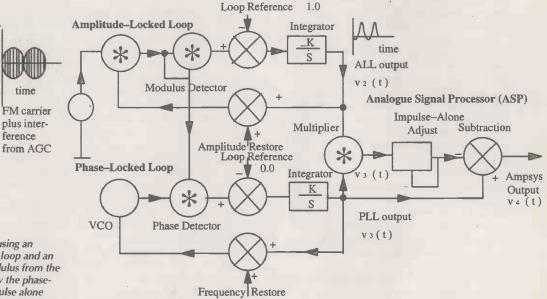
Fig. 6. Oscilloscope measurement of demodulated output showing a 300Hz signal gated on and off at 6 and 4ms intervals at a carrier-to-noise ratio of 0dB. Note stability of the noise during the period of zero level carrier. This is due to the amplitudelocked loop and the phase-locked loop both shutting down and awaiting the resumption of the signal.



Time (ms)

Fig. 7. The FM201 demodulator. Unsaturated output from the IF stage is stabilised in a slow acting automatic gain control, block 1. Block 2 removes the instantaneous envelope variations and generates the inverse modulus signal. Block 3 is the phased-locked loop and block 4 detects and subtracts the pulses.





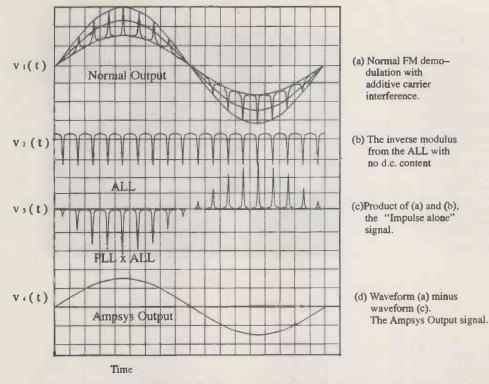


Fig. 9. Waveforms in the FM201 demodulator. The inverse modulus  $v_2(t)$  is multiplied by  $v_1(t)$  and subtracted from the phase-locked loop output to give  $v_4(t)$ . Fig. 9a).Normal FM demodulation with additive carrier interference – phase-locked loop output. Fig. 9b) inverse modulus from the amplitude-locked loop with zero average ie no dc content. Fig. 9c) shows the 'impulse alone' signal – product of the signals 9a) and 9b). Fig. 9d) final demodulated output where all harsh impulses or spikes have been removed.

Stability of the voltage controlled oscillator is then determined solely by the time constant of the filter following the phase detector. This can be made large ie of the order of one second.

Carrier stability is thus maintained due to this very long time constant. By use of the ALL, phase-capture transients are very short when signal is present and phase loss transients are long when the signal is absent. By this technique, the coherent carrier can be recovered reliably even during periods of poor carrier-to-noise ratio. The circuit diagram of this system is shown in Fig. 4.

The ALL is contained in the hybrid block  $U_1$ . The circuits which follow the ALL represent the normal synchronous AM demodulation technique, namely, a pure squaring device  $(U_2)$  followed by a narrow track range PLL  $(U_3)$ , a divide-by-two,  $(U_4)$  and finally a synchronous multiplier  $(U_5)$ .

Results obtained for this demodulator are presented in Fig 5. Figure 5 shows the comparison between a demodulator using a limiter and filter in place of the ALL. Whereas the limiter-filter ceased to operate effectively at about 3dB carrier-to-noise ratio, the ALL circuit still maintained synchronism until well into noise. Cycle slipping occurs in both demodulators at about the same relative position but does not result in complete loss of intelligibility.

It is interesting to note that there is no threshold effect present as would be the case in fm or angle demodulation. The output signal-to-noise ratio tracks the input carrier-tonoise ratio in a linear manner.

Results obtained from the above demodulator exceeded the performance of the normal synchronous demodulator in that carrier recovery could be achieved down to and below unity carrier-to-noise ratios. Figure 6 shows an oscilloscope trace of a 300Hz sine wave signal which is being gated on and off at 6 and 4ms intervals. Carrier-to-noise ratio with signal present was 0dB. Noise and carrier amplitudes were equal.

Due to carrier stability, system white noise is demodulated in a coherent manner. The PLL has an effective phase capture bandwidth of 500Hz and a phase release bandwidth of 0.1Hz. This phase capture-release phenomenon is a direct consequence of utilising the two in-lock and out-of-lock characteristics of the ALL and PLL simultaneously to make a near perfect am demodulator. This represents a major improvement in the state of the art on am demodulation.

This demodulator operates reliably and completely independently of the presence or absence of carrier. It is therefore ideal for the reception of am during multipath or quasisync. conditions.

#### FM demodulation

Frequency modulation is transmitted at constant amplitude. Any amplitude variation at the point of reception must be due to interference or noise acquired en route.

According to perceived wisdom, amplitude

variations must be removed by hard limiting and filtering of the carrier on reception. If not, two forms of degradation will occur at the demodulator output. The first is due to envelope variation and the second to phase variation.

In reality, the fm carrier is degraded not only by naturally occurring phase noise but also by amplitude noise. This is converted to phase noise in the limiting process. These two processes combine as the input carrier-to-noise ratio approaches a low value of typically 12dB.

The catastrophic fm threshold effect begins and rapid deterioration of the output signal-tonoise ratio then follows.

This same effect causes fm reception to be rendered unintelligible if two fm transmissions arrive at the antenna at equal or near equal strength to each other – assuming co-channel frequencies.

The corrupting carrier may be another transmission – co-channel – or a delayed version of the wanted carrier – multipath. It could even be a version of the same broadcast from an equidistant transmitter – simulcast or quasisync reception. Harsh acoustic spikes are demodulated which are inband and cannot be filtered.

#### **Capture effect**

In the past, much has been made of the 'capture effect' in fm. Generally, this means that if one carrier is say 10% stronger than the other, say 1dB, then capture takes place and the weaker station is completely suppressed. This was the argument put forward by Edwin Armstrong the inventor of fm. It is true – but it is not the whole story.

The unwanted carrier is suppressed but not into silence, which would be ideal. On the contrary, the co-channel interference is demodulated into strident noise, or large impulses which are intolerable to the ear and destructive of all intelligible communication. So destructive is this interference that all fm transmissions start to break down in the region where either carrier is within 6dB of the other. This is sometimes called the 'distortion zone' – when its existence is admitted. The 'capture effect' is not an advantage but is in fact a major disadvantage of fm in a crowded radio spectrum.

Frequency modulation works well when;

- carrier strength is high,
- there is only one single carrier,
- there is no co-channel interference,
- there is only one direct signal path,
- modulation depth is virtually unlimited
- transmission power is virtually unlimited.

These conditions prevailed some fifty years ago, but unfortunately not in today's overcrowded spectrum.

Ideal requirements of the modern demodulator would be a circuit technique which would make fm demodulation linear at low carrier-to-interference ratios but still have the co-channel rejection properties at high carrier-

#### **RF DESIGN**

to-interference ratios. Quasi-sync and multipath reception would then be improved by the addition of the intelligence in the carriers and co-channel reception would be equivalent to crossed lines in telephones.

#### The Ampsys FM201 demodulator

Using an amplitude-locked loop for the first time, an fm demodulator has been designed and tested which demonstrates the above requirements. It is designated the Ampsys *FM201*. Its block diagram is illustrated in Fig. 7 and a system diagram in Fig. 8.

In the FM 201 demodulator there are four separate processes or stages. The first process, after the normal intermediate frequency filtering, is to stabilise the wanted carrier and the interfering carrier to a fixed average value using a slow automatic gain control circuit. This process is necessary in order to present the ALL with a fixed average signal level.

The fm was originally transmitted as a fixed amplitude and the automatic gain control restores this long term average. Saturating limiting is always avoided. The automatic gain control block has a bandwidth of 10Hz.

In the second stage, block 2, the ALLremoves all short term variations leaving the carrier similar to the output of a hard limiter and filter. This stabilised carrier is then applied to the input of the PLL, block 3, which is regarded as normal demodulation.

A second output from the ALL, the modulus reciprocal less the dc term, is applied to a multiplier in the analogue signal processing stage, block 4, Fig. 7. Output of the PLL is applied to the second port of this multiplier. A product is formed at the output of this circuit – the 'impulse alone' signal. 'Impulse' refers to spikes superimposed onto the baseband signal by the demodulation process.

This new baseband signal is scaled in size and subtracted from the original PLL output. Care must be taken to ensure that any phase delays through the ALL and the PLL are equal otherwise subtraction will not be possible.

A demodulated signal is created which is free of harsh spikes and is now perfectly intelligible even when the carrier and interference are identical in magnitude. A simplified version of the relevant waveforms is shown in **Fig. 9a-d.** Voltages  $v_1(t)$  to  $v_4(t)$  correspond to those marked on Fig. 8.

#### Worst-case fm reception

Figure 10 is an oscillograph of the demodulator output when the interfering carrier is located at the centre of the the intermediate frequency passband and is of equal amplitude to the wanted carrier. This represents one of the worst case conditions in fm reception. It would result in the carrier vanishing and doubling alternately at the instantaneous difference frequency. It is equivalent to a fade of infinite depth.

The normal output signal-to-noise figure is much less than zero and is unmeasurable by normal instrumentation. Acoustically, all intelligence is lost and the channel would be muted. With the FM201 demodulator, signalto-noise ratio rises to about 14 dB unweighted. This is acceptable in a communication channel and represents 100% intelligibility.

The link has been preserved, so avoiding the call being dropped. In normal demodulation when Gaussian white noise is added or when both carriers become weaker, distortion and noise effects become even more severe and generally intelligibility is lost just after the fm threshold point. This means that there can be a 'distortion zone' or failure gap as wide as 12dB. In simple terms this means that if one carrier is more than one quarter the size of the other at the antenna, failure ensues rapidly.

With the FM201 demodulator however, the spikes are removed, as are the 'Rician' spikes due to Gaussian white noise. The net result is a much improved communication channel with almost 100% intelligibility well below threshold. Further testing has given the following observations.

• When the interfering frequency is offset from the centre of the passband, similar subtraction can be achieved by inserting an offset voltage at the input to the final multiplier. The interfering frequency however must be fixed.

• When quasi-synchronous reception occurs, baseband signals combine and an improvement in the signal-to-noise ratio of approximately 26dB is measured at the equal amplitude reception point. Multipath distortion causes a small reduction in signal-to-noise ratio.

• When two modulated carriers are present, the result is similar to that of a crossed line in a telephone. Although this is not ideal, it is preferable to complete loss of intelligence.

• With a very weak carrier, harsh spikes are removed and noise subjectively more acceptable. White noise can never be removed since there is never enough unique information.

• When the carrier-to-interference ratio is high, the 'impulse-alone' product diminishes rapidly since there are no envelope variations. The weaker transmission is suppressed as in normal demodulation and all beneficial characteristics of fm are retained, for example, quieting and co-channel suppression.

#### To summarise

A new circuit concept has been proposed called the amplitude-locked loop which can be used in conjunction with a phase-locked loop to improve the quality of fm demodulation.

By using the fundamental property that fm is transmitted at fixed amplitude, and that a unique relationship exists between the reciprocal of the modulus and the fm phase perturbations, a new signal has been derived called the 'impulse-alone' signal.

By a simple subtraction process this new signal can be used to eliminate spikes generated in fm demodulation. A fundamentally improved method of fm demodulation has been proposed which meets the criteria set out

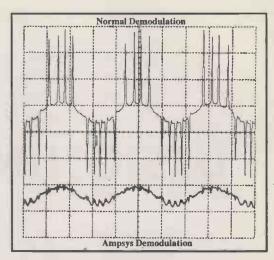


Fig. 10. These spikes could not be removed by any form of baseband filtering. At the interference-to-carrier ratio of unity the spike size is reduced by a factor of 20 fold, 26dB. Normally all intelligibility is lost. With Ampsys, demodulation is 100% intelligibility.

above for fm demodulation in today's overcrowded radio spectrum.

Two demodulators using the ALL have been built and tested and are available for evaluation purposes, from Ampsys, one for am demodulation and the other for fm.

#### **Acknowledgments**

I would like to thank Dr T. J. Moir of the Department of Electrical and Electronic Engineering at the University of Paisley for his help in the preparation of this paper and to the Governors of the University of Paisley for their support in the development.

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8. Moir T. J. 'Simulation of an Amplitude-Locked Loop using MATRIXx', *Electronic Engineering*, July 1995, pp 27-32. Ignoring cost, nearly all power switching applications can benefit from replacing a bipolar output device with a power mosfet. But there is one very common application where this is still not the case. David Sharples explains why.

# DESIGNING CRT deflection

The number of power applications that still have a bipolar transistor monopoly reduces by the day. The ingress of new technologies, such as high performance mosfets, igbts and power ICs, brings the humble bipolar transistor ever closer to the end of the road.

But there is one very common application where a bipolar high voltage transistor is the only viable power switch: tv and monitor horizontal deflection. As this situation is likely to continue for some time, while crt remains the dominant display technology, it is worth taking an extended look at this application.

#### Horizontal deflection circuitry

To understand the operation of the circuit shown in the panel consider the transistor turned on at time  $t_0$ , as shown in the waveforms in Fig. 1. DC voltage across the coil will result in a linear ramp in coil current:

$$\frac{dI_c}{dt} = \frac{V}{L_c}$$

This current,  $I_{\rm C}$ , flows through the transistor to ground. At time t<sub>1</sub> the transistor is turned off. Turn-off is not instantaneous for a bipolar transistor and the current continues to rise for a couple of microseconds after the forward base current has stopped. This phase of operation is known as the transistor storage time: conduction is maintained by charge 'stored' in the device during the previous on time.

To turn a bipolar transistor off efficiently charge has to be extracted from the base, ie a reverse base current. When the base is depleted of charge to a level that restricts the flow of electrons from emitter to collector, the load will start to see turn-off. In this example, the load is coil  $L_c$ .

At the end of storage time,  $t_2$ , the voltage across the device,  $V_{CE}$ , starts to rise. This rise in voltage reduces the voltage across  $L_c$  which in turn reduces the current ramp. With optimum charge extraction during the storage time the transistor collector current,  $I_C$  will fall rapidly to zero in around 300ns.

As current in  $L_c$  cannot change so quickly, it is diverted to the flyback capacitor,  $C_{\rm fb}$ . This current causes the voltage on  $C_{\rm fb}$  to rise;  $L_c$  and  $C_{\rm fb}$  operate as an *LC* circuit: sinusoidal rising voltage, cosinusoidal falling current.

At time  $t_3$ , current will be zero and a peak voltage will be reached. This is the peak  $V_{CE}$  on the horizontal deflection transistor.

Peak voltage now drops as the current is reversed and  $C_{\rm fb}$ 

discharges. If diode  $D_2$  was removed the system would become an *LC* resonant circuit. However, the diode has an important role.

At time  $t_4$ , the voltage reaches zero the current is a maximum, a negative going voltage forward biases the diode and the capacitor current is re-routed to the diode. The sinusoidal rising and falling voltage coincides with a polarity change in the coil current, this has then facilitated the flyback function.

With a negative peak current the beam is ready to start a scan at the left hand side of the screen. With a steady forward voltage drop across the diode,  $V_{\rm F}$ , the voltage across the coil is constant yielding a linear ramp in coil current. As the diode/coil current approaches zero the transistor is turned on again. This early turn-on ensures a smooth zero-crossing as the coil current now becomes transistor current as the beam crosses the centre of the screen. And so the cycle continues.

Typical waveforms for the deflection transistor  $I_{\rm C}$ ,  $I_{\rm B}$  and  $V_{\rm CE}$  are shown in Fig. 2.

#### Typical device types

Two of the semiconductor devices shown in the circuit in the panel are standard commodity parts and two are unique to this application.

**Primary switch transistor**  $Q_1$ . In the circuit in the panel this is shown as a mosfet but in most television circuits a cheaper bipolar is used. For a low primary supply voltage an industry standard bipolar *BC337* or *2N7000* mosfet could be used. For high primary supply voltages industry standard types can still be used: *BF422* (bipolar) or *BS108/BSN254* (MOSFETs).

**Turn-off** diode  $D_1$ . Most small diodes will fulfil the requirements of this application. A well-used type is the Philips *BYD33D*.

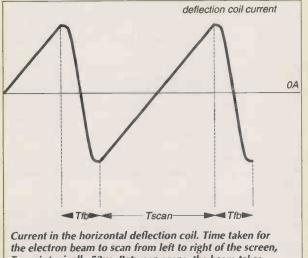
**Deflection transistor**  $Q_2$ . Most deflection circuits have a peak flyback voltage of 1100-1200V; to allow for fault conditions the standard peak voltage of deflection transistors is 1500V. A small 14in television will only require a peak coil current of 2A. For the large screen, home cinema type tvs – up to 36in – peak coil current can be as much as 7A. Over specifying the current is not efficient in this application: a bigger piece of silicon may not be better than a correctly specified device.

#### COMPONENTS

#### **Raster scanning basics**

In the UK and mainland Europe, conventional tvs have a complete picture change 25 times every second, ie a change every 40ms. Each picture is made up of a series of lines, a 625 line system being the current standard. A change of 625 lines in 40ms implies 64µs per line. From this comes the 16kHz – actually 15.625kHz – horizontal, or line, frequency.

Each line is produced by the horizontal deflection of the picture tube's electron beam as it scans across the screen, left to right. The time the beam takes to scan from left to right is the scan time,  $t_{scan}$ . When the beam reaches the right hand

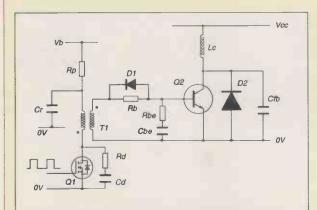


the electron beam to scan from left to right of the screen,  $T_{scan}$ , is typically 52 $\mu$ s. Between scans, the beam takes 12 $\mu$ s to fly back, hence  $T_{fb}$ .

side of the screen it has to fly back to the left hand side before the start of the next scan. Time taken for the beam to fly back is the flyback time,  $t_{fb}$ . Typically, the 64µs per line is composed of a scan time,  $t_{scan}$ , of 52µs and a flyback time,  $t_{fb}$ , of 12µs.

Originating at the cathode gun at the back of the picture tube, the electron beam is accelerated to the screen by a high potential anode, typically 25kV. The beam is deflected horizontally during the scan time by a magnetic field produced by a deflection coil. This field is produced by a current ramp through the deflection coil, as shown above.

This current waveform can be produced in a variety of ways but there is one dominant circuit which is used in over 90% of television and monitor designs, this is shown in its simplest form in the diagram below.



Used in over 90% of monitor and television designs, this simplified circuit produces the current waveform required to scan the electron beam from left to right on the screen.

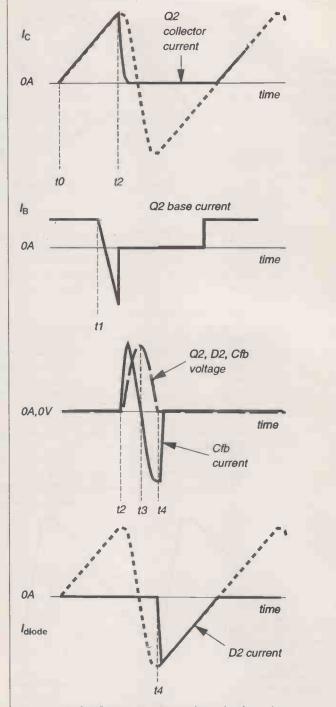
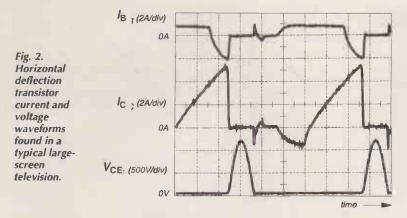


Fig. 1. Typical deflection circuit waveforms for the main circuit elements of the circuit in the panel.

Only a few of the world's major semiconductor suppliers offer a complete range of deflection transistors. Over 95% of the televisions produced will have a deflection transistor from one of these suppliers. Philips types range from the industry standard, and much copied, *BU508* to the new *BU2530AL*.

Damper diode  $D_2$ . As the damper diode is in parallel with the deflection transistor (see the circuit in the panel) it has the same peak voltage requirements. Also the coil current is symmetrical about OA, therefore, the current requirements of the damper diode are the same as the deflection tran-

#### COMPONENTS



#### sistor.

Products for this application are offered by most of the major semiconductor rectifier suppliers and some of the deflection transistor suppliers; including Philips Semiconductors. Philips types range from the glass bead *BY228* to the *BY459* in TO220 style packages.

#### **East/west and S correction**

To compensate for the curved surface of the picture tube, and obtain 'true' image reproduction, a number of corrections have to be carried out to the deflection waveforms; a linear ramp in coil current does not produce a watchable image. For horizontal deflection the two important correction functions to be aware of are S-correction and eastwest correction

Given a typical display surface and a linear coil current ramp a pattern of equidistant lines would actually show as close packed lines in the centre of the screen and widespaced lines at the sides. The electron beam has to travel further to the edges of the screen than the centre.

To obtain an equidistant display, a ramp that is fast at the deflection coil current

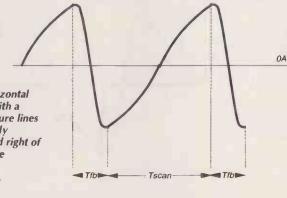


Fig. 3. Were the horizontal deflection coil fed with a linear ramp, the picture lines would be more widely spaced at the left and right of the screen than at the middle. S correction compensates for this.

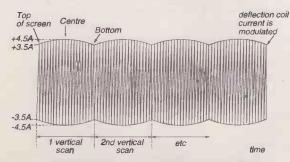


Fig. 4. Because the angle of electron beam deflection is smaller when the top and bottom of the screen are scanned, the current needed to move the beam from extreme left to extreme right is less than that needed to scan at the centre of the screen. As a result, the horizontal scan envelope is modulated as shown – a technique known as east-west correction. centre and slower at the edges is needed. This changes the shape of the coil current from a linear ramp to an S-shaped waveform, Fig. 3, hence the name S-correction.

S-correction is usually achieved by adding a capacitor in series with the deflection coil. In addition, compensation has to be made for the resistive component of the coil impedance. Coil resistance tends to shift the distortion to the right, and to compensate this a series negative resistance is required. This effect is achieved by a saturable inductance in series with the deflection coil.

The need for east-west correction arises from the fact that given the curved surface of the crt, the electron beam has to travel further per scan at the centre of the screen than at the top and bottom. And the amount of deflection is proportional to current. Adding this correction feature has the effect of applying an envelope to the deflection current with peaks for the centre.

Although the complete picture changes every 40ms, this is done by changing alternate lines so a frame changes every 20ms. Two frame changes produce a complete picture change. The frame frequency, or vertical deflection frequency, is then 50Hz. This 50Hz waveform is superimposed onto the deflection current to produce the east-west correction.

Modulated current is shown in Fig. 4. This is achieved by applying a modulated voltage across the deflection coil.

#### Generating eht

As well as being the power switch in the horizontal deflection circuit the transistor performs a secondary function – generating the extra-high tension, or eht. The eht circuit is a basic flyback converter power supply with a special high voltage transformer producing the 25kV required at the secondary windings. This transformer is commonly called the line output transformer, or LOT.

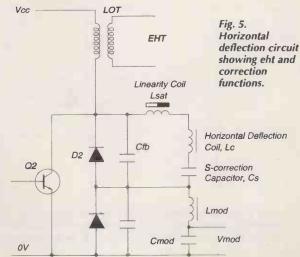
The horizontal deflection transistor provides the switching function to the primary of the LOT. For this reason the horizontal deflection transistor is also referred to as the line output transistor. Fundamentally, the eht function adds an offset of up to 1A to the total deflection transistor current,  $I_{\rm C}$ .

Coil current now becomes symmetrical about the hightension offset, therefore, the damper diode current reduces by this amount.

Adding the eht and correction functions to the basic circuit produces a modified circuit; a version of which is shown in Fig. 5.

#### **IDTV, HDTV and monitors**

So far, the discussion has been limited to European stan-



dard television but, fundamentally, all of the above holds also for US, Far East TV, idtv, hdtv and monitors.

The 50Hz frame frequency of European tv follows the 50Hz mains frequency. For 60Hz mains countries, including the US and Far East, 60Hz frame frequency is used.

For a 625 line, 50Hz system the line frequency is 15.625kHz, often referred to as 16kHz. For 60Hz systems fewer lines are employed – frequently 525 lines – yielding a line frequency of 15.75kHz. This difference in line frequency is not significant to the deflection transistor.

New idtv systems offer 'flicker free' viewing with a 100Hz frame frequency, which is less detectable to the eye than 50Hz. In turn the line frequency doubles to 31.25kHz. This change is very significant to the deflection transistor.

Current proposals for hdtv systems indicate a 64kHz line frequency may be standard. Again this will have a further significant bearing on the deflection transistor selection. However, this application is unlikely to produce any new requirements for deflection transistors as a more taxing application already exists – pc and workstation monitors.

Monitors are now being produced that offer modes of operation that require line frequencies above 100kHz. Such sets are still required to operate at the common low end as well; VGA is 31.5kHz. All these applications are being met by bipolar deflection transistors in circuits very similar to that shown in the panel.

Ten years ago, not many pundits would have predicted the use of bipolar power transistors in high volume, 100kHz plus switching applications into the 21st century. But this is almost certainly the case with horizontal deflection applications.

#### Specifying the deflection transistor

In the simplest terms, the device should provide the functions outlined above with minimum dissipation. The device should also be able to survive any fault condition that may occur.

In a cost driven business like domestic television and pc monitors, the device/circuit costs are also important. The following notes equate these requirements to device characteristics.

**On-state.** When the device is on, ie passing positive collector current,  $I_{\rm C}$ , the collector-emitter voltage drop,  $V_{\rm CE}$ , must be as small as possible. Any voltage drop will modulate the voltage across the deflection coil and either cause

#### **Optimising base current**

These steps outline how to match the deflection transistor's  $I_{\rm B}$  waveform to loading,  $I_{\rm C}$ .

• Measurement equipment: oscilloscope, 2 calibrated clamp-on current probes and 1 calibrated and compensated 100:1 voltage probe.

• Set  $I_{B}$  level (just before  $I_{B}$  turns off) to be 1/5 of the nominal peak  $I_{C}$  level.

• Set peak -/B level to 1/2 of the nominal peak /C level.

• Observe  $I_{\rm C}$  and  $I_{\rm B}$  waveforms, see Fig. 6. The  $I_{\rm B}$  waveform should be essentially flat during the on-state with a linear slope to  $-I_{\rm Boff}$ . • Observe  $V_{\rm CE}$  and  $I_{\rm C}$  waveforms during turn-off to when  $I_{\rm C}$ reaches zero. Waveforms for an optimised base drive are shown in Fig. 7.

• Observe the  $V_{\text{BE}}$  waveform; this should have no positive ring during flyback with an off-state level between -1V and -5V.

Once the principal operation has been established, the base drive should be optimised.

• Obtain high and low h<sub>FE</sub> samples from the supplier. These will represent the production spread for a particular device.

• Additional equipment for thermal tests: calibrated heatsink  $(R_{th} \ge 15 \text{K/W} \text{ for 16 kHz tv})$ , heatsink temperature measure (Eg thinfilm thermocouple between device and heatsink or infra-red detector), ambient temperature measure.

• Determine application minimum and maximum load conditions. In a tv these conditions could be forced: min. brightness and contrast, min. picture width for minimum load; maximum brightness and contrast, maximum picture width for maximum load.

• For high and low *h*<sub>FE</sub> devices record the steady-state heatsink and ambient temperatures for both minimum and maximum load conditions. Allow at least 15 minutes for the system to stabilise before taking temperature measurements.

where,

Power in the device can be calculated quite easily:

$$Power = \frac{Ths - Tamb}{Rth \ hs - amb}$$

R<sub>th hs-amb</sub>≥15K/W T<sub>amb</sub>≈25°C 85°C≥T<sub>hs</sub>≥45°C (typically)

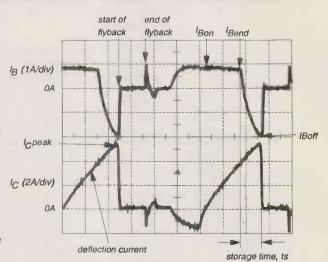


Fig. 6. Characteristics of the horizontal deflection transistor's collector and base-current waveforms after base-current optimisation.

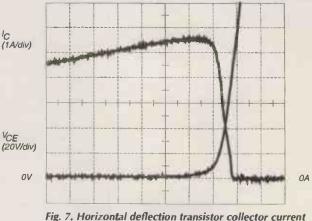


Fig. 7. Horizontal deflection transistor collector current versus collector-emitter voltage during turn off.

#### Fault finding in the deflection drive

Consider a 16kHz tv found to have a failed deflection transistor. Replacing it with an identical type restores full set functionality. If the picture shows some visible distortion then the chances are that there is a fault in the 'load' side of the deflection transistor, ie something causing a change to the  $I_{\rm C}$ .

If, however, everything appears ok there may still be a problem with the drive that does not immediately result in device failure. For 16kHz television, a typical deflection transistor should dissipate less than 2W which means that the device can run in free-air with a 25°C ambient. This can be tried in the workshop. If free-air operation leads to device failure or a visible distortion the drive circuit needs to be re-optimised.

This technique will not, of course, resolve the failure if it was caused by a single overstress event. These failure modes could be the result of lightning induced picture tube flash, or interference from some other source of electromagnetic radiation. This type of failure mode cannot be diagnosed easily.

a visible distortion on the screen or require some additional correction.

During the on-state the device should be operated in the 'saturation' region of the transistor operating area.

**Off-state**. The device must be able to withstand any voltage applied across the collector-emitter terminals when there is no positive drive.

Switching. The transition between on-state and off-state must be achieved quickly and without unnecessary dissipation. This is the most critical feature of operation with regard to the device requirements. Unfortunately, the switching characteristics of power devices are very circuit dependent. An appreciation of the interacting variables is essential if an optimised design is to be produced. The 'Base drive optimisation' section offers an empirical path through the maze of information surrounding bipolar horizontal deflection switching.

#### Using device data

Semiconductor companies usually adopt formats for data which have evolved from in-house rules laid down many years ago. It can be difficult to relate much of the published data to the requirements of the application. But, there are vital pieces of information that can be extracted.

The first parameter to check is peak voltage – the largest voltage value in data. This can be expressed as  $V_{CES}$ ,  $V_{CEX}$ ,

#### Glossary of terms

Deflection transistor parameters

1 <sub>C</sub>	collector current
VCE	collector-emitter voltage
/ <sub>B</sub>	base current
Bend	base current, end of on period
-/Boff	peak reverse base current
$V_{BE}$	base-emitter voltage
hFE	current gain: Ic/IB

Other abbreviations

EHT	extra high tension
HVT	high voltage transistor
LOT	line output transformer
R <sub>th</sub>	thermal resistance

 $V_{\text{CEV}}$ ,  $V_{\text{CER}}$  or  $V_{\text{CBO}}$ . For a solidstate physicist there are interesting differences between these parameters, but for a circuit designer all these can be viewed as the same. Most televisions of 21in and above, have a peak flyback voltage in normal running of 1100-1300V, in which case a 1500V peak voltage device is required.

There are no significant differences in the peak voltage characteristics of devices from different suppliers. This is the simplest data to comprehend.

A lower voltage value,  $V_{\text{CEO}}$ , is also often given in data. The subscript 'O' means the base is open circuit. Because the base is never open circuit in a deflection circuit,  $V_{\text{CEO}}$  is not of prime importance. The second parameter to check is recommended operating current, which may not be too easy to find. Some suppliers give an  $I_{Csat}$  value – ie the  $I_C$  in saturation – in the summary at the top of the data sheet. For other suppliers the value may have to be extracted from another characteristic.

All suppliers quote either  $V_{\text{CEsat}}$   $h_{\text{FEsat}}$  or some switching values for a given  $I_{\text{C}}$ : this can be taken as the  $I_{\text{Csat}}$  value. The  $I_{\text{Csat}}$  value is determined by the chip size and hence has a large influence on the device cost.

There are two possible pitfalls when comparing  $I_{Csat}$  data: the operating frequency and 'specmanship'. A device specified at 4.5A for 64kHz operation in a pc monitor will have a bigger chip than a device specified at 4.5A for 16kHz operation in a tv. Also, some devices are over-specified on  $I_{Csat}$ . If some devices were operated at the  $I_{Csat}$  recommended in data they would have to be bolted to a very large, water-cooled heatsink. This is not practical for tv applications.

The only other relevant specifications are the maximum junction temperature,  $T_{jmax}$ , which is usually 150°C for bipolar deflection transistors, and the thermal resistance values. These specifications are required for base drive optimisation. Initially, at least, all other data is irrelevant.

#### **Base drive design**

Base drive design can only be optimised empirically. Advances in circuit simulation models fall short in this application: the available device (HVT and diode) and component (LOT) models are insufficient. This situation is unlikely to improve much in the next five years. Industry standard bipolar HVT models are not possible as the different construction of a 1500V, 5A, 64kHz device from supplier A will require a different drive from a 1500V, 5A, 64kHz device from supplier B.

The bipolar HVT is a current driven device so base current is the important waveform to analyse. A successful design will have matched this  $I_{\rm B}$  waveform to the load ( $I_{\rm C}$  waveform). The method, with a few 'rules-of-thumb', is outlined in the panel 'Optimising base current'.

For small screen tv, with an optimised drive, the power should be 2W, or less. For the largest tvs the power could be as high as 5W in the extreme load case.

From the power, the device junction temperature,  $T_j$ , can be calculated. Thermal resistance between the junction and the heatsink,  $R_{\text{th }j-\text{hs}}$ , will be between 2K/W for a large, non-isolated device to 5K/W for a small, isolated device. So,

#### $T_j = T_{hs} + (Power \times R_{thj} - hs)$

A good rule-of-thumb is that the  $T_j$  is 10°C higher than the heatsink temperature.

The standard  $T_{j(max)}$  for bipolar deflection transistors is 150°C, however, it is not good practice to use this as the limit in the above experiment. The thermal analysis has to be good for a complete production program so it is usual to inset the desired  $T_{j(max)}$  to a lower value, typically 110°C. This should result in the elimination of any thermal failures during the production run of a tv model and enhanced reliability for the horizontal deflection stage.

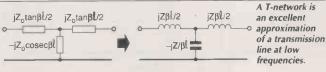
Using a small heatsink compensates for not carrying the tests out at an elevated ambient. In the laboratory, the tv may have the back off and the main pcb may be exposed to freely circulating air. In domestic use the set will be placed usually with its back to the wall in the corner of a room. Heat flow in these two situations is significantly different, so some allowance must be made for this in the laboratory measurements.



#### **Cable shunted**

Although Ben Duncan's analysis of loudspeaker cables is highly interesting, it is evident that a shunt capacitance of 228pF (impedance greater than  $10k\Omega$ ) cannot have any effect on a low impedance load. Indeed, if the amplifier were current driving, the cable modelled would have no effect at all.

A T-network is an excellent approximation of a transmission line at low frequencies (see figure) by linear approximation of the trigonometric functions. The total inductance and capacitance per metre in this case are the same as the intrinsic inductance and capacitance per metre of the transmission line.



The inductance parameter seems to be measured at cut-off to a 5.6 $\Omega$ load, i.e. at about 1MHz. The corresponding capacitance at that frequency must be about 60pF (or else the dielectric constant is as high as 10.2).

If, due to increasing skin depth, the characteristic impedance becomes much smaller at lower frequencies, the inductance must correspondingly decrease so as to

#### Is oxygen to blame?

I read with great interest Anthony Hopwood's account of Prof. Henshaw's ideas on the causes of some cancers and leukemias in humans, in the April issue. I am sure some of these diseases can result from the causes mentioned, but only very few due to direct damage by alpha particles on human tissue.

I have suffered both these dreadful diseases myself, and have worked for 26 years on the first cyclotron in the world to be built in a hospital for medical research. There, alpha particles and deuterons were accelerated up to 15MeV. Even though several of my colleagues died of cancer, I do not believe the alphas caused direct damage to body tissue.

I think the causes of large number of victims of radiation combined with high voltages is best shown by going back to my first employers in 1932. They were two brothers who in the twenties manufactured cold cathode, gas focussed X-ray tubes. They had diversified into making architectural lighting and neon signs. My job was to gas fill these signs.

The brothers, as did many early X-ray pioneers, both died of cancer. Others from Madam Curie onwards died of leukemia. All these people had one thing in common with people living under power lines and getting either cancer or leukemia - they all breathed air that had simultaneously been exposed to a high voltage and some sort of irradiation.

Thus the air all these people were breathing was likely to be ionised, and since oxygen is taken up some thirty times more than any other elemental gas, it seems to me that the oxygen that was breathed had a charge of +15eV instead of the normal oxygen charge of -2eV.

Now because radon has such a large mass it cannot be freely accelerated at normal temperature and pressure. This is because of its short mean free path, and since it is inert it cannot be attracted chemically.

However the tiny electron which is so vital in electron transport system in metabolism will be accelerated and increased greatly in number by the Townsend avalanche effect. In all aerobic organisms those that require  $O_2$  – electrons find their way back to the ultimate electron acceptor, oxygen.

While oxygen may be the breath of life, could ionised oxygen be the death of you?

Leslie C. Baker Dorset

make LC=1/c<sup>2</sup> constant. Am I right? Otherwise there would be dispersion, i.e. lower-frequency

waves propagating slower, but dispersion has to do with the dielectric which is relatively constant at low frequency. I couldn't find any loudspeaker cables hanging around, so I refrained from making the measurements myself. Michael Williams Jerusalem

#### **Delayed reflections**

I was intrigued to read Mr Russell's article on Transmission lines in Electronics World March issue. I designed and manufactured the MDN2484 8µS/8K delay line that you describe, in about 1965. Lexor Electronics of Coventry supplied these things mainly to the English Electric Company, who were Anglicising an RCA Computer and acquiring an interest in the LEO computer set up by J. Lyons. We designed a whole range of delay lines for them. Later the company became English Electric.

The article analyses the basic parameters correctly. However Mr Russel makes no mention of the factor which could possibly foul up the results if not taken into account

Simply stringing together a cascade of Ls & Cs gives you a 'Constant K' line. This has a group delay characteristic from hell. Delays at low frequencies will be much less than those at high frequencies. Therefore when you double or otherwise multiply frequencies, the apparent wavelengths and thus nodal

undershoot

relationships will not be as expected. Lexor delay lines were mainly

designed for time-domain - pulse operation. They were used in computers for equalising the delays through various diverging and converging paths in the computer, and a major third parameter following delay and impedance is overshoot and its opposite, undershoot. These are evinced in response to a pulse input.

Briefly, when undershoot and overshoot are equal, then all frequencies within the pass-band of the delay line (it can be considered as a type of low-pass filter with a Gaussian response) are delayed by the same amount.

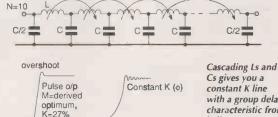
In order to achieve this within the design, you have to provide for magnetic coupling between adjacent sections of the line. Moreover the sign of the coupling should be positive between adjacent section and negative between alternate sections in order to avoid reflections (poor swr) at the highest frequencies.

In the 2484 series, this could not be contrived due to physical constraints, and all couplings were positive. Since the units were employed solely in the time-domain however this was not a problem.

The optimum coupling in a classic m'-derived design requires a 'K' of approximately 27%. This is managed in the 2484 series by winding the coils on ferrite 'cotton-reel' bobbins, and arranging them axially with a closely controlled spacing. Too close results in group delay negative with frequency, and vice-versa.

Values up to  $500ns/560\Omega$  are available in 14 pin, 0.3 in DIL form these days. However, we still supply them all to order. J.C. Pledger

Active Electronics Labs (tel. 01926 484050) Warwickshire



with a group delay characteristic from hell.

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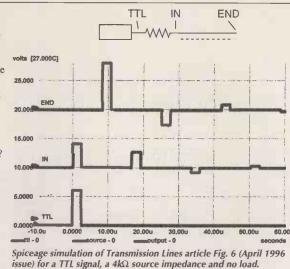
#### LETTERS

#### Ouch!

I would like to make it clear that Bill Russell's April 1996 article on transmission lines has used the ttl devices output for the top trace in Fig. 6. The actual input of the transmission line shows a pulse after 16.8µs. The amplitude of this pulse is 2.6V since a third of the returning 4V initial pulse is inverted and reflected back along the line.

The other nit I would like to pick at is; has Douglas Self actually measured his distortion levels with - to use an objective term - music? Music frequently contains peaks that may exceed five times the rms level. Many low distortion amplifiers use high voltage power supplies to supply these short duration peaks.

For uncompromising audio purists I suggest they bridge two of Self's amplifiers together and suffer a 3dB loss in the wallet! Andrew Pate Surrey



#### No contest

In response to the 'challenge' in Letters in the May issue, Allen Wright appears to have misunderstood the nature of scientific enquiry. In the famous example, the hypothesis 'All swans are white' is disposed of forever by seeing one black swan. It is not necessary to look at more black swans in different ways to confirm the finding.

Faced with the rather less plausible hypothesis 'All copper conductors are composed of 10mV diodes' it is only necessary to show once that this is not true. I think that my experiment reported in the March '96 issue of EW is proof positive that magical 10mV diodes do not and cannot exist in solid copper. Further evidence is given by my JAES paper 'Granularity Distortion' which probed the matter down to the -150dBu level<sup>1</sup>.

As far as I can gather, Mr. Wright's own hypothesis seems to be 'Thinner speaker cables sound different, and I think they sound better, so this must be because there are fewer magic diodes, as there is less total weight of copper.' Mr. Wright assumes - apparently for no other reason than because he wants to - that any change in subjective quality must be due to magic diodes, and that the highly unscientific procedure he outlines will 'prove' it. It is, I hope, unnecessary to point out the gaping holes in the logic here.

If an audible thin-cable effect exists, then I suggest the reason is as follows: single-strand cable will have a much higher resistance than normal speaker cables. The extra resistance means that the speaker impedance curve will be partially superimposed on the basic speaker/room frequency response. These extra response irregularities which will not have been anticipated by the speaker designer, who will have assumed that his brain-children are to be driven by a low-Z source may or may not make the overall

sound better according to unguessable subjective criteria. It may well be that a listener could convince himself that the result is greater clarity and lesser distortion; but he has no right to then state that the difference is due to mysterious effects when a very obvious explanation is right under his nose. Bring forth Occam's Razor.

Mr. Wright makes no mention of double-blind A/B testing in connection with his assertions, so I assume they were conceived under informal listening conditions. I

therefore decline to accept his statements about enhanced clarity and reduced distortion.

While I can only judge by the title, I can well believe that any book entitled 'SuperCable Cookbook' would upset a lot of people, especially those who feel that technical books should preferably contain facts.

1. 'Ultra-low noise amplifiers and granularity distortion' JAES Nov 1987, pp 907-915. **Douglas Self** Idmiston, Herts

#### Caller who?

I would like to raise a few points related to Segaran's Caller ID article in the April issue. Enhancement of the service to deliver the caller's name is on trial, I believe with 400 users in Edinburgh, and with good results. Users can specify information sent in the name field; apparently most prefer to send first names only.

In my experience, the 'number unavailable' message relates not to phones on older exchanges but to those on catv networks, confirmed by asking the caller. This seems to imply that while catv networks support their own caller ID system they are incapable of transmitting Caller ID to BT's network. This is pathetic.

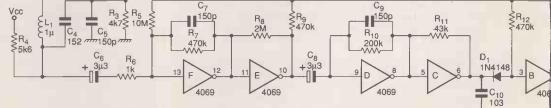
Mobile phones usually register as unavailable - but not always. Calls from ex-directory lines are not delivered as 'number withheld' by default; this must be specifically requested. Most of my 'number withheld' calls are from businesses whose numbers are advertised in the national press; this baffles and infuriates me.

Nor is Caller ID a particularly useful complement to an answering machine. I originally subscribed to the service to screen out bogus calls. I now find I cannot do this for fear of missing out on employment

One area where Caller ID would be useful is in deciding whether or not to answer a second call being



If you have any electronics-related questions that you have been unable to find an answer to, why not see if other readers can answer them? Simply write to me, the editor, at the address on page 267, fax 0181 652 8956, or e-mail martin.eccles@rbp.co.uk.



I would be grateful for your assistance. In the diagrams is a small transmitter and receiver which include encoding and decoding facilities.

Receiver: When the receiver is switched on, once a signal is received, the signal is processed by the components to the left of the solid black vertical line. The output of this processing is the same code sent by the transmitter which enters pin 14 of IC3 This chip has also been set to the same code as the transmitter. When the correct matching code is received pin 17 goes high to turn on the chime

section of the circuit. The section to the right of the solid line is fully understood.

Question 4: How is the signal processed by the receiver in order for the 4069 hex-inverter to work since the frequency of around 340MHz is too high a frequency for the chip to operate? Question 5: Could it be that the inverters are working as filters? If so how?

Transmitter: The main integrated circuit provides a number of combinations which can be sent by connecting pins 1 to 9 to ground. When power is

offered by Call Waiting. However, the number of such a call is not transmitted. From the data in Mr Segaran's article it appears that such an enhancement to the service is probably not possible; in any case BT has informed me that they do not intend to try.

This is a great shame. What is the 'metering and message waiting status' information that BT would like to transmit without alerting the phone user? I have asked BT to explain the 'message waiting' flag on the display of my *CD50* but they cannot be bothered to answer.

I note that the software provided with the *CID-PC1* is for Windows only. For the benefit of pc owners who, like me, have thrown away their copy of Windows, I would like to have DOS tsr software.

I apologise if this letter sounds negative. I have great enthusiasm for the concept of Caller ID and I am saddened by the reality. **Chris Bulman** Bedford

#### **Recalling the facts**

The letter from Chris Bulman certainly had a negative spin on Caller ID as a useful service. Although some of the points he makes are relevant, others are factually incorrect.

The 'number unavailable' message is mostly from older

form is the signal transmitted?

exchanges, although calls from subscribers on the catv network will also be delivered as 'unavailable'. However, when the interface between BT and the catv network is upgraded, this information should be available. Regarding mobile telephones, subscribers to the 'Orange' network both receive and transmit caller ID information. Certainly, if other network operators want to offer a competitive service, they too will have to offer this.

Chris is correct in that for 'number withheld' to be set permanently on a line or group of lines, a special request has to be made to BT. As for companies requesting suppression of their number, this is mainly for administrative convenience Companies that operate DDI (direct dial in) exchanges, have individual numbers for each staff member, but the number delivered is that of the main 'switchboard'. If calls are returned to this number, and not to the individual, then the switchboard will be swamped. I assume that other companies withhold their numbers for other reasons. In practice, this problem is not as extensive as Chris suggests. In our experience, about 70% of all calls to our office have number attached, the remaining being split into number withheld, number unavailable. international and payphone calls. In the area of Call Waiting, BT is

### Coaxial cable tester

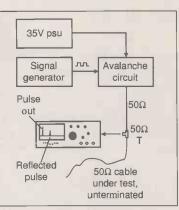
Design brief in the March 1996 issue discussed working with avalanche transistors and Nick Wheeler's article covered coaxial cable testing. I have combined elements of the two, constructing within a few minutes this avalanche pulse generator for testing and experimenting with coaxial cables. **PW Fry G4SBF** Southampton

well advanced in trials of such a system and should be introducing it within a matter of months. Its protocol has been defined for some time, and is already operational in some states in the US. Supplier's Information Note 242, as referred to in my article, gives technical details.

Introduction of name on a national basis is much more of a problem. Maintenance of a national database of names – 20 million plus – and the 'instantaneous' look-up of this for every call, presents a big technical and administrative problem that BT seems to be shying away from.

By the way, existing customers can obtain details on the protocol for exchanging Caller-ID data via the serial port. Seggy Segaran

**Seggy Segara** York

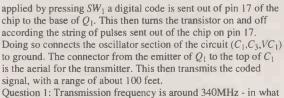


#### Do you have a vtr?

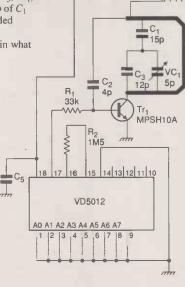
David Markie has designed a comprehensive remote control interface with pc-based control software for vtrs. It uses the industry standard, or 'Sony', protocol. Write to the editorial offices (Quadrant House address) for more details.

#### Non-slewing audio power In this article, from the March issue, the CSA amplifier of Fig. 1 there is a $200\Omega$ resistor between the $50\Omega$ resistor pair junctions. There should be no connection

between the junctions. Also, in Fig. 4, the resistor between the diode-junction pairs is  $3.3k\Omega$  and the emitter resistors for  $Tr_{18, 21}$  are  $62\Omega$ . Apologies for these.

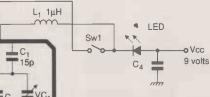


C<sub>11</sub> 103 Tr<sub>2</sub> ( C2926 Speaker A562 R<sub>13</sub> ≤ 43k ≤ R<sub>14</sub> 560k Ş IC<sub>3</sub> VD5013 IC<sub>2</sub> VD5011 A0 A1 A2 A3 A4 A5 A6 A7 14 5 6 2 3 18 Out ş R<sub>16</sub> 470k ≩R<sub>17</sub> ₽ С<sub>12</sub> 3µ3 470k 3µ3 m



Question 2: Can the value of transmitter frequency be derived from the component values and if so how? Question 3: Is the above statement correct?

The circuit is sold by Rapid Electronics in kit form, but the company cannot help. Grahame Collins Reading College



#### **Schumann Resonance**

I wonder if any of your readers could help me with information on Schumann Resonances – particularly in relation to the instrumentation required to detect it – including antenna. The topic is mentioned in EW, Research Notes, May 1993.

#### Ted Crowley

Invotron

Co. Wicklow Ireland

Would Mr Callegari, who wanted to contact people measuring Schumann Resonances, please let us have his address? – Ed

#### **Headphone bass**

Why do small 'personal' earphones give such a good bass response? I do not think they are infinite baffle designs, so why is the low frequency cut-off not higher than it apparently seems to be? **David Gibson** Leeds



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# Thermal dynamics in audio power

Class B amplifier requires thermal compensation to avoid thermal runaway, and because bias setting is critical for the minimisation of crossover distortion, which is generally regarded as the most pernicious of non-linearities. The biasing of a Class B output stage requires the establishment of an accurate voltage drop  $V_q$  across emitter resistors  $R_e$  of tiny value, by means of hot transistors with varying  $V_{be}$  drops. It's surprising it works as well as it does.

This thermal compensation has two main problems, attenuation and delay. Since the thermal sensor is more or less remote from the junction whose gyrations in temperature will hopefully be cancelled out, heat losses and thermal resistances cause the temperature change reaching the sensor to be generally too little and too late for complete compensation.

As in Part 1, all the voltages and errors here are for one half of an output stage, using symmetry to reduce the work involved. These 'half amplifiers' are used throughout this piece for consistency, and the error voltages only doubled to represent reality (a complete output stage) when they are compared against the tolerance bands previously quoted.

In this study, we are faced with errors that vary not only in magnitude, but also in their persistence over time; judgement is required as to whether a prolonged small error is better than a large error which quickly fades away.

#### The absolute error criterion

The same issue faces most servomechanisms, and I borrow from Control Theory the concept of an 'Error Criterion' which combines magnitude and time into one number<sup>1,2</sup>. The most popular criterion is the Integrated Absolute Error (IAE), which is computed by integrating the absolute value of the error over a specified period after giving the system a suitably provocative stimulus; the absolute value prevents positive and negative errors cancelling over time. Another common criterion is the Integrated Square Error (ISE) which solves the polarity problem by squaring the error before integration - this also penalises large errors much more than small ones. It is not immediately obvious which of these is most applicable to bias control and the psychoacoustics of crossover distortion that changes with time, so I have chosen the popular IAE.

One difficulty is that the IAE error criterion for bias



In Part 2 of his analysis of thermal dynamics in high performance power amplifiers, **Douglas Self** discusses the importance of temperature sensor location.

voltage tends to accumulate over time, due to the integration process, so any constant bias error quickly comes to dominate the IAE result. In this case, the IAE is little more than a counter intuitive way of stating the constant error, and must be quoted over a specified integration time to mean anything at all. This is why the IAE concept was not introduced in the first part of this article.

Much more useful results are obtained when the IAE is applied to a situation where the error decays to a very small value after the initial transient, and stays there. This

#### **AUDIO**

can sometimes be arranged in amplifiers, as I hope to show. In an ideal system where the error decayed to zero without overshoot, the IAE would asymptote to a constant value after the initial transient. In real life, residual errors make the IAE vary slightly with time, so for consistency all the IAE values given here are for 30s after the step input.

#### The emitter-follower stage

In the first part of this article, it was shown that the basic emitter-follower (ef) stage with the sensor on the main heatsink has significant thermal attenuation error and therefore under compensates temperature changes. The  $V_{\rm q}$  error is +44mV, the positive sign showing it is too high. If the sensor is on the TO3 can top it over compensates instead,  $V_q$  error equals -30mV.

If an intermediate configuration is contrived by putting a layer of controlled thermal resistance 80°C/W, between the TO3 top and the sensor, then the 50s timescale component of the error can be reduced to near zero. This is the top error trace in bottom half of **Fig. 1**. The lower trace shows the wholly misleading result if sensor heat losses are neglected in this configuration.

Despite this medium term accuracy, if the heat input stimulus remains constant over the

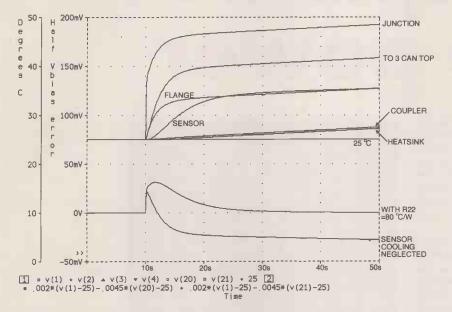


Fig. 1. EF behaviour with semi-insulating pad under sensor on TO3 can top. The sensor in the upper temperature plot rises more slowly than the flange, but much faster than the main heatsink or coupler. In lower Vq-error section, upper trace is for a 80°C/W thermal resistance under the sensor, giving near zero error. Bottom trace shows serious effect of ignoring sensor cooling in TO3-top version.

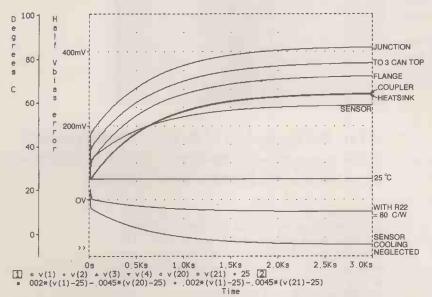


Fig. 2. Over a long timescale, the lower plot shows that the Vq error, although almost zero in Fig. 1, slowly drifts into over compensation as the heatsink temperature (upper plot) reaches asymptote.

very long term (several kilo-seconds) there still remains a very slow drift towards over compensation due to the slow heating of the main heatsink, **Fig. 2**. This extra complication over very long periods was glossed over in Part 1 due to sheer lack of space.

This long term drift is a result of the large thermal inertia of the main heatsink and since it takes 1500s (25 minutes) to go from zero to -32mV is of doubtful relevance to the timescales of music and signal level changes. On doubling to -64mV, it remains within the ef V<sub>q</sub> tolerance of ±100mV. On the shorter 50s timescale, the half amplifier error remains within a ±1mV window from 5s to 60s after the step input.

For the ef stage, a very long term drift component will always exist so long as the output device junction temperature is kept down by means of a main heatsink that is essentially a weighty chunk of finned metal.

The ef system stimulus is a 20W step as before, being roughly worst case for a 100W amplifier. Using the 80°C/W thermal semiinsulator described above gives the upper error trace in Fig. 3, and an IAE of 254mV/s after 30s. This is relatively large because of the extra time delay caused by the combination of an increased  $R_{22}$  with the unchanged sensor thermal capacity  $C_6$ . Once more, this figure is for a half amplifier, as are all IAEs in this article.

Up to now I have assumed that the temperature coefficient of a  $V_{be}$ -multiplier bias generator is rigidly fixed at  $-2mV/^{\circ}C$  times the  $V_{be}$ -multiplication factor, which is about 4.5× for ef and 2× for cfp. The above figures are for both halves of the output stage, so the half amplifier value for ef is -4.5mV/°C, and for cfp  $-2mV/^{\circ}C$ .

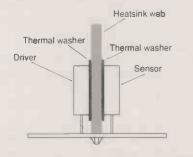
#### Speeding the response

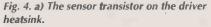
Staying with ef, if we boldly assume that the V<sub>bias</sub> generator can have its thermal coefficient varied at will, the insulator and its aggravated time lag can be eliminated. If the 80°C/W thermal pad is replaced with standard material, between the sensor and the TO3 top, the optimal V<sub>bias</sub> coefficient for minimum error over the first 40s proves to be -2.8mV/°C, which is notably less than -4.5. The resulting 30s IAE is 102mV/s, more than a two times improvement. See the lower trace in Fig. 3, for comparison with the semi-insulator method described above. In view of the fixed time constants, dependant upon a certain weight of metal being required for heat dissipation, it appears that the only way this performance could be significantly improved upon might be to introduce a new kind of output transistor with an integral diode that would sense the actual junction temperature, being built into the main transistor junction structure. Although it would be of immense help to amplifier makers, no one seems to be keen to do this.

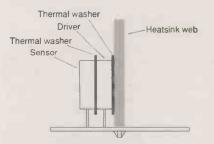
From here on I am going to assume that a variable temperature coefficient (tempco) bias generator can be made when required. The details of how to do it must wait for a later article. It should be an extremely useful device, as thermal attenuation can then be countered by increasing the 'thermal gain'. It does not however help with the problem of thermal delay.

In the second ef example above the desired tempco is  $-2.8 \text{mV}/^{\circ}\text{C}$ , while an ef output stage plus  $V_{be}$ -multiplier has an actual tempco of  $-4.5 \text{mV}/^{\circ}\text{C}$ . In this case we need a bias generator that has a *smaller* tempco than the standard circuit. The conventional ef with its temp sensor on the relatively cool main heatsink would require a *larger* tempco than standard.

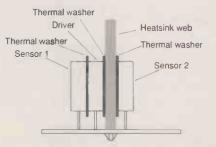
A potential complication is that amplifiers should also be reasonably immune to changes in ambient temperature, quite apart from changes due to dissipation in the power devices. The standard tempco gives a close approach to this automatically, as the  $V_{be}$ -multiplication factor is naturally almost the same as the number of junctions being biased. However, this will no longer be true if the tempco is significantly different from standard, so it is necessary to think about a bias generator that has one tempco for power device temperature changes and another for ambient changes. This sounds rather daunting but actually proved fairly simple.







b) An improved version, with the sensor mounted on top of the driver itself, is more accurate.



c) Using two sensors to construct a junction estimator.

**Complementary feedback-pair output** As revealed in Part 1, the complementary feedback pair (cfp) output stage has a much smaller bias tolerance of  $\pm 10$ mV for a whole amplifier, and surprisingly long time constants. A standard cfp stage therefore has larger relative errors than the conventional emitter follower (ef) stage with thermal sensor on the main heatsink. This is the opposite of conventional wisdom. Moving the sensor to the top of the TO3 can was shown to improve the ef performance markedly, so we shall attempt an analogous improvement with driver compensation. The standard cfp thermal compensation arrangements have the sensor mounted on the driver heatsink, so that it senses the heatsink temperature rather than that of the driver itself. See Fig. 4a for mechanical arrangement, and Fig. 5 for thermal model. As in the ef, this gives a constant long term error due to the sustained temperature difference between the driver junction and heatsink mass. See the upper traces in Fig. 7, plotted for different bias tempcos. The cfp stimulus is a 0.5W step, as before. This constant error cannot be properly dealt with by choosing a tempco that gives a bias error passing through zero in the first fifty

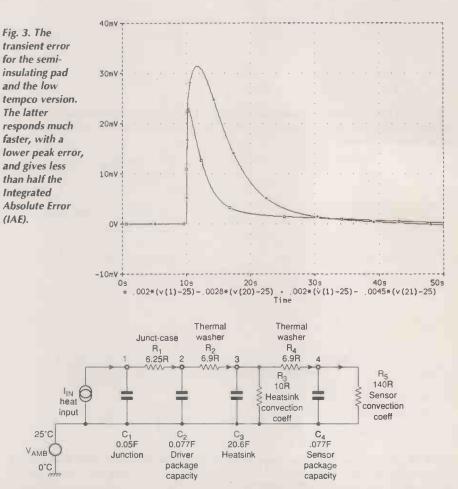
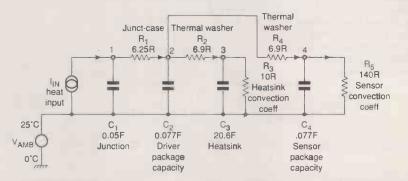
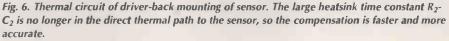


Fig. 5. Thermal circuit of normal CFP sensor mounting on heatsink.  $R_3$  is the convective cooling of the heatsink, while  $R_5$  models heat losses from the sensor body itself.





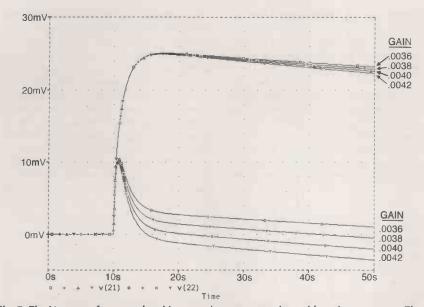
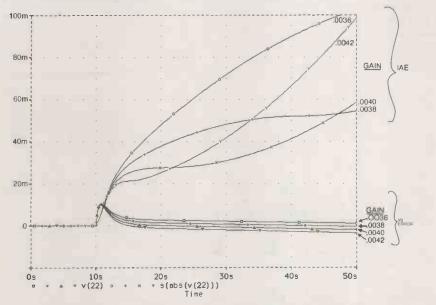
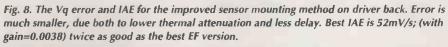
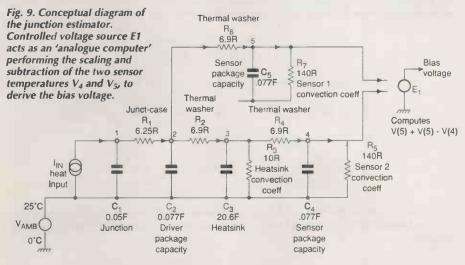


Fig. 7. The Vq errors for normal and improved sensor mounting, with various tempcos. The improved method can have its tempco adjusted to give near zero error over this timescale. Not so for the usual method.







seconds, as was done for the ef case with a TO3-top sensor, as the heatsink thermal inertia causes it to pass through zero very quickly and head rapidly South in the direction of ever increasing negative error. This is because it has allowed for thermal attenuation but has not decreased thermal delay. It is therefore pointless to compute an IAE for this configuration.

#### A better sensor position

By analogy with the TO3 and TO3P transistor packages examined earlier, it will be found that flat driver packages such as TO-225AA on a heatsink get hotter faster on their exposed plastic face than any other accessible point. It looks as if a faster response will result from putting the sensor on top of the driver rather than on the other side of the sink as usual. With the Redpoint SW38-1 heatsink this is fairly easy as the spring clips used to secure one plastic package will hold a stack of two TO-225AA's with only a little physical persuasion. A standard thermal pad is used between the top of the driver and the metal face of the sensor, giving the sandwich shown in Fig. 4b. The thermal model is Fig. 6. This scheme greatly reduces both thermal attenuation and thermal delay, (lower traces in Fig. 7) giving an error that falls within a ±1mV window after about 15.5s, when the tempco is set to -3.8mV/°C. The IAE computes to 52mV, as shown in Fig. 8, which demonstrates how the IAE criterion tends to grow without limit unless the error subsides to zero. This value is a distinct improvement on the 112mV IAE which is the best that could be got from the ef output.

The effective delay is much less because the long heatsink time constant is now partly decoupled from the bias compensation system.

#### A junction estimator

It appears that we have reached the limit in what can be done, as it is hard to get one transistor closer to another than they are in Fig. 4b. It is however possible to get better performance, not by moving the sensor position, but by using more of the available information to make a better estimate of the true driver junction temperature. Such 'estimator' subsystems are widely used in servo control systems where some vital variable is inaccessible, or only knowable after such a time delay as to render the data useless<sup>3</sup>. It is often almost as good to have a 'model system', usually just an abstract set of gains and time constants, which will give an estimate of what the current value of the unknown variable must be, or ought to be

The situation here is similar, and the first approach makes a better guess at the junction temperature V(1) by using the known temperature drop between the package and the heatsink. The inherent assumption is made that the driver package is isothermal, as it is modelled by one temperature value V(2).

If two sensors are used, one placed on the heatsink as usual and the other on top of the driver package, as described above Fig. 4c,

then things get interesting. Looking at Fig. 6, it can be seen that the difference between the driver junction temperature and the heatsink is due to  $R_1$  and  $R_2$ . The value of  $R_1$  is known, but not the heat flow through it. Neglecting small incidental losses, the temperature drop through  $R_1$  is proportional to the drop through  $R_2$ . Since  $C_2$  is much smaller than  $C_3$ , this should remain reasonably true even if there are large thermal transients. Thus, measuring the difference between V(2) and V(3) gives a reasonable estimate of the difference between V(1) and V(2). When this difference is added to the known V(2), we get a rather good estimation of the inaccessible V(1). This system is shown conceptually in Fig. 9, which gives only the basic method of operation. The details of the real circuitry must wait until we have decided exactly what we want it to do.

We can only measure V(2) and V(3) by applying thermal sensors to them, as in Fig. 4c, so we actually have as data the sensor temperatures V(4) and V(5). These are converted to bias voltage, scaled and subtracted, thus estimating the temperature drop across  $R_1$  this is added to V(5) to give the estimate of V(1). The computation is done by Voltage-Controlled-Voltage-Source E1, which in PSpice can have any equation assigned to define its behaviour. Such definable VCVS's are very handy as little 'analogue computers' that do calculations as part of the simulation model. The V(1) result is then multiplied by a scaling factor called estgain which is incor-

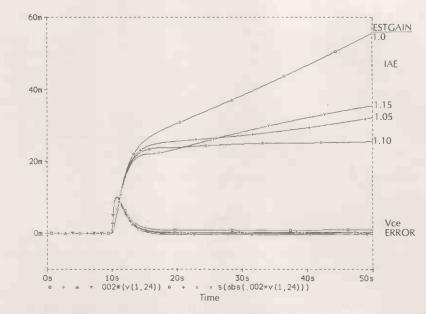
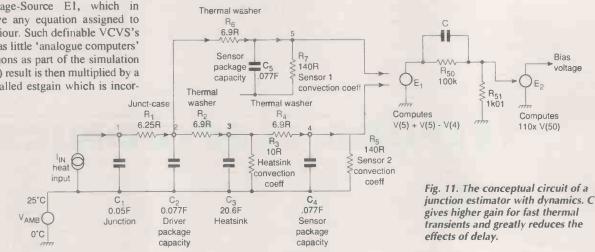


Fig. 10. Simulation results for the junction estimator, for various values of estgain. The optimal IAE is halved to 25mV/s; compare with Fig. 8.

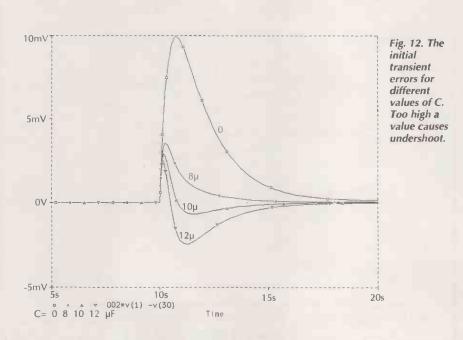


porated into the defining equation for E1, and is adjusted to give the minimum error. Note the variable tempco bias approach is used to allow for the difference in resistance between  $R_1$  and  $R_2$ .

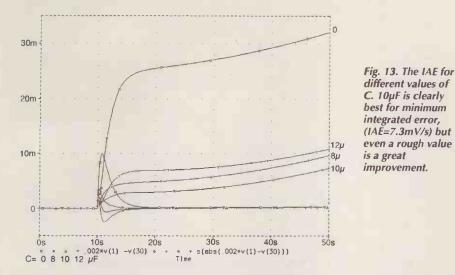
The results are shown in Fig. 10, where an estgain of 1.10 gives the minimum IAE of 25mV/s. The transient error falls within a  $\pm 1mV$  window after about 5s. This is a major improvement, at what promises to be little cost.

A junction estimator with dynamics The remaining problem with the junction estimator scheme is still its relatively slow initial response. Nothing can happen before heat flows through  $R_6$  into  $C_5$ , in Fig. 9. It will take even longer for  $C_4$  to respond, due to the inertia of  $C_3$ , so we must find a way to speed up the dynamics of the junction estimator.

The first obvious possibility is the addition of phase advance to the forward bias com-



AUDIO



pensation path. This effectively gives a high gain initially, to get things moving, which decays back over a carefully set time to the original gain value that gave near zero error over the 50s timescale. The conceptual circuit in Fig. 11 shows the phase advance 'circuitry' added to the compensation path. The signal is attenuated 100 times by  $R_{50}$  and  $R_{51}$ , and then scaled back up by VCVS E2, which is defined to give a gain of 110 times, incorporating an estgain of 1.10 times. C causes fast changes to bypass the attenuation, and its value in conjunction with  $R_{50}$  and  $R_{51}$  sets the degree of phase advance or lead. The slow behaviour of the circuit is thus unchanged, but transients

pass through C and are greatly amplified by comparison with steady state signals.

The result on the initial error transient of varying C around its optimal value can be seen in the expanded view of Fig. 12. The initial rise in  $V_q$  error is pulled down to less than a third of its value if C is made  $10\mu$ F. With a lower C value the initial peak is still larger than it need be, while a higher value introduces some serious undershoot that causes the IAE to rise again, as seen in the upper traces in Fig. 13. The big difference between no phase advance, and a situation where it is even approximately correct, is very clear.

With C set to 10µF, the transient error falls

within a  $\pm 1$ mV window after only 0.6s, which is more than twenty times faster than the first improved cfp version, (sensor put on driver) and gives a nicely reduced IAE of 7.3mV/s at 50s. The real life circuitry to do this has not been designed in detail, but presents no obvious difficulties. The result should be the most accurately bias compensated Class B amplifier ever conceived.

#### In summary

It is, I hope, clear that most of this work is purely theoretical and would be much the better for confirmation by practical tests. This would be a mountain of work and I have no intention of undertaking it.

Hopefully it is equally clear that it is no longer necessary to accept ' $V_{be}$ -multiplier on the heatsink' as the only option for the crucial task of  $V_{bias}$  compensation. The alternatives presented promise greatly superior compensation accuracy.

The third part of this series will deal with variable tempco bias generators.

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**TELFORD ELECTRONICS** 

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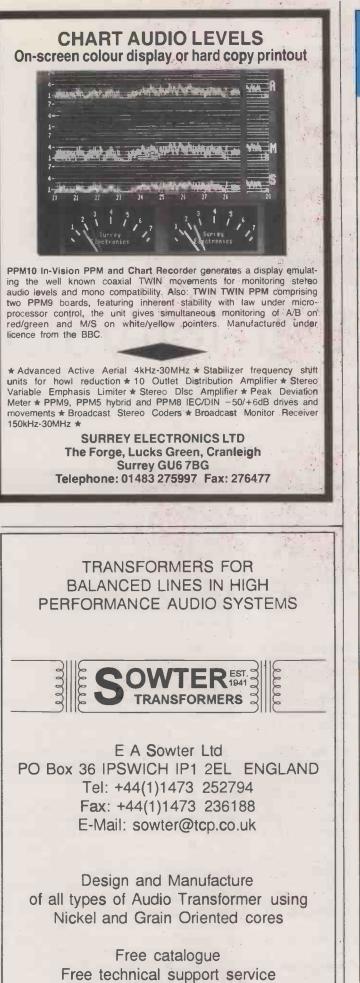
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## Designing for spectrum analysis

## Felice Labbrozzi outlines modules of his high-performance, yet economical, spectrum analyser.

typical spectrum analyser, one not based on fast Fourier transforms, is essentially a superheterodyne receiver. Within this receiver the local oscillator, a vco, is swept using a sawtooth signal. The oscillator starting frequency equals the intermediate frequency.

With this technique, the received frequency theoretically starts from zero, or dc. In practice, the lower limit is affected by the IF filter response and the input dynamic range. The higher frequency is related to the first IF value.

#### **Design criteria**

In order to develop a useful set of specifications for the spectrum analyser, I examined ten commercial spectrum analysers. The specifications I chose are shown in the panel.

Measurements displayed on a spectrum analyser's vertical axis usually need to be logarithmic. As a result, the input voltage is passed through a logarithmic amplifier.

As with any heterodyne receiver the ability to select the signals received is determined by the intermediate-frequency filter. When tuning rapidly to different signals with a bandwidth near to or lower than the band of the detected signals, there are no simple effects. This is because the time needed by a signal to pass through a filter is inversely proportional to its bandwidth.

As a result, to analyse signals with different characteristics, it is necessary to change three parameters. These are,

- bandwidth selectivity of the intermediatefrequency filters
- span the frequency range of the measurement in question
- sweep time the time needed to analyse the same frequency range.

#### Spectrum analyser design goals

- Frequency range dc to 1GHz
- Dynamic display of more than 80dB with linearity of around ±1dB
- Input amplitude range +30, -120dBm minimum
- Frequency accuracy dependent on only one reference oscillator
- Resolution lower than 1kHz
- Ability to print reports, graphs and comparisons
- Capability for storing measurements on dos disks

#### Analyser system elements

To accommodate a range of signals from very large to those close to the thermal noise level,

a very sensitive front end circuit is needed, preceded by an attenuator. This attenuator must have precise and repeatable characteristics over the whole frequency and amplitude range of the instrument. For this reason I have made it a separate module, Fig. 1.

Input frequencies over a gigahertz could be converted by harmonics from the vco. Displaying all the vco harmonic responses at the same time is likely to cause confusion. In order to separate the spurious responses from the required signals it is better to use a low-pass input filter. This will attenuate those signals higher than 1GHz. If it is necessary to extend the input frequency band, the low pass filter can be replaced by band pass preselectors of 1GHz each. The rf attenuator and the first mixer should be adequate enough to cope with this frequency range if the required amplitude response is to be achieved.

All rf circuits are mounted on one pcb and all control lines are dc. When this module receives input

#### **RF ENGINEERING**

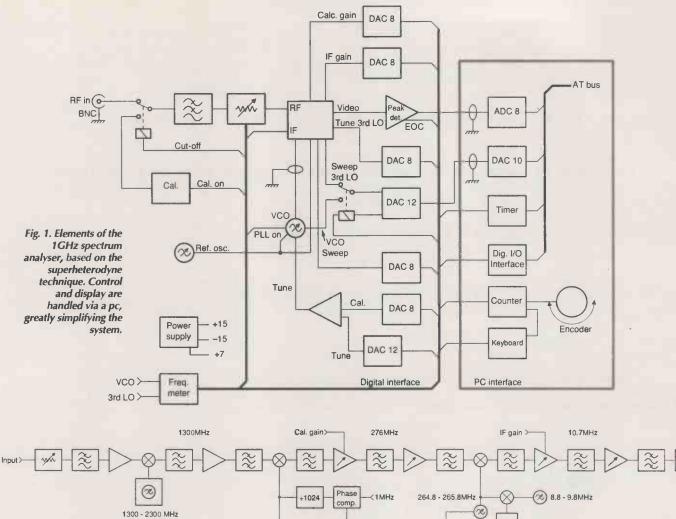


Fig. 2. RF-IF module block diagram. Three intermediate frequencies bring the signal down to 10.7MHz.

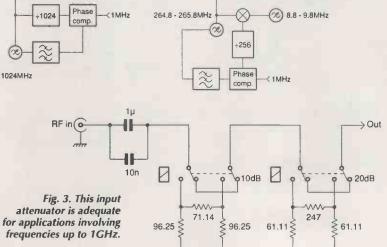
signals together with those from the vco, it sends the resulting signal to the digital interface and then to the pc interface. This signal is converted to digital form for display and/or computation.

#### RF and intermediate-frequency

Measurement receiver Figure 2 uses three frequency conversions to bring the input signal to 10.7MHz. This frequency is processed by quartz filters with variable band width and then applied to a logarithmic amplifier such as a TDA1576. After the filters, a low cost logarithmic amplifier such as TDA1576 works well.

When two signals are mixed, the product of the mixed signal has all the characteristics of the original signal, together with those of the local oscillator. To avoid additional noise as each local oscillator increases the original signal, all local oscillators are controlled via phase lock loops. In this way, the local oscillators can be locked to just one stable and low noise oscillator reference derived from the internal frequency reference.

An exception to this is the third local oscillator, which can be continuously tuned over IMHz when the first vco is phase locked.



Here, phase noise near the carrier remains low enough to be ignored.

The vco has to be tuneable over a very large band – typically 1.3 to 2.3GHz. Because of this, the stability and noise performance required to detect signals hundreds of hertz apart cannot be guaranteed.

All rf amplifiers operating under 1GHz are dual-gates mosfets – BF 961s, or 40673s for 10.7MHz. These are straightforwardly configured, with gain being controlled via the second gate. The input amplifier and 1.3GHz amplifier comprise inexpensive minicircuits MAR 6s and BFR91s.

System gain is software controlled. Software

also compensates for small ripples due to components or their coupling. This makes selection of the first mixer less critical and cheaper.

An auto calibration routine imposes a flat response to the whole system when a signal derived from a harmonic generator is connected to the input.

#### **RF** attenuation

If you are not interested in extending the frequency range over 1GHz, you can make the rf attenuator following Fig. 3.

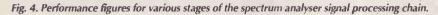
To form a 40dB attenuator, it is better to connect two 20dB sections together. If we use

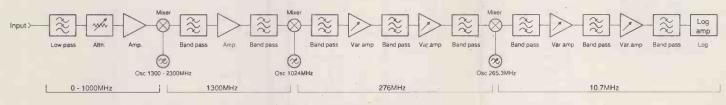
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#### **RF ENGINEERING**

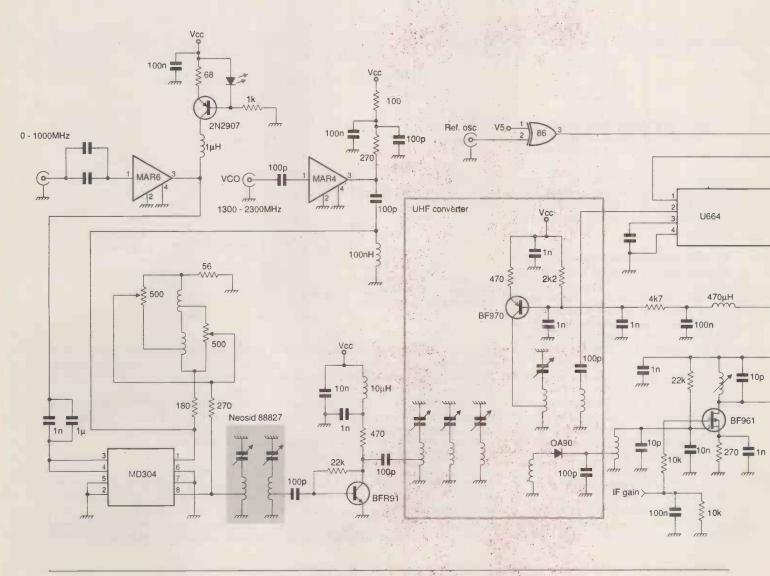
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Min. noise	LP 0,5	Att. - 0,5	Amp 16	Mix 1 -7	<b>BP</b> -2	Amp 15	-3	Mix 2	-1	Amp 17	-4	Vara 17	imp	<b>BP</b>	Mix 3	-1	Var amp. 19	<b>BP</b> 6	<b>Amp</b> 16	-3		
Typ. gain	-0,5	-40,5	-	-7	-2	15	-3	-7	-1	17	-4	17		-1	-7	-1	9	-6	16	-3		
Max. gain	-0,5	-70,5	16	-7	-2	15	3	-7	-1	7	-4	17		-1	-7	-1	19	-6	16	-3		
dBm levels	LP	Att.	Amp	Mix 1	BP	Amp	вр	Mix 2	BP	Amp	вр	Var.	Amp	BP	Mix 3	вр	Var. amp	вР	Amp	вр	Log amp	
Max.sens.	-50	-50,5		35		-44	-29	-32	-39			-27		-10			-19	0	-6	10	7	
Тур.	0	-0,5	-41	-25		-34	-19	-22				-17		0	-1	-8	-9	0	-6	10	7	
Max. level	30	29,5	-41	-25	32	-34	-19	-22	-29	-30	-23	-27		-10	-11	-18	-19	0	6	10	7	





F=F1+(F1-2)/G1+(F3-1)/G1G2=2.91 (see text), and NF=10logF=4.65dB

Fig. 5. Front end synthesis. Theoretically, given a noise figure, NF, of 4.65, a signal just 3dB above noise can be detected.



only one pi network attenuator, stray capacitances limit the frequency response to under 1GHz. Selecting or parallelling standard carbon resistors a 70dB attenuator can be made, increasing the dynamic range of the system. It is necessary to repeat the 20dB section three times using low capacitance reed relays. Excitation coils of the two dual-ganged relays are connected together, as shown.

You must cut the connections as short as possible. The best method is to compute a  $50\Omega$  strip line, and insert the relays in the middle of it cutting the strip between the relay's pins. Relays should have an appropriate pinout; I used *FEME ZFH 002 12* types.

Input capacitors are unpolarised tantalum and ceramic types. If you cannot use surfacemount components, cut the resistor wires down to an absolute minimum and solder the remaining tag directly onto the relay pins.

To compensate for stray capacitances, two short teflon insulating wires can be connected in parallel with the series resistors. Winding the wires together acts as a small capacitor, helping to maintain a flat frequency response.

The following circuit descriptions are not unique solutions. I have tried several different types of circuit, each with good results. However, if you decide to change the schematics, ensure that the local oscillator rf power is higher than +7dBm. This guarantees acceptable values, imposed in the system design, for losses in the balanced mixers. If the oscillators have a high harmonic content, it is better not to increase the rf power more than 3dB otherwise you could have difficulties reducing spurious responses.

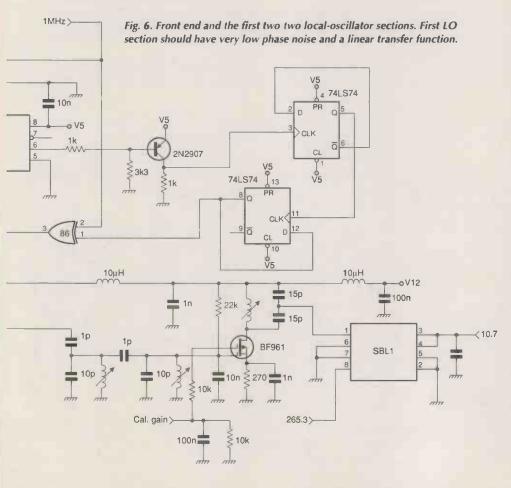
The second conversion, 1300 to 276MHz, was made in a separate silvered-brass box measuring 10 by 50 by 85mm. Inside this box I made resonant coupled circuits using small 6mm brass tubes, teflon standard insulators, small plastic tubes and 3M bolts.

The second mixer uses an OA90 or AA119 germanium diode but I also tested HP5082 series schottky diodes with good dynamic range results.

#### **Designing the rf system**

After selecting the conversion frequencies so that the harmonics or mixing products do not block the intermediate-frequency or generate strong spurious frequencies, it is possible to design the amplifier and establish the noise figure of the receiver system.

From the local oscillator and intermediate



frequencies you can compute the intermediate -frequency filters so that the attenuation of the images frequencies and the 6/60dB frequency band ratio reaches the desired level. Divide insertion losses so that no filter exceeds 10dB. With a spread sheet such as *Excel* you can assign the gain needed for each amplifier so that you arrive at the input level needed for the log amplifier input, Fig. 4.

You can consider the noise figure of a passive mixer as being roughly the same value as its loss. The passive stages can be grouped together in series, making it possible to draw an equivalent block diagram.

Remember that the noise figure of a circuit with a loss of A decibels, connected to the input of an amplifier with noise figure NF decibels, is A+NF decibels. A cascade of two amplifiers with  $N_1$ ,  $G_1$  and  $N_2$ ,  $G_2$  will show looking from the input,

$$F = F_1 + (F_2 - 1)/G_1$$

or in decibels, a noise figure,

NF=10×logF.

Now you can draw an equivalent block diagram with three or four stages in cascade. Within this diagram, you can integrate the losses before each amplifier.

To find the system's noise figure, apply the formula to these equivalent amplifiers for two cascade modules, starting from the last amplifier. Make sure that formulas consider decimals, ie do not mix it with decibels.

The lowest detectable signal depends on the noise present, which is proportional to the band width of the testing system. The minimum noise that cannot be cut, with a bandwidth B of 1kHz, has a power,

$$N = 10\log\frac{KTB}{10^{-3}} = -144$$
dBm

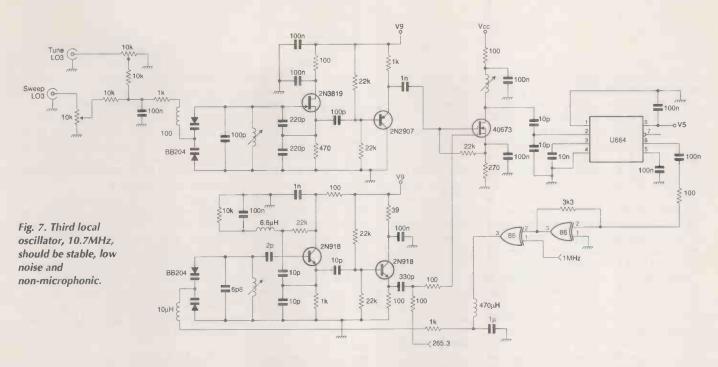
where K is the Boltzmann's constant,  $1.38 \times 10^{-23}$ , and T = 293 K, is room temperature.

Thus theoretically, given a noise figure, *NF*, of 4.65, as per Fig. 5, a signal just 3dB above noise can be detected. This corresponds to a level of,

#### -144+4.65+3=-136.65dBm.

When the vco generates 1300MHz it is important that the first amplifier, which has to operate on the lowest amplitude signals, does not saturate. To decrease the signal passing through the mixer, a double balanced type is insufficient.

I have made a phase network to produce a 1300MHz signal with opposite phase, and the same amplitude as the mixer output. The res-



onant lines, a quarter wavelength, shown in Fig. 6, were made with teflon RG174 coaxial cable and the trimmers are miniature carbon types, as are the resistors.

#### Third local oscillator

The third local oscillator, Fig. 7, is simple, especially if it is phase locked loop with a very high comparator frequency.

The high comparator frequency guarantees short lock time and spurious signals are far from the carrier minimum of 1MHz. As a result, they are outside the range of the intermediate-frequency filters.

With a direct synthesis phase-locked loop, it is possible to further decrease phase noise and increase stability. This circuit does not limit the noise characteristics of the spectrum analyser provided that you take care with the 9MHz voltage-controlled oscillator.

To make a stable, low noise and non-microphonic oscillator, use silvered-mica *NPO* capacitors, inductors with mechanically stable supports and a stable, well filtered power supply.

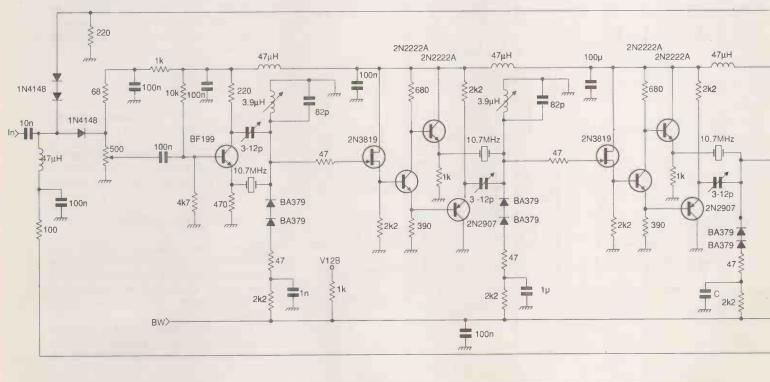
Remember to solder oscillator components to the board, or fix them using wax or adhe-

sive. This will prevent microphonic effects and allow you to remove them if necessary.

#### Variable quartz filter

The quartz filter that determines bandwidth relies on the resistance of *PIN* diodes in parallel with the tuned circuit. Increasing current into the diodes decreases their equivalent resistance. It also decreases the ratio Q=F/B between the centre frequency and the 3dB bandwidth.

If the variation of diode capacitance is negligible, they do not change F but increase B.



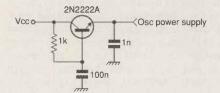


Fig. 9. Low impedance power supply. Input ac fluctuations are reduced by the 100nF capacitor.

In Fig. 8, trimmer capacitors compensate for asymmetry in the frequency response. The junction fet guarantees a high impedance to help obtain a high Q.

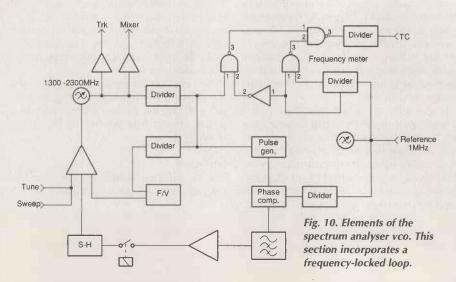
When implementing this circuit, it is necessary to select crystals that work in series fundamental mode, with identical frequencies and with minimum equivalent resistance.

#### **Digital interface**

Control voltages are produced by the digital interface. This comprises two *MAX500* quad 8bit serially-controlled d-to-a converters and two *MAX543* 12bit d-to-a converters. These generate voltages for tuning the vco and for sweeping and calibrating it.

Together with low noise op-amps, these d-to-a converters generate voltages to calibrate the vco and the third local oscillator. They also produce signals for tuning the third local oscillator, controlling bandwidth, calibrating gain and changing intermediate-frequency gain.

On the same board *ULN2004* drivers control the rf attenuator relays, the cut-off relay and close the vco phase-locked loop in the first local oscillator. A peak detector integrates the



amplitude of four successive samples of the log amplifier prior to the a-to-d conversion. Sweeping is produced by a 12bit d-to-a converter, but on screen it is not possible to detect more than 500 horizontal steps. Moreover this integration can be used to increase signal to noise ratio and sensitivity.

#### Interfacing to a pc

I designed most of the control ICs on to a pc AT BUS expansion card. It holds an Analog Devices' *AD7821* fast a-to-d converter, a 12bit d-to-a converter, a triple programmable timer and an 8255 i/o interface.

One flat cable and two miniature coaxial cables transfer every digital control, analogue input to the a-to-d converter and sweep volt-

of the age to the digital interface board. This is not the best solution, but it is simple.

#### **First local oscillator**

Many of the spectrum analyser's parameters depend on local oscillator characteristics. The main technical specifications of this module are,

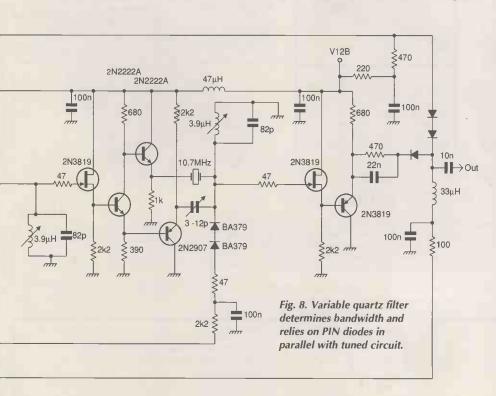
- Frequency range with a relatively constant amplitude from 1.3-2.3GHz,
- two output ports with power higher than +7dBm,
- phase lock capabilities with steps of 1MHz or lower,
- very low phase noise,
- linear transfer function from control voltage and output frequency.

Together these characteristics are difficult to achieve. If you do not have uhf components, instrumentation and experience in ultra high frequencies, you can waste a lot of time trying to sort out the oscillator. Certainly a yttriumiron-garnet oscillator can solve many of these problems. But such oscillators are expensive and difficult to find.

A good alternative to a labour-intensive home made oscillator is a solid-state voltagecontrolled crystal oscillator. Several manufacturers, including Avantek and Watkin Johnson, make small, uhf oscillator modules in packages similar to *TO5*. Such oscillators do not normally give the required power, but they do allow you to simplify and repeat the circuit characteristics.

When using this module, the power supply should have a low impedance between dc and the operating frequencies. To achieve this it is not sufficient to have very short connections to ground – even leadless ceramic capacitors. It is necessary to use an active buffer, **Fig. 9**.

To linearise the vco transfer function I have made a frequency-locked loop like the one shown in the internal feed back of **Fig. 10**. Output frequency is divided 2048 times before



#### **RF ENGINEERING**

triggering a constant pulse generator.

If pulses are shorter than the triggering period, their number per second is proportional to the output frequency. Integrating these pulses, whose amplitude and duration is constant, gives a dc signal proportional to frequency. I use this voltage as feedback in an analogue adder, where tune and sweep voltages and the error voltage from the phased-locked loop comparator are connected.

To obtain low phase noise near the carrier it is better not to divide the output frequency too far. If you do, it is possible to transfer the stability and phase noise of the reference oscillator to the output signal. In my spectrum analyser, this only happens when the vco is locked and the sweep voltage is connected to the third local oscillator. Also if the low frequency vco in the third local oscillator is free running, it is relatively clean, and its phase noise is not detectable on the screen with a span of several megahertz.

#### **Phase comparator**

The phase comparator is made with a very fast pulse generator and a mixer that samples output frequency, divided by four. Using this solution, pulses are separated from the oscillator output with a cleaner spectrum spread, and amplitude on the phase-comparator can be kept constant.

By connecting a signal derived from the fre-

quency-locked-loop divider to a 16bit divider it is possible to produce a frequency meter. It is possible to count how many pulses are required to bring the counter to zero using the pc. Since the precise counting period is known, derived from the reference oscillator, it is easy to calculate the input frequency with a good degree of accuracy.

The same frequency counting system is used to measure the variable 9MHz third local oscillator. Mixing the measured frequencies in a simple formula it is possible to display the receiving frequency.

#### Software

The pc software controlling the spectrum analyser comprises these functions:

- draw a graticule and reference numbers for the set parameters on screen,
- draw lines between the y axis samples, repaint colours and clear graticule elements from previous lines,
- read keyboard and optical encoder to determine functions requested,
- save measurement samples in memory for later disk storage,
- configure the pc so that 'Print Screen' key can start a print out.

Some of these functions are time critical

because the 'time per division' must be independent from program cycle time. To execute the graphics functions mentioned fast enough for a real-time display, using serial and parallel ports on a standard pc can cause problems.

I tried small 386 assembly language routines and specific professional software, for example National's *LabWindows* and Hewlett Packard's *APPCAD*. Both produced good results in terms of speed and graphics.

My main program was written in Quick Basic. It is unpretentious, and is continuously undergoing modifications and updating.

In a subsequent article, Felice discusses set up, calibration and software details.

#### Further reading

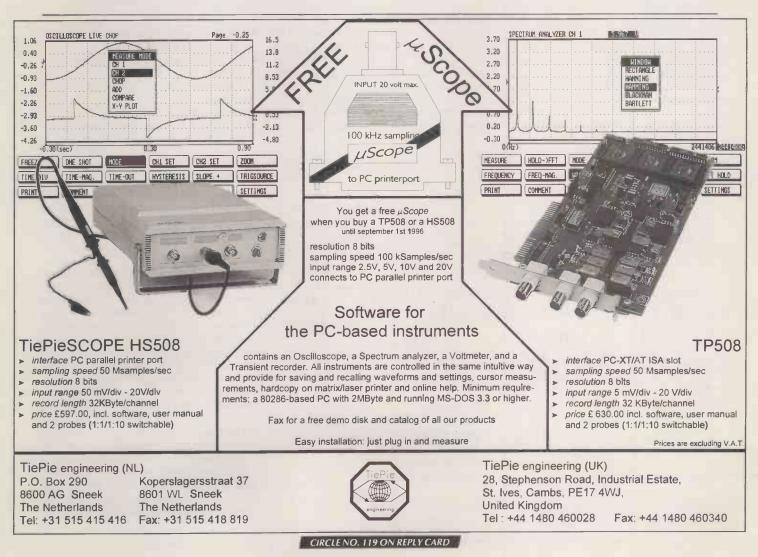
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## Unipolar positive operation for the DAC-08

The DAC-08 digital-to-analogue converter has excellent performance and provides complementary outputs. Its data sheet

Table Outsut meaning block	ry input for the unipolar d-to-a.
i ladie. Output versus dinar	y input for the unipolar a-to-a.

Input status	B <sub>1</sub>	B <sub>2</sub>	<b>B</b> <sub>1</sub>	B <sub>1</sub>	<b>B</b> <sub>1</sub>	<b>B</b> <sub>1</sub>	<b>B</b> <sub>1</sub>	Eo	Ē,
Full scale	1	1	1	1	1	1	1	0.04	10.00
Full scale-lsb	1	1	1	1	1	1	0	0.08	9.96
Half scale-Isb	1	0	0	0	0	0	1	4.96	5.08
Half scale	1	0	0	0	0	0	0	5.00	5.04
Half scale-Isb	0	1	1	1	1	1	1	5.04	5.00
Zero scale+lsb	0	0	0	0	0	0	1	9.96	0.08
Zero scale	0	0	0	0	0	0	0	10.00	0.04

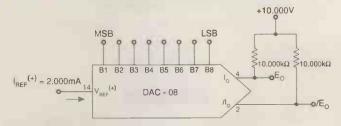


Fig. 1. Basic bipolar operation, as shown in Motorola's data sheet for the DAC-08.

shows various schemes for using the outputs with external components to obtain bipolar or unipolar characteristics. There is, however, no apparent method of obtaining a unipolar *positive* output. The circuit shown for the positive low-impedance equivalent has no provision for complementary output. This circuit is a solution to the problem.

Basic bipolar operation is shown in the data sheet, reproduced in Fig. 1, and a modification of this, Fig. 2, provides the answer. Splitting the two  $10k\Omega$  resistors into two halves, with outputs taken from the junctions, effectively shifts the whole output positive by 10V, as indicated in the table.

With this scheme, unipolar positive and bipolar outputs are available from the same circuit.

**S Ravindranathan** Naval Physical and Oceanographic Laboratory Kochi Indi**a** 

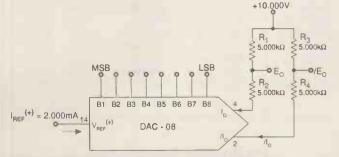


Fig. 2. Modifying the circuit of Fig.1 provides both unipolar positive and bipolar working at the same time.

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200K 500 IC SO 14/16/18/ 8-WAY D 32-WAY D SIMM SO POLY	100R 200R 250R 500R 2K 2K2 2K5 5K 10K 47K 50K 100K           (2M         50p ea           CKETS         50p ea           0204/23/40-WAY DIL SKTS         £1 per TUBE           L SKITS         £2 per TUBE           URNED PIN SKTS         3 for £1           CKETFOR 2x 30-way SIMMS         51           CKETR/POLYCARB CAPS         51           CAPLAC YA DATED PUN US TYPE 320         50/000	
200K 500 IC SO 14/16/18/ 8-WAY D 32-WAY D SIMM SO POLY	100R 200R 250R 500R 2K 2K2 2K5 5K 10K 47K 50K 100K           (2M         50p ea           CKETS         50p ea           0204/23/40-WAY DIL SKTS         £1 per TUBE           L SKITS         £2 per TUBE           URNED PIN SKTS         3 for £1           CKETFOR 2x 30-way SIMMS         51           CKETR/POLYCARB CAPS         51           CAPLAC YA DATED PUN US TYPE 320         50/000	
200K 500 IC SO 14/16/18/ 8-WAY D 32-WAY D 32-WAY D 330F 10 100n, 220 10/15/2 100n 500 100n 620 1000 600 2µ2 160V	100R 200R 250R 500R 2K 2K2 2K5 5K 10K 47K 50K 100K           (2M         50p ea           CKETS         50p ea           020/24/23/40 WAY DIL SKTS         £1 per TUBE           L SKITS         £2 per TUBE           URNED PIN SKTS         3 for 12           CKETFOR 2x 30-way SIMMS         51           ESTER/POLYCARE CAPS         520100           % 250V AC X2 RATED PHILIPS TYPE 330         20c1 100/23, 52           2n/33n/47m66n 10mm rad         100/23, 52           7 radial 10mm         100/25, 52           7 radial 10mm         100/25, 57           7 rad 22mm, 2µ2 100V rad 15mm         100/25, 52	
200K 500 IC SO 14/16/18/ 8-WAY D 32-WAY 1 SIMM SO POLY 330nF 10 100n, 220 100n 250 100n 600 2µ2 160V 10r/33n/4 1µ 600V I	100R 200R 250R 500R 2K 2K2 2K5 5K 10K 47K 50K 100K           K 2M         50p ea           CKETS         50p ea           00R 24/24/40-WAY DIL SKTS         £1 per TUBE           L SKITS         52 per TUBE           URNED PIN SKTS         3 for £1           CKETOR 2x 30-way SIMMS         51           ESTER/POLY CARB CAPS         500 for 60           % 250V CK 2X RATED PHILLIPS TYPE 330         20/100           n 63V 5mm         20/23n/47n/66n 10mm rad         100/53,57           Y adala 10m         100/53,57         7 adala 100°1           7 ad 22mm 22 100V rad 15mm         100/516         70 ado 200 AC x rated 15mm           10 KED DIELECTRIC         50p ea         100/516	
200K 500 IC SO 14/16/18/ 8-WAY D 32-WAY T SIMM SO <b>POLY</b> 330nF 10 100n, 220 100n 600 2µ2 1600/ 10n/33n/4 1µ6 000/ 100/33n/4	100R 200R 250R 500R 2K 2K2 2K5 5K 10K 47K 50K 100K           (2M	
200K 500 IC SO 14/16/18/ 8-WAY D 32-WAY T SIMM SO POLY 330nF 10 100n 250 100n 250 100n 600 2µ2 160V 100 100V 2µ2 160V 1µ60V V 1µ0 100V 0.22µ 250 0.22µ 900	100R 200R 250R 500R 2K 2K2 2K5 5K 10K 47K 50K 100K           K2M         50p ea           CKETS         50p ea           00R 24/24/40-WAY DIL SKTS         £1 per TUBE           L SKITS         £2 per TUBE           URNED PIN SKTS         3 for £1           CKET FOR 2x 30-way SIMMS         51           ESTER/POLY CARE CAPS         \$20/100           x033n 47/n/66n 10mm rad         100/E3 5C           2n/33n 47/n/66n 10mm rad         100/E3 5C           7 adda1 10m         100/E1 5C           7 add 22mm 2y 100V rad 15mm         100/E1 5C           7 add 15mm, 100 25mm rad         100/E1 5C           7 add 22mr 2,4 200V rad 15mm         100/E1 5C           7 add 22mr 2,4 100 25mm rad         100/E1 5C           7 add 22mr 2,4 100V rad 15mm         100/E1 5C           7 ad 22mr 2,4 200V rad 15mm         100/E1 5C	
200K 500 IC SO 14/16/18/ 8-WAY 1 32-WAY 1 330nF 10 100n, 220 100n 600 2µ2 160V 100/33n4 1µ 600V 1µ60V 1µ602V 1µ60V	100R 200R 250R 500R 2K 2K2 2K5 5K 10K 47K 50K 100K         50p ea           CKETS         50p ea           000R 2002 /23/40-WAY DIL SKTS         £1 per TUBE           L SKITS         £2 per TUBE           URNED PIN SKTS         3 for £1           CKETFOR 2x 30-way SIMMS         3 for £1           CKET FOR 2x 30-way SIMMS         2010           630 5mm         20011 00 fc3           2n/33n/47n/66n 10mm rad         100135           7 radial 10mm         1000516           7 radial 10mm         1000516           7 rad 22mm, 22 100V rad 15mm         100165           70 at 10nc11         50p ea           MIXED DIELECTRIC         50p ea           VAC X2 RATING         4/et m           VAC X2 RATING         4/et m	
200K 500 IC SO 14/16/18/ 8-WAY 1 32-WAY 1 330nF 10 100n, 220 1001 500 2µ2 160V 1001 000 000 200 2µ2 160V 1001 000 000 200 2µ2 160V 1001 000 002 2µ2 50 002 2µ2 000 <b>RFBI</b> SAW FILT 379.5 MH	100R 200R 250R 500R 2K 2K2 2K5 5K 10K 47K 50K 100K           (2M         50p ea           CKETS         50p ea           000R 200R 250R 500R 2K 2K2 2K5 5K 10K 47K 50K 100K         50p ea           CKETS         50p ea           000R 200R 250R 500R 2K 2K2 2K5 5K 10K 47K 50K 100K         51p er TUBE           L SK17S         51 per TUBE           URNED PIN SKTS         51 per TUBE           SCRETFOR 2X 30-way SIMMS         51           ESTER/POLYCARE CAPS         500 f00           63V 5mm         200100           n 63V 5mm         100153           20/32n/47/n66n 10mm rad         100153           100 F1         100154           7 radal 10mm         100251           7 radal 10mm         100251           7 radal 10mm         100251           7 radal 10mm         100251           7 rad 22mm rad         100251           7 rad 15mm, 100 22mm rad         100252           V AC X2 RATING         4E1           V         V           V         4E1           TS         20051 100 250           TS         20052 250 651 PLESSEY SIGNAL TECHNOLOGY           Z         51,50 ea	
200K 500 14/16/18 8-WAY D 32-WAY 330nF 10 32-WAY 300nF 20 100n 520 100n 520 100 5	100R 200R 250R 500R 2K 2K2 2K5 5K 10K 47K 50K 100K           (2M         50p ee           CKETS         50p ee           0.0024/23/40-WAY DIL SKTS         £1 per TUBE           L SK15S         £2 per TUBE           URNED PIN SKTS         3 for £1           CKET FOR 2x 30-way SIMMS         £1           ESTER/POLYCARB CAPS         £20100           r033 5m         2011           r04alal 100mm rad         100(£3, 52)           r04alal 10mm         100(£5, 52)           r04alal 10mm         100(£6, 62)           Y Sprague axial 10(£1)         100(£6, 62)           r04 5mm, 24, 2100V rad 15mm         100(£6, 62)           r04 5mm, 24, 2100V rad 15mm         100(£6, 72)           r04 5mm, 24, 200V rad 15mm         100(£6, 72)           r04 5mm, 24, 200V rad 15mm         100(£6, 72)           r04 5mm, 100 22mr rad         100(£6, 72)           VAC X2 RATING         4/2 for           TS         ERIS SW662/SW661 PLESSEY SIGNAL TECHNOLOGY           EIRS SW662/SW661 PLESSEY SIGNAL TECHNOLOGY         £1,50 ee           EIRITE RING 10 5mm 0D 10mm         10 for £1	
200K 500 14/16/18 8-WAY D 32-WAY 330mF 10 32-WAY 300nF 20 100n 520 100n 520 1	100R 200R 250R 500R 2K 2K2 2K5 5K 10K 47K 50K 100K           (2M         50p ee           CKETS         50p ee           0.002/4/28/40-WAY DIL SKTS         £1 per TUBE           L SK17S         £2 per TUBE           URNED PIN SKTS         3 for £1           CKET FOR 2x 30-way SIMMS         £1           ESTER/POLYCARB CAPS         \$20100           r0305 mm         20211 100/£3           2n/33n/47n/66n 10mm rad         100/£3, £2           100/£3, £7         100/£6           2n/33n/47n/66n 10mm rad         100/£3, £2           100/£3, £7         100/£6           7 radal 10mm         100/£5, £2           7 radis 10mm         100/£6           7 radis 10mm         100/£5, £2           7 radis 10mm         100/£5, £2           7 radis 10mm         100/£5, £2           Y AC X2 RATING	
200K 500 IC SO 14/16/18/ 8-WAY 1 32-WAY 1 330nF 10 330nF 10 100n 500 POLY 330nF 10 100n 500 100n 500 100 600 V 100 100V 000 222 160V 100 100V 100 500 222 160V 100 100V 100 500 222 160V 100 100V 100 500 222 160V 100 100V 100 500 222 160V 100 500 500 222 160V 100 500 500 222 160V 100 500 500 500 222 160V 100 500 500 500 500 500 500 500 500 500	100R 200R 250R 500R 2K 2K2 2K5 5K 10K 47K 50K 100K           K2M         50p ea           CKETS         50p ea           00R 200R 250R 500R 2K 2K2 2K5 5K 10K 47K 50K 100K         50p ea           CKETS         50p ea           URNED PIN SKTS         £1 per TUBE           L SKITS         52 per TUBE           URNED PIN SKTS         3 for £1           SCKET FOR 2x 30-way SIMMS         51           ESTER/POLY CARBE CAPS         \$20/100           x033n 47/r/66n 10mm rad         100/E3 5C           100 rad 22m 72 100V rad 15mm         100/E1           100 s0 AC x rated 15mm         100/E1           10 200 AC x rated 15mm         100/E1           10 AC XR ATED FHILLISE YPE 30.         20/10           10 AC XR ATED FMILLISE YPE 30.         20/10           10 AC XR ATED FMILLISE YPE 30.         20/10           rad 15mm, 10 021         100/E3 5C           10 AC XR ATING         10/021           10 AC XR ATING         4/E1           10 AC XR ATING         10 for E1           10 X23 UHF VIDEO MODULATO	
200K 500 IC SO 14/16/18/ 8-WAY 1 32-WAY 330nF 10 100n 500 POLY 330nF 10 100n 500 100n 500 212 160V 100 1000 002 21 60V 100 1000 002 21 60V 100 1000 002 20 900 REBI 379.5 MH FX3266 ASTEC U STOCK MARCOM	100R 200R 250R 500R 2K 2K2 2K5 5K 10K 47K 50K 100K         50p ea           CKETS         50p ea           CKITS         21 per TUBE           URNED PIN SKTS         21 per TUBE           URNED PIN SKTS         31 or 1           CKETS         31 or 1           CKETOR 2x 30-way SIMMS         51           ESTER/POLY CARB CAPS         20/100           x 250V CK 2X RATED PHILLIPS TYPE 330         20/100           n 63V 5mm         20/121 100/123           2n/33n/47n/66n 10mm rad         100/13, 57           rad 22mm 2/2 100V rad 15mm         100/13, 57           Yadal 100E1         100/25, 67           7 ad 22mm 2/2 100V rad 15mm         100/13, 57           YAC 2X RATED FILECTRIC         50p ea           YAC 2X RATING         4/21           YAC 2X RATING         4/21           YAC 2X RATING         4/21           YAC 2X RATING         10/107           YAC 2X RATING         11.50	
200K 500 14/16/18/ 8-WAY 32-WAY 330mF 10 100n, 220 100/15n/2 100n 500 2µ2 160V 100 1000 200 2µ2 160V 1µ0 100V 0.22µ 250 0.22µ 900 <b>RFBI</b> SAW FILI 379.5 MH FX3266 F ASTEC U STOCK. MARCON DC4229F STAL FIL ALL TRIM VIOLET.	100R 200R 250R 500R 2K 2K2 2K5 5K 10K 47K 50K 100K         50p ea           CKETS         50p ea           CKITS         21 per TUBE           URNED PIN SKTS         21 per TUBE           URNED PIN SKTS         31 or 11           CKETS         22 per TUBE           URNED PIN SKTS         31 or 11           CKETFOR 2x 30-way SIMMS         51           ESTER/POLY CARB CAPS         20/100           x 250V CK 2X RATED PHILLIPS TYPE 330         20/100           n 63V 6mm         20/11 00/013           2n/33n/47n/66n 10mm rad         100/13, 54           1/ radial 10mm         100/13, 54           1/ radial 10mm         100/13, 54           1/ radial 10mm         100/13, 54           1/ radial 10x1         100/25, 54           1/ radial 10x1         100/25, 54           1/ radial 10x1         100/25, 54           1/ radial 10x1         10/02, 56           1/ rad 2zmm, 2µ2 100V rad 15mm         10/02, 56           1/ rad 2zmm, 2µ2 100V rad 15mm         10/02, 56           YAC X2 RATING         4/21           YAC X2 RATING         4/21           YAC X2 RATING         10/21           YAC X2 RATING         10/21           YAC X2 RATING	
200K 500 IC SO0 14/16/18/ 8-WAY D 32-WAY 330nF 10 100n, 222 10/15/ 100n 250 100n 600 2µ2 1600/ 1µ6 1000/ 0.22µ 900 0.22µ 900 0.22µ 250 0.22µ 900 RF BI SAW FLT 379.5 MH FX3266 F ASTEC U STOCK MARCON DC4229F XTAL FIL ALT TRIN VIOLET RED 10-1	100R 200R 250R 500R 2K 2K2 2K5 5K 10K 47K 50K 100K         50p ea           CKETS         50p ea           000R 200R 250R 500R 2K 2K2 2K5 5K 10K 47K 50K 100K         50p ea           CKETS         50p ea           000R 200R 250R 500R 2K 2K2 2K5 5K 10K 47K 50K 100K         50p ea           CKETS         51p er TUBE           URNED PIN SKTS         51 per TUBE           CKET FOR 2x 30-way SIMMS         51 or 51           S20V AC X2 RATED PHILIPS TYPE 330         520/100           R3V 5mm         100/13, 55           Y oradial 10mm         100/25, 57           Y oradial 10mm         100/25, 57           Y oradial 10mm         100/25, 67           Y add 310mm         100/25, 67           Y AC X2 RATING         4/21           Y         Y           Y AC X2 RATING         4/21           Y         Y           Y AC X2 RATING         4/21           Y         Y           Y         Y           Y	
200K 500 IC SO0 14/16/18/ 8-WAY D 32-WAY T 330nF 10 100n, 222 10n/15/v2 100n 250 100n 600 2µ2 1600/ 100 2µ2 1600/ 100/30/4 1µ6 1000/ 0.22µ 900 RFBI SAW FLI 379.5 MH FX3266 F ASTECK MARCON 0:242 F XTAL FLI ALL TRIN VIOLET RED 10-1 2 to 22p F TRANSIS	100R 200R 250R 500R 2K 2K2 2K5 5K 10K 47K 50K 100K         50p ea           CKETS         50p ea           CKITS         51p per TUBE           LSK17S         51p per TUBE           URNED PIN SKTS         51p per TUBE           URNED PIN SKTS         3 for 51           SCRETFOR 2x 30-way SIMMS         51           ESTER/POL YCARE CAPS         520/100           % 250V AC X2 RATED PHILIPS TYPE 330         520/100           ROV 5Mm         100/13, 52           7 / radial 10mm         100/25, 52           7 / radial 10mm         100/25, 52           100 / rad 22mm 2/100V rad 15mm         100/25, 62           100 / rad 22mm 2/100V rad 15mm         100/25, 62           100 / rad 15mm, 1/00 / 22mm rad.         100/25, 62           V AC X2 RATING         4/21           V AC X2 RATING         4/21           V AC X2 RATING         4/21           V X         4/21           V X         20 / 22           XU         20 / 22           X         10 / 20           X         10 / 20           X         100 / 21           X         10 / 22           X         10 / 20           X         10 / 20 </td <td></td>	
200K 500 IC SO0 14/16/18/ 8-WAY D 32-WAY T 330nF 10 100n, 222 10n/15/v2 100n 250 100n 600 2µ2 1600/ 100 2µ2 1600/ 100/30/4 1µ6 1000/ 0.22µ 900 RFBI SAW FLI 379.5 MH FX3266 F ASTECK MARCON 0:242 F XTAL FLI ALL TRIN VIOLET RED 10-1 2 to 22p F TRANSIS	100R 200R 250R 500R 2K 2K2 2K5 5K 10K 47K 50K 100K         50p ea           CKETS         50p ea           CKITS         10p er TUBE           LSK17S         12p er TUBE           URNED PIN SKTS         10p r TUBE           SK17S         12p er TUBE           URNED PIN SKTS         3 for 11           OXCX 2X 30-way SIMMS         10f 11           CKET FOR 2x 30-way SIMMS         10f 21           CKET FOR 2x 30-way SIMMS         100 C13           CAST POR 2x 30-way SIMMS         2011 00/C13           X 250V AC X2 RATED PHILIPS TYPE 330         22011 00/C13           CAST PATTER         100/C13           Y 3prague axia 10/C1         100/C15           TA 220m 21 00V rad 15mm         100/C15           TA 220M AC x rated 15mm         100/C15           TA 250V AC x rated 15mm         100/C15           Y AC X2 RATING         4/E1           V         2           X 2         15.00 ec           ERS X062/SW661 PLESSEY SIGNAL TECHNOLOGY         2           X 2         11.50           ENGUMAY DIDE	
200K 500 IC SO 14/10/918 8-WAY D 32-WAY 330nF 10 32-WAY 300nF 20 100n,222 100/15/2 100n 250 100n 250 100n 250 100 242 160V 100 500 242 160V 100 500 242 160V 100 500 00,229 00 0,229 00 0,200 00 0,000 00	100R 200R 250R 500R 2K 2K2 2K5 5K 10K 47K 50K 100K         50p ea           CKETS         50p ea           CKETS         50p ea           CWARD PUN SKTS         £1 per TUBE           L SKITS         £2 per TUBE           URNED PUN SKTS         3 for £1           CKET FOR 2x 30-way SIMMS         51           CKET FOR 2x 30-way SIMMS         51           CKET FOR 2x 30-way SIMMS         520100           CS0V AC X2 RATED PHILIPS TYPE 330         520100           CASU ATED PHILIPS TYPE 330         520100           CY adail 10mm         10013.55           Y radial 10mm         10015.55           Y radial 10mm         10015.55           Y adail 10mm         10015.55           Y AC X2 RATING         4/21           Y AC X2 RATING         4/21           Y AC X2 RATING         4/21           Y         Y         4/25           Y         TS         50 pe           ERS SW662/SW661 PLESSEY SIGNAL TECHNOLOGY         11.51           IMICROWAVE DIODES TYPES DC2929, DC2922,	
200K 500 14/16/14 8-WAY D 32-WAY 330m 520 POLY 330m 520 10/15m2 100m 520 10/15m2 10/15m	100R 200R 250R 500R 2K 2K2 2K5 5K 10K 47K 50K 100K         50p ea           CKETS         50p ea           CKITS         10p er TUBE           LSKITS         12p er TUBE           URNED PIN SKTS         11p er TUBE           LSKITS         12p er TUBE           URNED PIN SKTS         10r 11           OCKET FOR 2x 30-way SIMMS         11           ESTER/POLY CARE CAPS         20/10           n 63V 5mm         20/10           n 63V 5mm         20/10           n 63V 5mm         100/11           Y chail 10mm rad         100/21           100 21 f 20/21         100/21           7 add 2mm 2/21 00V rad 15mm         100/11           100 20 AC x rated 15mm         100/11           10A 22mm 2/21 00V rad 15mm         100/12           17 a 250V AC x rated 15mm         100/11           10A 22m ALLOCTRIC         50p ea           rad 15mm, 1µ0 22mm rad.         100/21           VAC X2 RATING.         4/21           V.         4/21           VIE23 UHF VIDEO MODULATORS (NO SOUND) 1/250           11MICROWAVE DIODES TYPES DC2929, DC2962.         11.50           11MICROWAVE DIODES TYPES DC2929, DC2962.         11.51           11MICROWAVE DIODES TYPES DC2929, D	
200K 500 14/16/18 8-WAY D 32-WAY 330mF 10 100n,220 100n 520 100n 520	100R 200R 250R 500R 2K 2K2 2K5 5K 10K 47K 50K 100K         50p ea           CKETS         50p ea           CKITS         21 per TUBE           LSK17S         21 per TUBE           LSK17S         21 per TUBE           LSK17S         21 per TUBE           URNED PIN SKTS         31 or 11           CKETS         20/100           RESTER/POLY CARB CAPS         \$20/100           % 250V AC X2 RATED PHILIPS TYPE 330         20/100           n 633 %mm         20/11 100/12           2n/33n/47n/66n 10mm rad         100/13, 5           Y radial 10m         100/13, 5           Y radial 10m         100/13, 5           Y radial 1001         100/25, 6           Y calal 1001         100/10, 7           Y calal 1001         100/10, 7           Y calal 1001         100/10, 7           Y cala 2mm, 2µ2 100V rad 15mm         10/02, 10           YAC 24 RATING         4/21           YAC 24 RATING         4/21           YAC 24 RATING         4/21           YAC 24 RATING         10 for 1           YAC	E E I I D B B B B B B B B B B B B B B B B B
200K 500 14/16/18 8-WAY D 32-WAY 330mF 10 100n 520 100n 520	100R 200R 250R 500R 2K 2K2 2K5 5K 10K 47K 50K 100K         50p ea           CKETS         50p ea           CKITS         21 per TUBE           LSK17S         21 per TUBE           Stort CX 2R ATED PHILIPS TYPE 330         20/10           n 630 %mm         20/11 00/013           2n/33n/47n/66n 10mm rad         100/013           17 radial 10mm         100/013           17 radial 10mm         10/013           17 radial 10mm         10/014           17 radial 10mm         10/015	E E I I D B B B B B B B B B B B B B B B B B
200K 500 IC S00 14/16/18/ 8-WAY D 32-WAY 330nF 10 100n, 222 10n/15/v2 100n 250 100n 600 2µ2 1600 000 200 1000 200 000 200 000 200 <b>RFBI</b> SAW FL1 379.5 MH FX3266 F ASTEC U STOCK MARCON 0.22µ 900 0.22µ 900	100R 200R 250R 500R 2K 2K2 2K5 5K 10K 47K 50K 100K         50p ea           CKETS         50p ea           CKITS         10p er TUBE           LSKITS         12p er TUBE           LSKITS         12p er TUBE           URNED PIN SKTS         10 r 11           SCRETCR         20/100           RSTER/POL YCARE CAPS         20/100           % 250V AC X2 RATED PHILIPS TYPE 330         20/100           R03V 5mm         100/13           2n/33n/47n/66n 10mm rad         100/13           100/13         100/13           2n/33n/47n/66n 10mm rad         100/13           100/14         100/15           7 radial 10mm         100/16           7 radial 10mm         100/16 <td>E E I I D B B B B B B B B B B B B B B B B B</td>	E E I I D B B B B B B B B B B B B B B B B B
200K 500 IC SOO 14/16/18/ 8-WAY D 32-WAY 330nF 10 132-WAY 330nF 10 100n, 222 100n/15// 100n 250 100n 250	100R 200R 250R 500R 2K 2K2 2K5 5K 10K 47K 50K 100K         50p ea           CKETS         50p ea           000R 200R 250R 500R 2K 2K2 2K5 5K 10K 47K 50K 100K         50p ea           CKETS         50p ea           000R 200R 250R 500R 2K 2K2 2K5 5K 10K 47K 50K 100K         50p ea           CKETS         51p er TUBE           000R 200R 250R 500R 2K3 3K5         51 or 51           00R 200R 250R 500R 2K3 3K5         51 or 51           00R 200R 250R 500R 2K3 3K5         51 or 51           00R 50R 50R 50R 50R 50R 50R 50R 50R 50R	E E I I D B B B B B B B B B B B B B B B B B
200K 500 14/16/18/ 8-WAY D 32-WAY 330nF 10 100n, 222 100n/1502 100n 600 2µ2 160V 100n 600 2µ2 160V 100n 600 2µ2 160V 100n 600 2µ2 160V 100n 600 2µ2 160V 100n 500 <b>RFBI</b> SAW FILT 379-5 MH FX3286F ASTEC U STOCK MARCON 0C4229F XTAL FIL ANSIS CERAMIC FED TH SL610 6 VOLT T 21N2222 2N3369A 2N3416 TF 2N2222 2N3369A 74N16 TF EQUIV MONOCO	100R 200R 250R 500R 2K 2K2 2K5 5K 10K 47K 50K 100K         50p ea           CKETS         50p ea           CKETS         50p ea           000R 200R 250R 500R 2K 2K2 2K5 5K 10K 47K 50K 100K         50p ea           CKETS         51p er TUBE           000R 200R 250R 500R 2K2 2K2 5K 10K 47K 50K 100K         51p er TUBE           000R 200R 250 WAY DIL SKTS         51 per TUBE           00R 200R 250 WAY DIL SKTS         51 per TUBE           00R 200R 250 WAY DIL SKTS         51 or 51           00R 200R 250 WAY DIL SKTS         52 of 100           00R 200R 250 WAY AT M66N 10mm rad         1000C1 52           20/30R 47 M66N 10mm rad         1000C1 52           20/30R 47 M66N 10mm rad         1000C1 52           20/30R 47 M66N 10mm rad         1000C1 52           20/30R 42 100V rad 15mm         1000C1 52           7 A 250 VA CX rated 15mm         100 for 50           10/30R 42 100V rad 15mm         100 for 51           10/30R 42 100V rad 15mm         100 for 51           10/30R 42 PATING         4/4 for 72           7         500 862/SW661 PLESSEY SIGNAL TECHNOLOGY           10/30R 42 PATING         4/2 for 50           10/30R 500 500 100 10mm         10 for 51           10/30R 500 500 500 100 10mm         10 for 50	E E I I D 3 3 3 3 3 3 3 3 3 3 3 3 3 3 3 3 3
200K 500 IC SOO 14/10/918 8-WAY D 32-WAY 330nF 10 32-WAY 330nF 10 100n, 222 100/15/02 100n 250 100n 250 100n 250 100 202 100/0 202 160V 100/0 202 100V 100/0 202 205C 100/0 202 205C 202 205C	100R 200R 250R 500R 2K 2K2 2K5 5K 10K 47K 50K 100K         50p ea           CKETS         50p ea           CKETS         50p ea           URNED PIN SKTS         £1 per TUBE           L SKITS         52 per TUBE           URNED PIN SKTS         3 for £1           OX4 2/2/40 WAY DIL SKTS         £1 per TUBE           URNED PIN SKTS         3 for £1           OKET FOR 2x 30-way SIMMS         51           ESTER/POL YCARE CAPS         \$20100           % 250V AC X2 RATED PHILIPS TYPE 330         520110           R03V 5mm         100£3           Y oradial 10mm         100£5           Y cadal 10mm         101£5           Y         2         £1.50           ERS SW662/SW661 PLESSEY SIGNAL TECHNOLOGY         \$1.50           Y cadal 10m	a a a a a a a a a a a a a a a a a a a
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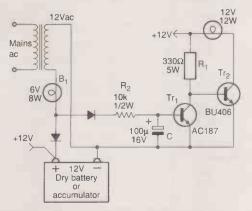
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## **Trickle-charged emergency light**



Emergency lights designed to switch on when the mains fails have the disadvantages that it can be expensive to repair them when necessary and to keep them in batteries. This design uses an old 12V car battery, but the circuit may be modified to take a 6V battery.

With normal mains operation, the

Car battery is normally charged from the mains, powering the 12V emergency lamp during mains failure. battery charges through  $D_1$ , the 6V bulb indicating the fact. Since  $Tr_1$  is bottomed by way of  $D_2$  and the smoothing components  $CR_2$ ,  $Tr_2$  is turned off. Consequently the 12V lamp is off. A mains failure cuts  $Tr_1$ off, so  $Tr_2$  conducts and the 12V lamp comes on.

Transistor  $Tr_2$  is a power type on a heat sink and the 12V bulb may be replaced by three 6V, 8W bulbs for a longer life. *I Rahman* 

Islamabad Pakistan

### £100 WINNER 200MHz spectrum analyser displays to -75dB

Used with an ordinary oscilloscope, this circuit forms a spectrum analyser for the 0-200MHz range of frequencies. To simplify examination of the wanted frequency, span and centre frequency controls

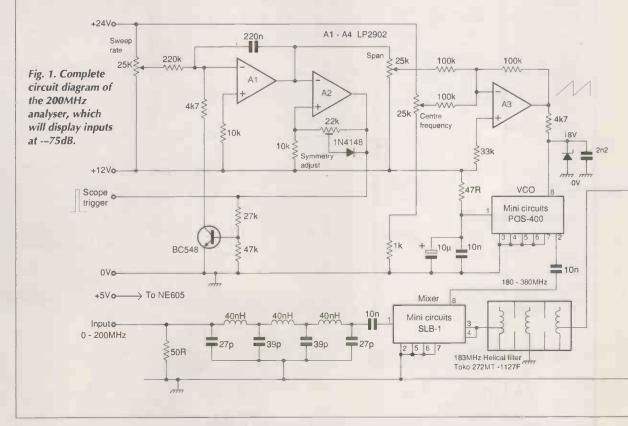
are arranged to make signals in the

middle of the trace stay there as span

decreases.

Amplifiers  $A_1$  and  $A_2$  produce a sawtooth waveform, symmetrical about the 12V rail, which is amplified in  $A_3$  with control of amplitude for span and offset for centre frequency. The discharge pulse from  $A_2$  for the integrator also goes to the oscilloscope as a timebase trigger.

Driven by the sawtooth, the Mini Circuits POS-400 voltage-controlled oscillator provides a linear voltage/frequency output over the 180-380MHz range and drives the SLB-1 double-balanced mixer



#### **CIRCUIT IDEAS**

## Electrostimulator

Droviding a constant-frequency, variable-amplitude train of pulses in response to a probe coming in contact with a low-resistance biological point, this circuit is also usable as a voltage detector or to measure resistance.

Oscillator  $IC_{1a,b}$  drives the monostable  $IC_{1c,2b}$ , this part of the circuit only operating when its voltage supply is provided by  $IC_{2a}$ . When the passive probe touches a biologically active point of low resistance, the output of  $IC_{2a}$  rises and turns on the oscillator, also opening gate IC<sub>1d</sub>. Oscillator pulses now pass, via the amplitude control  $R_4$ , to the probe, being prevented from affecting the rest of the circuit by  $D_1$ . Resistor  $R_2$  determines the input sensitivity and  $R_1$  and  $R_3$  are frequency and pulse width adjustments respectively.

To provide an indication of operation, particularly at low frequency, the  $IC_1$  oscillator modulates a second oscillator in IC2c.d, which drives the sounder, transistor and led.

Component values shown give a 10-150Hz train of 0.5 to 5ms pulses.

Vasiliy Borodai Zaporozhje Ukraine

8p2

173 3MHz

SAW resonator

47p

22µ

Tant +5V0

Murata SAR173.3MB40X

Ճ80nH

≲18k

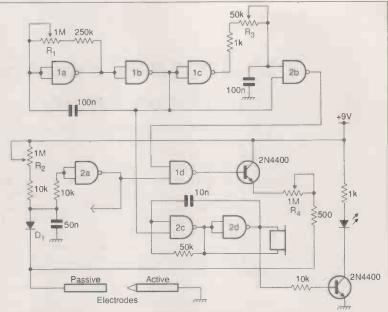
1

100n

33k

80nH

820R



Using c-mos ICs, this circuit emits a constant-frequency pulse train to stimulate biologically active points. No switching is needed, since it only operates when the probe touches the point.

directly, signal input to the mixer coming via the low-pass filter.

After filtering by the Toko 272MT-1127F, mixer output is impedance matched to the NE605. This device converts down to a standard if of 10.7MHz, the local oscillator being a saw type. A voltage proportional to the log. of the internally amplified 10.7MHz if appears at pin 7 of the NE605 and is buffered in  $A_4$  to be used as the oscilloscope input.

Symmetry of response is maintained by the CFSK ceramic filters, which also determine the bandwidth.

A limitation is the fairly slow response of the output of the NE605. It is usable, but reduces the amplitude of the display at faster sweep rates. It may be that the NE625, which is pincompatible and faster, would improve matters. **Givn** Roberts

> 100n 100

> > 560R

A4

Gain

221

Walsall West Midlands

**NE/SE605** 

820R

47k

BSSI

100k

390R2

560R

47p

CFSK107M5

8µ2H

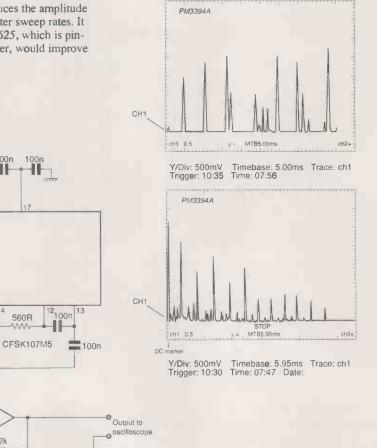
1n

an

1n

220

Spectrum of local fm broadcast band, 88 to 108MHz, top, and 20MHz square wave, demonstrating sweep linearity, bottom.



### 25-1025MHz signal generator with sweep facility

This very simply built generator is effectively a set of commercial voltage-controlled oscillators with some power and control circuitry. It provides good performance in a novel arrangement, which can be modified to suit individual needs.

Output is from  $50\Omega$  at 5dBm, varying about 1.5dBm over the frequency range, harmonics are at less than -20dBc and phase noise around -100dBc at 10kHz.

Two switched rails carry the tuning voltage, which may be adjusted on each by potentiometers or varied by an externally applied sawtooth for a sweep. A meter, driven by voltage followers, indicates the tuning voltage and therefore the frequency fairly roughly.

A set of seven oscillators from Mini Circuits covers the 25-1025MHz band in roughly 2:1 steps and forms the core of the circuit, each oscillator being followed by an attenuator to define the  $50\Omega$  impedance at the BNC outputs rather more exactly than do the oscillators. This also allows individual output levels to be adjusted, since they do vary somewhat. Again, the attenuators come from MiniCircuits.

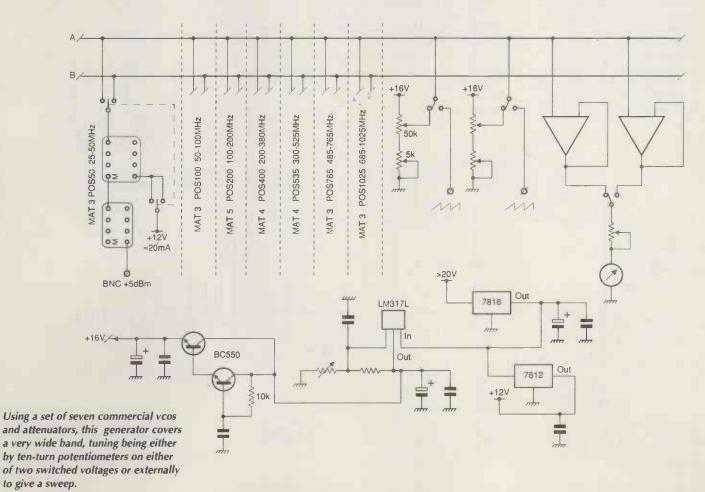
Since, even if all the oscillators were to be switched into circuit at the same time, current requirement would be only 140mA, the power supply need only be fairly modest, although the tuning voltage must be well filtered to maintain a low noise level.

A BICC-Vero Eurocard 03-2989L suits the circuit well. Note that a ground plane is essential. Björn Nilsson Mijas Spain

Make sure that V+ is as clean as possible. Decouple each tuning port pin with 10nF but do not use an electrolytic capacitor – ed.

#### Special offer to EW readers

Electronics World readers can obtain a set of oscillators for this design at £60.65 excluding VAT. This represents over 10% discount on the normal price. For each PATx surface-mount attenuator (MATx equivalent) required add £2.95 excluding VAT. Send your order requesting one KPOS2EW set plus any attenuators you want at £2.95 each, together with a cheque or postal order payable to Mini Circuits, to Mini Circuits Europe, Dale House, Wharf Road, Frimley Green, Camberley, Surrey GU16 6LF. Credit card orders are acceptable, Phone 01252 835094, fax 01252 837010.





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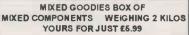
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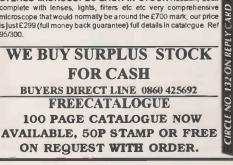
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## Simulation for mixed signals

Bashir Al-Hashimi explains how mixed-mode circuit simulation packages differ from their solely analogue or digital predecessors.

ircuit simulation packages have become an important part of the design and implementation cycle of electronic systems. The result is fewer prototypes, shorter design cycle, and significantly better quality products.

Simulation packages divide into three types: analogue, digital and mixed signal simulators. Almost all analogue simulators are based on the popular Spice – an acronym for simulation program with integrated circuit emphasis. Spice was developed in the 1970s in the University of California. This type of simulator predicts the frequency and time response of analogue circuits.

The simulation results are graphs of amplitude, phase against frequency in the case of frequency analysis and graphs of amplitude against time for transient analysis. This shows that Spice can be used to simulate the functions of network analysers and oscilloscopes in practice.

A digital simulator enables the designer to

perform a timing analysis of a digital circuit. The result is a timing diagram or a truth table of the circuit. In practice, this is the similar to using a logic analyser.

As circuits increase in complexity, it is likely that a mix of analogue and digital parts is used for implementation. To predict the performance of such circuits, mixed signal simulators are needed. This article aims to provide an introduction to this type of simulation through a detailed worked example. The simulator PSpice A/D from MicroSim<sup>1</sup> is used for demonstration purposes. For an introduction to circuit simulation and PSpice, read reference 2.

#### Types of mixed-signal simulator

Mixed signal simulators are basically divided into two types: native and glued. A glued simulator consists of a separate analogue and digital simulators combined through an interface software which controls data flow between the two simulators.

An example of glued simulator is

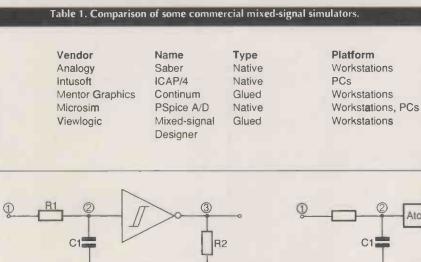


Fig. 1. In mixed-mode simulation, when a combination of analogue and digital components are used, an interface node occurs.

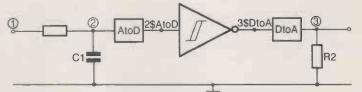


Fig. 2. This shows the circuit in Fig. 1 after PSpice has inserted a-to-d and d-to-a interface subcircuits.

*Continuum* from Mentor Graphics. Glued simulators are aimed primarily at systems with large number of analogue and digital parts. Also, they provide designer with the opportunity to integrate their favourite simulators.

A native simulator on the other hand consists of one simulator which performs mixed signal simulation. Examples are *PSpice A/D* and *Saber* from Analogy. When simulating systems that contain large analogue circuitry and small number of digital parts, a native simulator is usually a better choice. **Table 1** is a list of some commercially available mixed signal simulators.

#### Mixed signal simulator principles

Analogue simulators recognise only analogue nodes where all components connected to the node are analogue. Similarly, digital simulators deal only with digital nodes. A mixed signal simulator on the other hand recognises three types of nodes, namely analogue, digital and interface.

An interface node occurs when a combination of analogue and digital components are connected to it as shown in Fig. 1. Here, node 1 is an analogue node, while nodes 2 and 3 are interface nodes. A mixed signal simulator must translate interface nodes into purely analogue or digital nodes. The translation is achieved using different techniques depending on the simulator. The *Saber* simulator, for example, uses special models called Hypermodels for the translation.

The *PSpice A/D* simulator on the other hand, achieves the translation using 1-bit analogue/digital, a-to-d, and digital/analogue, d-

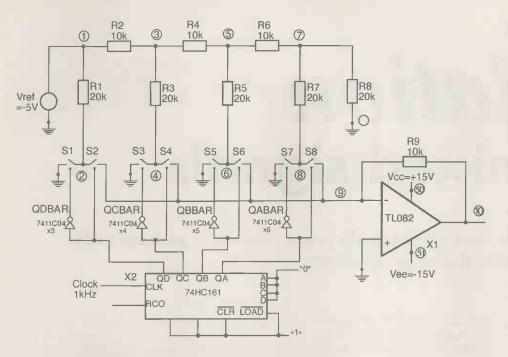


Fig. 3. Mixed-mode circuit example for producing ramp waveforms.

to-a, interface subcircuits. The function of both the hypermodels and the 1-bit a-to-d and d-to-a subcircuits is to change analogue voltages and impedances to digital states (0, 1, X, Z...) and *vice versa*. The simulator automatically inserts the appropriate subcircuits between analogue and digital parts.

For example, Fig. 2 shows the circuit of Fig. 1, after *PSpice* has inserted a-to-d and d-to-a

interface subcircuits. Nodes 2 and 3 are now purely analogue nodes. As Fig. 2 shows that the simulator has created two new digital nodes designated 2\$AtoD and 3\$DtoA. The *PSpice* symbol \$ represents new nodes occurring as a result of a-to-d and d-to-a interface subcircuits.

For more information on how *PSpice* creates and name these nodes, see reference 2.

#### **Entering circuit details**

In order to perform a circuit simulation, the circuit must first be described to the simulator. There are usually two methods of achieving this task, one a netlist, the other schematic capture. The choice of circuit entry depends largely on user preference, with both methods requiring some time to learn. However, it is generally accepted that understanding the basic rules of creating netlists often allow a better appreciation of the simulation process and principles in particular for analogue simulation.

The *PSpice A/D* simulator supports both types of circuit entry, with the dos version providing the netlist entry, while the windows version provides the schematic capture entry. In this article, the netlist method is used. Note, however, that the simulation of complex digital circuits requires the use of schematic capture. To demonstrate mixed signal simulation, consider the following example.

#### A mixed simulation example

**Figure 3** shows a circuit for producing ramp waveforms<sup>3</sup>. Outputs of the four-bit counter, QD QC QB QA, determine the position of switches  $S_1$ ,  $S_2$ ,  $S_3$ ... Logic zero connects the switch to ground, while logic one connects the switch to the inverting input of the amplifier.

The amplifier acts as a current-to-voltage converter. Here, the simulator is used to obtain the amplifier output voltage as the four-bit counter goes through its different 16 states. Listing 1 gives the *PSpice* netlist of the circuit. First consider the description of the analogue parts. The listing shows that the resistors

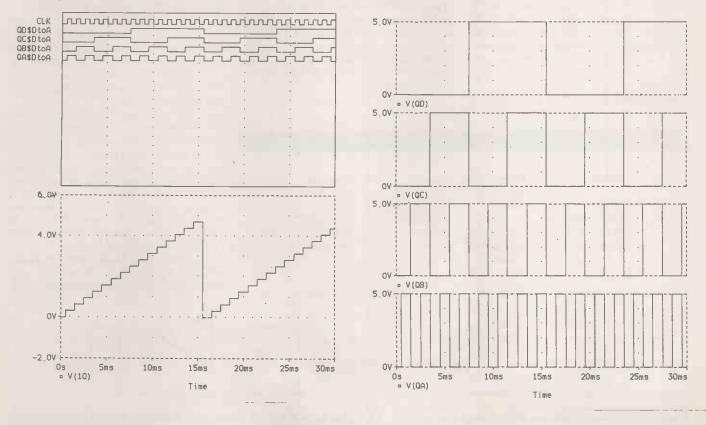
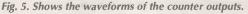


Fig. 4. The simulated digital and analogue signals of the circuit in Fig. 3.



are described using passive component description statements and the voltage reference  $V_{ref}$  is described using a dc independent source statement.

Op-amps are modelled in *PSpice* using X statements. In this example it is assumed that the *TL082* op-amp is used with  $\pm 15V$  power supplies. The model of the *TL082* device is obtained from the 'linear.lib' *PSpice* library. Switches  $S_{1-8}$  are voltage controlled and are modelled as follows. First the input, output, control nodes and model name of the switch are described using an S statement.

For example the input and output of the switch  $S_1$  are connected to nodes 2 and 0 respectively, while the control is connected to nodes 'QDBAR' with respect to ground. *PSpice* allows you to express nodes as numbers and/or names. For example, the control node of  $S_1$  has been given the name 'QDBAR', which has been chosen arbitrarily.

Attributes of a switch are defined using a .MODEL statement giving the optional parameters of the switch model. The model parameters are: on and off resistance, and the control voltage for on and off switch state. In this example, all switches have been modelled using the model name 'SW1' which has all its parameters set to their model default values.

Now consider the description of the digital parts of the circuit. *PSpice A/D* has an extensive digital models library including the 74xx ttl series and the 4000 cmos series. The library also has models of data converters and memory devices.

*PSpice* models digital devices using X statements. For example, the 74HC161 counter is defined by the X2 statement. To be compatible with practical digital devices, *PSpice* expresses the device nodes using names. The counter output nodes, for example, have been assigned the names QA QB QC QD, as shown in the X2 statement. Note that the parameters \$D\_HI and \$D\_LO in the statement represent a digital one and zero respectively. Finally, the inverters are defined using the X3,X4, X5 and X6 statements.

#### Simulating input/output

Having described the circuit, the next step is to define the circuit input(s), desired analysis type, and how to display the simulation output results. Clock signals are defined using the U statement as shown in the listing. It has been assumed that the counter clock is 1kHz, or 1ms period. The parameter STIM in the statement is the *PSpice* symbol for the stimulus generator. Statement (1 1) defines one signal of binary format<sup>2</sup>. Also, the parameters \$D\_DPWR and \$D\_DGND represent digital power supply and ground nodes respectively.

To simulate the output voltage of the amplifier as a function of time, a transient analysis is required. This type of analysis is specified using a .TRAN statement. The netlist shows the transient analysis is performed over a period of 30ms.

The .PROBE command generates a data file for viewing the simulation results graphically. Figure 4 shows the simulated digital and anaListing 1. PSpice netlist of mixed-mode ramp generator, Fig. 3. Ramp waveform generator, Fig. 3; comment line \* analog parts R1 1 2 20K R2 1 3 10K R3 3 4 20K R<sub>4</sub> 3 5 10K R5 5 6 20K R<sub>6</sub> 5 7 10K R<sub>7</sub> 7 8 20K R<sub>8</sub> 7 0 20K R<sub>9</sub> 9 10 10K ; resistors V<sub>ref</sub> 1 0 –5V ; reference voltage source X<sub>1</sub> 0 9 50 51 10 *TL082* ; op-amp description V<sub>cc</sub> 50 0 15V ; positive power supply Vee 51 0 -15V ; negative power supply .LIB c:\msim61\lib\linear.lib ; op-amp library S1 2 0 QDBAR 0 SW1 ; voltage controlled switch S2 2 9 QD 0 SW1 S3 4 0 QCBAR 0 SW1 S4 4 9 QC 0 SW1 S5 6 0 QBBAR 0 SW1 S6 6 9 QB 0 SW1 S7 8 0 QABAR 0 SW1 S8 8 9 QA 0 SW1 .MODEL SW1 VSWITCH [RON=1, ROFF=10M, Von=5V, Voff=0v] ; switch model \* digital parts X2 CLK \$D\_HI \$D\_HI \$D\_HI \$D\_HI \$D\_LO \$D\_LO \$D\_LO + QA QB QC QD RCO 74HC161 ; 4-bit counter X3 QD QDBAR 74HC04 ; inverter X4 QC QCBAR 74HC04 X5 QB QBBAR 74HC04 X6 QA QABAR 74HC04 .LIB c:\msim61\lib\74HC.lib; digital devices library .LIB c:\msim61\lib\dig\_io.lib ; AtoD & DtoA subcircuits library .OPTIONS DIGINITSTATE=0 ; clear digital devices . U1 STIM (1,1) \$D\_DPWR \$D\_DGND CLK IO\_STM TIMESTEP 0.5ms + 0c 0 + label=loop +1c1 + 2c 0+ 3c goto loop -1 times ; 1kHz clock .TRAN 0.02ms 30ms 0m 0.02m ; transient analysis range

.PROBE ; graphic outputs

.END ; end of netlist

logue signals of the circuit. The digital signals are the clock and the counter outputs, while the analogue signal is the amplifier output voltage. Note that the digital signals are expressed in terms of logic values (0 and 1), while the analogue signal is described in terms of voltage levels.

A number of interface nodes in the circuit of Fig. 3 occur when the counter digital outputs QD QC... and the inverter outputs QDBAR QCBAR... drive the control inputs of the analogue switches  $S_1$ ,  $S_2$ .... In this case *PSpice* automatically breaks these nodes into purely analogue nodes using digital/analogue inter-

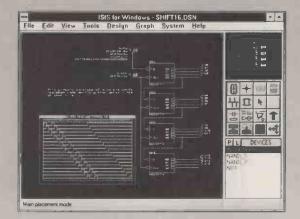
face subcircuits as mentioned earlier. Figure 5 shows the waveforms of the counter outputs. Note how *PSpice* changes the output from digital states 0, 1 (top waveforms, Fig. 4) into analogue voltages 0, 5V.

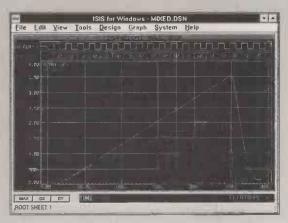
#### References

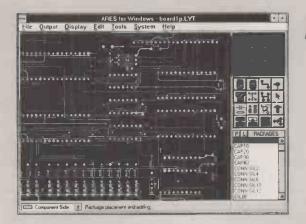
 MicroSim Corporation, Pspice A/D, 20 Fairbanks, Irvine, California 92718.
 Al-Hashimi, B, The Art of Simulation Using Pspice: Analog and Digital, CRC Press, ISBN 0849378958.
 Horowitz, P, and Hill, W., The Art of Electronics, Cambridge University press, 1st edition, pp. 411, 1980.



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## Schematic Capture

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#### A-to-D and D-to-A converters

High-speed a-to-d. SPT7730 and SPT7830 are two 3.3/5V 3Msample/s serial analogue-to-digital converters in 8-pin small-outline packages, recently introduced by Signal Processing Technology. The 7730 is an 8-bit, serial-output device, sampling at 3Msample/s, 7830 being a 10-bit type with a sample rate of 2.4Msample/s. Both are cmos devices with on-chip s/h and provide a reference settling time of 90ns. Signal Processing Technology. Tel., 01932 254904; fax, 01932 254903.

#### **Discrete active devices**

1GHz transistor. Motorola has the MRF5811LT1 rf n-p-n silicon transistor for low-power application at frequencies up to 1GHz. Dc gain on a 300µs pulse is 50-200 and fT typically 5GHz, collector/base capacitance at 10V and 1MHz being about 2pF. Noise figure at 50mA, 10V and 500MHz is 2dB. Motorola Semiconducteurs sa. Tel., 00 33 61 199981; fax, 00 33 61 199565.

#### Linear integrated circuits

Catv amplifier. For broadband, low-distortion application – and particularly for catv use - Motorola's MNN424B feedforward amplifier consists of two hybrid ampliers, couplers and delay lines in one package. It is a 750MHz maximum, 110-channel, 24dB power gain device, giving at least 20dB improvement over conventional catv amplifiers. Gain flatness is ±0.3dB up to 750MHz. Motorola Inc. Tel., 001 602 244-3831; fax, 001 602 244-6002.

#### **Memory chips**

Notebook dram. Mitsubishi's 3.3V or 5V dram MelCard comes in 4, 8, 16 and 32Mbyte form and is suitable for Toshiba, IBM, Compaq and some other notebook computers. The cards have 88-pin connectors and are compatible with JEIDA and JEDEC. Power consumption of the 3.3V type is 930mW. Gothic Crellon Ltd. Tel. 01734 788878; fax, 01734 776095.

#### Microprocessors and controllers

Very low-cost controller. Toshiba's new member of its TLCS-90 family of 8-bit microcontrollers is the TMP90CM38, which is much cheaper than Its TMP90CM36 pin-compatible stablemate, being a general-purpose device without specialised peripherals and timing. The TLCS core remains, providing a 163-instruction set, 16-bit arithmetic, minimum instruction time of 250ns at a 16MHz clock speed and dma functioning. Toshiba Electronics UK Ltd. Tel., 01276 694600; fax, 01276 694800.

Pentium replacement. Announced as a plug-in replacement for the Pentium, AMD's AMD5<sub>K</sub>86 chips, in P75 and P90 form, give the performance of the relevant Pentium chips according to the Ziff-Davis Winstone 96 P-rating tests and have been licensed to carry the Windows 95 logo. Advanced Micro Devices (UK) Ltd. Tel., 01483 740440; fax, 01483 756196

Starter kit. Texas offers the TMS370 8-bit microcontroller starter kit, which includes eprom/eeprom programming board and all software and literature. The kit may be connected to COM1 or COM2 pc ports by way of a standard RS-232C lead. Power needed is 5V at 500mA, Farnell Components Ltd. Tel., 0113 2636311; fax, 0113 2633411.

#### Mixed-signal ICs

Quad codec. AKM's AK2304A combines four conventional voice codecs in one 44-pin package and complies with CCITT G711/2 and AT&T D3/4 requirements. It is a selectable A-law/µ-law device operating from one 5V supply and dissipating about one-third the power of four codecs. There are internal opamps for gain adjustment and antialiasing and a 2.048Mb/s pcm highway interface. The device can be used in ST-bus or GCI interface systems and muting is done by toggling mute control pins. DIP International Ltd. Tel., 01223 462244; fax, 01223 467316.

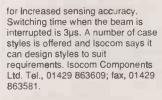
#### Motors and drivers

3hp servo amplifier. Copley Controls introduces the Model 5231 brushless servo amplifier which puts out ±30A -±15A continuous - to provide rapid acceleration and regenerative braking for motors up to 3.4hp. It operates at 25kHz, has a 3kHz bandwidth and copes with motors presenting a load of 0.2-40mH. Supply is 24-180Vdc, from which a four-quadrant supply is developed, and a current-sensing circuit gives an analogue output for monitoring. Two different boards are available to allow the amplifier to take brushless tachos, motor hall sensors or digital encoders to develop velocity feedback. Copley Controls. Tel., 001 617 329 8200; fax, 001 617 329 4055.

#### **Optical devices**

Photo-interrupter, Isocom's ISTS802 optical interrrupter switch has a 5mm slot and a 0.5mm aperture for the light

Surface-mount darlington. The Zetex FZT603 Darlington, an E-line device and SOT223 device, has a minimum  $h_{FE}$  figure of 5k at 500mA and 5V,  $V_{CBO}$  and  $V_{CE}$  of 100 and 80 and saturation voltage of 0.79V for 0.25A collector current and 0.25mA base current. Zetex plc. Tel., 0161-627 5105; fax, 0161-627 5467.



Lens holders. Melles Griot has a new range of bench lens holders for experimental work, which are fitted with easily distinguishable locking knobs and adjuster knobs. Not much more to say, really, except that the holders hold firmly and won't move until you move them. Melles Griot Ltd. Tel., 01223 420071; fax, 01223 425310

Lasers. A range of visible and infrared lasers is available from UV-Tec in wavelengths of 635, 650, 660 and 670nm at 5mW, near infrared wavelengths of 780, 830 at up to 30mW and 808nm at 5mW. There is also a self-contained lab, version with an emission indicator and power switch. UV-Tec Ltd. Tel., 01252 844880; fax, 01252 844885.



#### **Passive components**

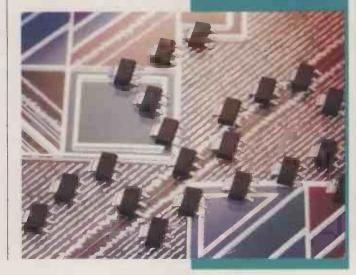
Chip thermistors. Taiyo Yuden has ntc chip thermistors rated at 63mW in size 0603 and made in values from 220 $\Omega$  to 150k $\Omega$ , although lower values can be supplied to order. The multilayer technique in use provides much less change in resistance than conventional glass-coated types. Thermal time is under 5s and heat dissipation constant 1-2.5mV/°C. Taiyo Yuden UK. Tel., 01494 464642; fax, 01494 474743.

#### Surface-mounted electrolytics.

Panasonic's VS Series of aluminium, s-m electrolytic capacitors, which are all 5.5mm high, covers the range  $22\mu$ F-220 $\mu$ F, 4V to 0.1 $\mu$ F-10 $\mu$ F, 50V. The VA series 50V types go up to 47µF and the 6.3V series has values of 1000µF, maximum ripple of 700mA at 120Hz and operating temperature of 85°C. These are wave-solderable. Flint Distribution. Tel., 01530 510333; fax, 01530 510275.

#### Audio products

Multimedia audio recording. AKM's AK4531 is a mixer codec for pc-based recording applications, having a twochannel, 16-bit audio codec and a two-channel, 18-bit digital-toanalogue converter, both with an



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86dB dynamic range. It has fivechannel stereo and three-channel mono playback mixers. Sampling rates are 4-50kHz for variable audio bandwidth and input can be down to -60dB. DIP International Ltd. Tel., 01223 462244; fax, 01223 467316.

#### **Connectors and cabling**

Miniature connectors. Amp Micro-MaTch connectors have a contact spacing of 1.27mm, the range including board and wire connectors to allow a variety of wire-to-board and interboard connections. Versions in the range are somewhat improbablesounding but, to quote, are "femaleon-board, top entry, side entry and surface-mount; male-on-board; maleon-wire; and paddle board connector". Contact springs are in the board connector rather than, as usual, In the cable connector. In the cable connector is a simple pin with

General-purpose dso range. Goulds's *600 Series* is a new range of digital storage oscilloscopes for general use. Three models have 100Msample/s sampling, 50,000 words of memory per channel, a colour display, built-In floppy drive, auto measurement and IEEE-488.2 and RS232 interfaces. Model *640* is a 150MHz bandwidth instrument which can acquire 'difficult' signals; *650* has a 400MHz bandwidth and is for showing fine detail-in wide band signals and *680* has 12-bit resolution and 150MHz bandwidth, with vertical zoom to give a 32 times expansion, or 62.5µV to 40V per division. *650* and *680* offer the option of a thermal plotter. Gould Instrument Systems Ltd. Tel., 0181-500 1000; fax, 0181-501 0116. either insulation-displacement section or a kinked solder leg, so separating and optimisIng the contact force generation and termination requirements. Gothic Crellon Ltd. Tel., 01734 788878; fax, 01734 776095.

Relay sockets. Inelco has a range of DIN sockets and bases for relays, mountable on DIN rails, printed boards and chassls and all having finger protection and low flammability material. Examples are a screw base for the two-pole 4.7/5mm blade plugin relays, which can be surface mounted or clipped to a 35mm DIN rall, rated at 240V ac, 10A; and a 14-pin base for 4-pco miniature relays, timers and controllers rated at 240V ac, 5A. Inelco Ltd. Tel., 01734 810799; fax, 01734 810844.

Chip sockets. Robinson Nugent's *TSOP* and *QFP* low-profile surfacemounted sockets are meant for ram, rom and other isi devices where replacement may be necessary. *TSOP* types have 28, 32 or 40 pins at lead spacings of 0.5, 0.55 and 1.27mm, *QFP* models are in 64 and 80-pin styles on a spacing of 0.8mm. Contacts are rated at 0.1A for the *TSOP* and 0.2A; breakdown 500V ac, insulation 1GΩ, contact resistance  $60m\Omega$  for the *TSOP* and 50mΩ. Robinson Nugent (Europe) Ltd. Tel., 01256 842626; fax, 01256 842673.

Test points. Glass-beaded, boardmounted test points by William Hughes consist of a colour-coded bead and phosphor bronze, tinned tag, with 1.3-2.03mm diameter loops for probe connection or to take other components; so raising them above the board surface. The tags are so shaped to avoid damage to throughhole plating and to keep the test points in position when the board is being flow soldered. William Hughes Ltd. Tel., 01963 363377; fax, 01963 363640.





#### Displays

Lcd/tft panel driver. IMS has a new multi-display video controller card, the *PCA-6653*, which simultaneously controls SVGA crt displays and flatpanel tft, dstn, mono lcd or electroluminescent types. It is register and bios-compatible with the IBM VGA standard and has a Windows graphics accelerator. There is onboard memory and a 256K by 16 dram socket to take an optional frame buffer. Integrated Measurement Systems Ltd. Tel., 01703 771143; fax, 01703 704301.

#### Hardware

Collet knobs. Ritel collet knobs are available in diameters from 8mm to 45mm in polyamide materlal and all offer a choice of style, colour and matt or gloss finish. Collets are ready assembled and fit a range of shaft sizes without the use of special tools. Accessories include shaped or flat caps with a variety of markings, polnters and arrow dials. Gothic Crellon Ltd. Tel., 01734 788878; fax, 01734 776095.

Enclosure framework. Widney Dorlec would like to point out that the 20/30 Series enclosure framework system, introduced in 1951, is still around. In fact, the company is currently tooling for more components to add to the 79 corner castings and 47 extrusion profiles already available. For the benefit of anyone who has been on Saturn for some decades, it is a set of extruded aluminium sections and corner shapes which are screwed together with concealed bolts to make a smooth cabinet, having been cut to size with a hacksaw. Widney Enclosures Ltd. Tel., 0121-327 5500; fax, 0121-328 2466.

#### Test and measurement

Emc and flicker meter. From Seaward comes the *Orb* harmonics and flicker meter, to test single-phase equipment rated at up to 16A to EMC Directive standards. It carries out

#### Navigation systems

GPS starter pack. From TDC comes a global positioning system starter pack, which is based on the Rockwell Microtracker LP receiver and which also contains a TDC evaluation board, magnetic car antenna, mains power unit, cable, batteries, manual and software. The TDC board provides the power and serial level conversion for the Microtracker and conditioned power for the antenna, output being over an RS232 port to a pc. Accuracy is within 5m, 95% of the time. If Autoroute Express, now swallowed up by Microsoft, is also bought from TDC, a GPS driver is supplied. Telecom Design Communications Ltd. Tel., 01256 332800; fax, 01256 332810.

Class A, B, C and D harmonic testing using Fourier analysis and flicker measurements are taken at up to 10min and 2h respectively. The instrument is pc-controlled and Is provided with a windows-based package to give features such as limit lines, pass/fail indication and many data display options. Test results are transferable to final report documents. Seaward Electronic Ltd. Tel., 0191-586 3511; fax, 0191-586 0227.

Infrared thermometer. Calex Instrumentation introduces the Convir Close Focus series of portable infra-red thermometers, which measure the temperature of objects down to 3mm diameter. Resolution is 1°C to within  $\pm$ 1%, with a response time of 350ms. The instrument is strong enough for factory floor use. Calex Electronics Ltd. Tel., 01525 853800; fax, 01525 851319.

Real-time/storage oscilloscope. VC-6555 by Hitachl is a 100Msample/s (two channels) and 100MHz bandwidth osclilscope, with 8Kword capacity for a single channel, delaying sweep and a counter. One-

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shot and Intermittent events are easily captured and a pre-trigger function shows the leading edge of a triggering waveform. Averaging reduces noise and sweep rate is automatically adjusted for the input frequency Output is available for hard copy and, via the RS232 Interface, for a po Hitachi Denshi (UK) Ltd. Tel., 0181 202 4311; fax, 0181-202 2451

GPS station clock. Nothing to do with BR, the 8820A GPS Station Clock, available from Steatite, is a time generator whose outputs are synchronised to within 100ns of UTC. It automatically tracks up to six GPS satellites, disciplines its own crystal or rubidium low-noise oscillator and synchronises its outputs to universal time, automatically accounting for leap years and seconds. Several time and frequency outputs are provided, as are two RS232 ports and an optional IEEE-488 port. Steatite Insulations Ltd. Tel., 0121-643 6888; fax, 0121-643 2011

Measuring amplifier. HBM has a small digital amplifier, for the measurement of mechanical quantities, that is for use in laboratory and mobile application. Scout55 operates at 4.8kHz, being connected



Lout-proof keypad. Numeric keypads in the C & K 4800 Series are sealed and gasketed to IP66 and have a 2mm stainless steel faceplate bolted to the polycarbonate body that holds the membrane, so that the average grunt would have a hard time doing them much permanent damage. The keys have click feel and 0.05-50mA, 1.5-30V dc ratings. Roxburgh Electronics Ltd. Tel., 01724 281770; fax, 01724 281650.

by the 6-wire technique to strain gauges, half and full bridge inductive transducers, plezoresistive and potentiometric transducers and linear variable differential transformers. It has a membrane keyboard, protected for hard use, and a ten-digit readout; its RS232C interface allows pc control. HBM United Kingdom Ltd. Tel., 0181-420 7170; fax, 0181-420 7336

Rso. Which Is to say, real-time and storage oscilloscope, Hitachi Denshl's family of which is now being completed by the introduction of the VC-6645. This Instrument is a 100Msample/s, 25msample/s (four-channel), 100MHz, 4Kword (single-channel) type with delayed sweep and a 100MHz frequency counter. A standard RS-232 Interface allows stored waveforms to be transferrred to a computer using Hitachl HIMES software and the memory contents are held for up to 10 days when power is switched off. Hitachl Denshi (UK) Ltd. Tel., 0181-202 4311; fax, 0181-202 2451.

Low-resistance measurement. Used in conjunction with one's own digital multimeter, the Sutronics Millo-Test 200 enables the measurement of resistance on a most sensitive range of 200mΩ. Inherent accuracy of the Millo-Test is typically 0.1%, but final accuracy depends on the dvm in use. A four-terminal bridge method is used, providing a guaranteed 0.2% accuracy at 20°C for the instrument itself, temperature coefficient being 0.02%/°C from 0°C to 40°C; best accuracy is at 20°C. Test current on all but the  $20\Omega$  range is 20mA. Sutronics. Tel./fax, 01929 426400.

#### Literature

Siemens semiconductors. Technical data on cd-rom from Siemens provides data sheets, s-parameters, curves and signal charts, together with the Microelectronic training centre, sales information, data for circuit simulation, technical articles and more. The disk is available for dos or Windows and can be installed In networks. There are also files for component comparison and a data retrieval system. BFI IBEXSA Electronics Ltd. Tel., 01622 882467; fax, 01622 882469.

Instrument hire. Livingston Rental, formerly Livingston Hire, has published its first catalogue under the new name. It contains much new equipment and a number of new services in the Instrumentation field The catalogue is free. Livingston Rental Ltd. Tel., 0181-943 5151; fax, 0181-977 6431

Data communications. Dataforth Corporation has issued a new catalogue of Industrial Data Communications Products which, in 50pp, provides full specifications, applications and installation data on modems, optical-fibre multiplexers and rack-mounted modems. Impulse Corporation Ltd. Tel., 01543 466552; fax, 01543 466553.

Thurlby Thandar. TTi has a new free catalogue of electronic test gear, which is all developed and made in the UK. New this time is the 1705 a 4.5-digit, dual-display multimeter with an RS-232 interface, true-rms ac measurement, frequency measurement and an optional GPIB interface. There is also a range of counters that handle up to 1.3GHz and a number of instruments for emc testing. Thurlby Thandar Instruments Ltd. Tel., 01480 412451; fax. 01480 450409.

Power supplies. From Computer Products, the 1996-7 Power Supply Product Handbook fully describes the company's range of ac/dc supplies, dc-dc converters and dc/ac ring generators, over 1200 in all, 800 of them new this time. Also on offer are three free technical guides on thermal management, safety regulations and emc and principles of power conversion. E-mail on jackie.day@cpipce.cpi.sprint.com. Computer Products, Power Conversion Ltd. Tel., 01494 883113; fax, 01494 883419

Farnell Components. You can order Farnell's new catalogue and obtain data on the Internet

(http://www.farnell.co.uk) or, if you suffer from technofear, the 'phone from 8am to 8pm. The 50,000 products, 6000 of them new ones, should satisfy most people's needs, since it includes everything from ordinary passive and active components to network and datacom equipment and top-end instrumentation. Farnell Components Ltd. Tel., 0113 2636311; fax, 0113 2633411.

#### Printers and controllers

Small print heads. Mitsubishi's WH Series 24V dc thermal print heads take the form of a small, flexible printed circuit with a connector, and are intended for incorporation into low-cost mini-printers. They are based on a thick-film process, cmos chips providing shift register, latch and switching functions. The heads are 5mm high and are in the form of a hard ic moulding, requiring no other cover, since the drive ics are epoxy coated. Print widths are 48mm, 72mm and 96mm in the three types available, with resolution of 8dot/mm and selectable speed of 3 or 10ms/line. Mitsubishi Electric UK Ltd. Tel., 01707 276100; fax, 01707 278692

#### **Production equipment** Workstations. Robert Bosch's ESD

range of workplaces are



#### **Power supplies**

Dc-to-ac converters. PROwatt inverters, which are CE-approved, convert battery power to 230Vac to allow mains equipment to be run from 12-24Vdc, these,new versions conforming to interference standards. The 150kand 250i units are in an aluminium case and connect to a 2 cgar-lighter socket or a terminal strip. socket or a terminal strip, socket or a terminal strip, providing the 230Vac via an IEC 320 socket on the case. The units cope with difficult loads, such as low-energy light bulbs, and overheating and overload protection is provided. Low battery voltage gives rise to an audible alarm and switch-off. *PROwalt* prices start at f 249 95 *PROwatt* prices start at £49.95. Merlin Equipment. Tel., 01491 824333; fax, 01491 824466.

electrostatically discharged to reduce the number of ics blown by voltages in excess of 100V, which can easily be developed by a worker who shuffles about a bit too much. The workplaces are designed to suit customers requirements in width and height and are provided with chairs, component containers, trolleys, shelves and a number of other features to reduce not only the shuffle factor but also injuries such as RSI and tendonitis. Robert Bosch Ltd. Tel., 01895 834466; fax, 01895 838548.

Adhesive printing. Loctite Varidot is a new stencil system which prints different heights of surface-mounting adhesive to suit different components in one pass of the squeegee. This is brought about by the use of a flexible stencil providing off-contact printing, which also avoids contaminating the underside of the stencil and therefore cleaning, except when the stencil is changed. Printed dot diameters can be as small as 0.3mm or up to 1.6mm. varying in height from 50microns to 0.6mm. Loctite UK Ltd. Tel., 01707 821000; fax, 01707 821200.

Transformer kits. For those occasions when no available transformer known to man will do the job, Electrospeed can now offer kits to make your own. Kits consist of a double bobbin section, half of it

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already wound with two independent 115V primaries, a pair of bobbin half shrouds, E and I laminations, end caps and all the other bits, including wire in 12 slzes from 0.2mm to 1.5mm diameter. Four kits cope with ratings of 20, 50, 100 and 200VA. There is a standard turns/V figure for each to give the wanted output voltage and the kits have full instructions and working examples. Electrospeed. Tel., 01703 644555; fax, 01703 610282.

Plug-in switchers. Relec's Mascot 9000 series of switched-mode power supplies are cased units plugging straight into a mains outlet and giving 10-40W outputs of 5-24Vdc. Line stabilisation is 0.1% and load regulation below 3% for all models. Output connection is a 2m cord with one of a selection of single or multiheaded jack plugs. Reflec Electronics Ltd. Tel., 01962 863141; fax, 01962 855987.

25W and 40W switching psus. XP announces the NAN 25 and NAN 40 low-cost, universal ac input switchers, which use a fixed switching frequency to allow them to meet EN55022 emi specifications. The range of modules provides outputs from 5V to 48V in

#### PCMCIA card. Amplicon Liveline's *PCM DAS08* and *DAS16* PCMCIA data acquisition cards fit type II and type III expansion slots in portable computers. Suppied with card-socket services and universal driver software, the cards have have a 12-bit analogue input and automatic configuration on insertion. *DAS 08* takes eight bipolar, 12-bit analogue. ±5V inputs, gives digital i/o and samples at 3.12, 6.25, 12.5 and 25kHz, selectable in software, while *DAS16* provides 16

analogue input and automatic configuration on insertion. DAS 08 takes eight bipolar, 12-bit analogue. ±5V inputs, gives digital i/o and samples at 3.12, 6.25, 12.5 and 25kHz, selectable in software, while DAS16 provides 16 bipolar/unipolar inputs from ±10V to ±1.25V and from 0-10V to 0-1.25V, with eight digital i/o and three 16-bit counters. It also has a high-speed driver for the Labtech Notebook Pro. Amplicon Liveline Ltd. Tel., 0800 525 335 (free); fax, 01273 570215. singles and various arrangements of 5V, 12V and 15V in duals and triples. Input is universal 90-264Vac, overvoltage and overcurrent protection is present and the units measure 5 by 3 by 1.2in. XP plc. Tel., 01734 845515; fax, 01734 843423.

Network ups. MaxiMiser from Galatrek is a range of single and three-phase uninterruptible power supplies covering the 5-15kVA output band and Intended for large lans, midrange systems, servers and data processing centres. Their non-volatile memories store up to 5000 parameters to give a history of ups and mains activity, the result being passed by RS232 or a front-panel lcd. Regular battery tests are run automatically or when a panel button Initiates a test and the units adjust their chargers to suit the battery temperature. Galatrek International Ltd. Tel., 01492 640311; fax, 01492 641828

#### Radio communications products

Satcom frequency converters. Anglia Announces the Zeta 6160 range of frequency converters to convert communications signals from and to the microwave bands used by satellites. Zeta 6163 converts 70, 140 or 700MHz ifs to an intermediate C-band signal tunable between 5850 and 6425MHz, with phase noise at 85dBc/Hz for 10Hz offset, and is therefore usable as a standalone Intelsat-C converter. This output will drive the 6161 band-selectable block up-converter for conversion to X-band or Ku-band for DSCIII and Intelsat. Reverse conversion is carried out by the 6160 and 6162 units. Anglia Microwaves Ltd. Tel., 01277 630000; fax, 01277 631111

#### **Protection devices**

SM transient suppressors. Semitron SMBJ series transient voltage suppressors are surface-mounted devices rated at 600W and providing picosecond turn-on and low on impedance. With ratings of 5V to 170V, in unidirectional and bidirectional form, peak transient current in avalanche mode is 2.2A to 62.5A for 170V and 5V devices





respectively, while In the forward direction, the devices withstand 100A for 8.3ms. Flint Distribution. Tel., 01530 510333; fax, 01530 510275.

#### Switches and relays

Time-delay relays. Matsushita offers the *TR/TS* ultraminiature time-delay relays, which will switch  $10^{-10}$  to 1kVA on each of four separate contacts arranged in varlous forms of open and closed. Each *TS* contact will carry 5A at 250V, although the relays measure only 34 by 34 by 10.8mm. Both are available for conventional on/off delay timing and, for off delay, no extra power supply is needed. Using either an Internal trimmer or an external pot., timing is adjustable from 0.1 to 1000s. The relays are available in 5, 12 or 24Vdc operation. Matsushita Automation Controls Ltd. Tel., 01908 231555; fax, 01908 231599.

Switch lens caps. EAO-Highland offers a range of lens caps to make its *EAO Series 96* tamily of illuminated, push-button switches look better. The lenses are rounded and come in black(?), red, green, grey, bright orange and blue. There are versions with recesses for one or two leds and for momentary or maintained operation. EAO-Highland Electronics Ltd. Tel., 01444 236000; fax, 01444 236641.

Sealed keyboard. Announced by Fairchild Is the *KBM Series* of metalcased keyboards sealed to IP65 standard and provided with a tracker ball. They come in a variety of forms, for both desk-top use and to mount vertically in a panel and are compatible with IBM AT or PS/2, the serial output from the tracker ball suiting Windows applications. Keys have a positive feel with 1.4mm movement and the front panel is chemical resistant. Fairchild Ltd. Tel., 01703 211789; fax, 01703 211678.

Automotive relays. Han-Kuk's *HR*-*AMR* series of board-mounted relays for cars provide 40-60A switching in a 26 by 22 by 22mm package, sealed or open, accepting 6-24Vdc. Life is said to be in excess of 10<sup>7</sup> operations. Inelco Ltd. Tel., 01734 810799; fax, 01734 810844.

#### Transducers and sensors

Shaft encoder. Digipots are simple, self-contained shaft encoders,

PC radio receiver card. Rosetta Laboratories of Australia make the *WinRadio* radio receiver card and software for the pc. The card plugs into a slot in the motherboard and contains a processor-controlled wideband receiver with antenna, speaker and headphone connectors. It covers the 500kHz-1.3GHz range-in tuning steps-from 1kHz to 1MHz and handles am, fm-w, fm-n and ssb at 1µV sensitivity. Being Windowsbased, a 'front panel' is displayed on-screen to give full control in the normal way. A scanning facility is provided and there is a database of over 300,000 frequencies, which can be extended by the user. Screening has received much attention to allow the receiver to operate inside the pc. Lowe Electronics Ltd. Tel., 01629 580800; fax, 01629 580020.

designed for use in x/y detection, motor speed monitoring, pick-andplace of components and many other areas. They are non-contacting panelmounted types, producing a twochannel, quadrature digital output proportional to rotation at speeds up to 10,000rev/min. Power needed is under 40mA at 5V. Line counts on the internal disc are from 96 to 2048 per revolution, with an optional index. Accessories include line-driver cards and power supplies. Control Transducers. Tel., 01234 217704; fax, 01234 217083.

#### Vision systems

Graphics accelerator. Ark Logic offers the ARK2000MT 64-bit graphics and video acclerator, which supports the graphics functions such as BITBLT, line draw, pattern-BLT, colour expansion and raster-ops used by graphics user interfaces. Resolutions are from 640 by 480 to 1600 by 1200 and colour depths 4-24bits/pixel, depending on the amount of dram installed and the resolution. It will accept YUV video from a software decompression utility and perform colour space conversion and scaling of the video image to full screen size, interfacing with both PCI and VESA local bus motherboards. The board comes with a set of drivers. Amega Technology Ltd. Tel., 01256 330301; fax, 01256 330302.

### COMPUTER

### Computer board-level products

3U single-card pc. On a single 3U VME bus card, Ovation's VME 486 PC supports all standard pc i/o functions such as keyboard interface, two serial i/o ports, Centronics/parallel i/o interface, floppy and hard disk interfaces and a high-resolution VGA display. An optional module allows up to 16Mbyte of dram in simms, Ethernet connection and dual-port static ram expansion to 1Mbyte. Ovation Systems Ltd. Tel., 01844 279638.

Single-board computer. Apex II from Blue Chip is a single-board computer for industrial and embedded applications, having processor, video and peripherals on one 5V board. It takes 486SX up to P24T processors and provides a 16Mbyte maximum dram memory in 72-pin simm form. There is 1Mbyte of flash memory to give solid-state disk storage, and two further sockets for more of the same. Local bus SVGA video control has 512Kbyte of vram to give 640 by 480 colour lcd. Blue Chip Technology. Tel., 01244 520222; fax, 01244 531043.

#### Data acquisition

Modular, PC-compatible system. Yokogawa's DARWIN, a modular family of data acquisition instruments, will compose a complete data-logging system from a range of input measurement and scanning modules, output modules such as computer interfaces and alarms, and hard-copy recording. Each system may be specified as a stand-alone unit with up to 40 channels or as an expandable system with from 10 to 300 channels. The standard software handles data logging and configuration, while an enhanced package is available that provides trends, bar graphs, panel-meter-type display and alarms. Built-in maths functions allow for signal processing before measurements are passed to the pc. Martron Instruments Ltd. Tel., 01494 459200; fax, 01494 535002.

### Development and evaluation

Thermal development. Redpoint Thermalloy has a design kit containing a selection of active and passive heatsinks, materials and accessories, with data, to help with the thermal management of microprocessor-based designs. The kit includes the Thermalloy Cooling Module, which is a pin-fin type with a fan, in 5V and 12V versions. It all comes in a carrying case. Redpoint Thermalloy Ltd. Tel., 01793 537861; fax, 01793 615396.

#### Software

Emc measurement, ESxS-K1 from Rohde & Schwarz Is a Windowsbased package for emc measurement in small and mediumsized companies. It supports R & S emi test receivers and eases the user's task by providing dialogues and masks for entering data. Features Include single-keystroke measurement, graphic display of test results and scan data. comparison of limit lines with peak search function and average-value detection. Rohde & Schwarz UK Ltd. Tel., 01252 811377; fax, 01252 811447

High-level language debugger. Noral Micrologics offers the *Flex* universal, real-time embedded systems debugger for Windows, which incorporates an integrated macro language and editor for 8-bit, 16-bit and 32-bit applications. It operates independently of hardware providing the Information from the embedded system and can be used with in-circuit emulators and background debug mode hardware, rom monitors and simulators for use In the future. It is also independent of file formats. Noral Micrologics Ltd. Tel., 01254 682092; fax, 01254 680847.

Industrial control. From PC Soft International comes Wizcon 5, a Scada package in true 32-bit Windows 95 native code. (Scada is short for 'supervisory control and data acquisition'.) It is designed for use in both stand-alone applications and in systems for manufacturing and management information, including such applications as control and supervision of processing and manufacture, building automation and public utilities. New features In v.5 are online diagnosis and de-bugging and cluster libraries of animations for many processes. The company offers the package with no extras, all options being included. PC Soft International. Tel., 01233 503838; fax, 01233 513687.

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In the second extract from his book Simplified design of micropower and battery circuits, John Lenk shows how to apply the MAX712/713 and other ICs in a wide variety of charging circuits.

## er back in

f you read Part I of this article in the March issue, you should have a good understanding of how the *MAX712* and *713* work. These are highly integrated charger ICs specifically designed for use with NiCd and NiMH cells.

Putting the

Here is a basic simplified design procedure for using these ICs – and others – in practical circuits. The following steps assume that the maximum power dissipation is not exceeded in your application, that the charge current does not exceed 600mA, and that the battery stack has 11 cells or fewer.

**Check recommendations:** Follow the battery manufacturer's recommendations for maximum charge currents, as well as charge-termination methods for the specific batteries in an application. **Table 1 provides** some general guidelines. When the charge rate is greater than 2C, use both temperature and voltage-slope/time. With charge rates below C/2, use the *MAX712* for NiMH batteries. Use the *MAX713* for all NiCd applications.

**Decide on a charge rate:** A charge **rate** of C/3 (where C is the battery capacity) charges the battery in about 3h. Current in milliamps required to charge at this rate is calculated as:

IFAST=(capacity of battery in mAh)/(charge time in hours)

Depending on the battery, charging efficiency can be as low as 80%, so a C/3 fast-charge could take 3h 45min. This has nothing to do with the efficiency of the IC, but reflects the efficiency with which electrical energy is converted to chemical energy within the battery.

Choose an external dc power source: An example of this is a wall-cube. Minimum output voltage, including ripple, must be greater than 6V and at least 1V higher than the maximum battery voltage.

Know the power dissipation: Calculate the worst-case power dissipation of the power p-n-p transistor  $Tr_1$  and diode  $D_1$  in Fig. 2, "Putting the power back in, Part I" *EW*, March, pp. 223-228) in watts, using:

#### PD=(max wall-cube voltage, loadedmin battery voltage)×(charge current in amps)

**Make sense**: If the calculated power dissipation exceeds the maximum; if the battery stack has more than 11 cells, or if the charge current exceeds 600mA, calculate  $R_1$  and  $R_{\text{SENSE}}$  as described in Part I. Otherwise, calculate the values of  $R_1$  (in

 $k\Omega$ ) and  $R_{SENSE}$  (in  $k\Omega$ ) as follows:

 $R_1 = (minimum \ wall - cube \ voltage - 5V)/5mA$ 

then.

#### $R_{\text{SENSE}} = 0.25 \, \text{V} / (I_{\text{FAST}})$

Check pin-straps: Consult Tables 2 and 3 to determine the pin-strap settings. For example, with a battery of six cells, both PGM0 and PGM1 (pins 3, 4) should be left open. For a charge time of 90min with the charge-slope limit enabled, PGM2 and PGM3 (pins 9, 10) should be connected to REF (pin 16).

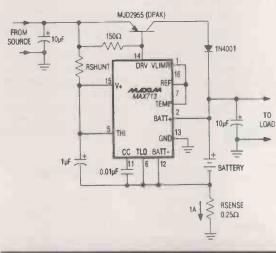


Fig. 1. NiCd/NiMH charger with step down regulator (Maxim Battery Management Circuit Collection, 1994, p. 2).

### Table 1. End of charge. Termination methods for fast-charge controllers

(Maxim New Releases Data Book, 1994, p. 4-55).

Charge	NiMH cells	NiCd cells
>2C	DV/Dt and	DV/Dt and
	temperature	temperature
	Max712/3	MAX713
2C to C/2	DV/Dt and/or	DV/Dt and/or
	temperature	temperature
	Max712/3	MAX713
<c 2<="" td=""><td>DV/Dt and/or</td><td>DV/Dt and/or</td></c>	DV/Dt and/or	DV/Dt and/or
	temperature	temperature
	Max712	MAX713

#### Simple fast-charger with linear-regulator

Figure 1 shows the MAX713 connected to provide a fastcharge with linear regulation to both NiCd and NiMH batteries.

Note that Fig. 1 is similar to Fig. 2 in Part I. The major difference is that the external pass transistor in Fig. 1 is a MJD2955 and the resistor at pin 15 (V+) is called  $R_{SHUNT}$ instead of  $R_1$ , as in Fig. 2, Part I.

The circuit of Fig. 1 solves two closely related problems found in powering small portable systems – firstly charging the battery and secondly switching over from battery power to ac power when an external ac-to-dc adaptor is plugged in. The *MAX713* supplies the system load current while the battery is being charged by sensing and dynamically regulating the battery current.

Using a linear regulator instead of a switch-mode circuit is a good approach for small systems: palm-top computers having low-voltage ac-to-dc adaptors and low-wattage battery packs with 5V, 9V, and 12V outputs are common examples. The linear regulator approach is also effective for battery back up in non-portable systems, such as large file servers.

The choice between linear and switch-mode is usually a matter of what is an acceptable power dissipation in the regulator pass transistor. For instance, fast-charging three 750mAh NiCd cells from 9Vdc at a 1C rate produces a worst-case dissipation of about 5W. This dissipation is too high for most hand-held applications.

The MAX713 must be programmed for the desired number of cells and charging time. Use the pin straps, as described above, with Tables 2 and 3. The circuit will charge up to 16 cells.

Operating area of the MAX713/MJD2955 circuit, Fig. 2, shows that if the input-output differential can be kept low, the operating current – i.e. charging current plus load current – can be 1A. Input voltage range is battery voltage plus 1V, up to 20V, with a 5V minimum. Supply current when not charging is  $5\mu$ A maximum. Charging current is limited only by maximum power dissipation PD, and efficiency is battery voltage divide by source voltage multiplied by 100%.

For example, if the supply voltage is 6V, used to charge a 3V battery, efficiency is  $3/6 \times 100 = 50\%$ .

Where heat-sinking is not practical, fast-charging large batteries in compact enclosures raises the problem of temperature rise. The battery-charger current source must have adequate efficiency to prevent temperature rise. This usually

> means some form of switch-mode current source, if the charging plus load currents – i.e. operating current – is greater than about 1A.

#### Table 2. Number of cells.

Programming the number of cells for fast-charge controllers (Maxim New Releases Data Book, 1994, p. 4-56).

No of cells	PGM1	PGMO
1	V+	V+
2	open	V+
3	REF	V+
4	BATT-	V+ 1
5	V+	open
6	open	open
7	REF	open
8	BATT-	open
9	V+	REF
10	open	REF
11	REF	REF
12	BATT-	REF
13	V+	BATT-
14	open	BATT-
15	REF	BATT-
16	BATT-	BATT-

Fast-charger with switch-mode current source

The MAX713 can be connected as a switchmode regulator to provide a fast-charge for both NiCd and NiMH batteries, Fig. 3. The operating area of the switch-mode circuit, Fig. 4, shows the input voltage range is battery voltage plus 1.5V, up to 20V, with a 7V minimum. Efficiency is 80% with an input of 12V and two cells being charged at 1A. Note that the circuit of Fig. 3 is programmed for two cells, with PGM0 strapped to V+; PGMI open, and for a timeout of 90min, i.e. PGM2 and PGM3 strapped to RET.

Control loop for the circuit is a variablefrequency type, which senses and regulates current through the battery. Battery current is measured by the  $0.08\Omega$  resistor ( $R_{\text{SENSE}}$ ), and this sense signal is compared to an

#### Table 3. Maximum charge time.

Programming the maximum charge time for fastcharge controllers (Maxim New Releases Data Book, 1994, p. 4-56).

Timeout	A-to-d t <sub>A</sub>	Slope	PGM3	PGM2
(min)	sampling (seconds)	charge limit	pin	pin
22	21s	Disabled	V+	open
22	21s	Enabled	V+	REF
33	21s	Disabled	V+	V+
33	21s	Enabled	V+	BATT-
45	42s	Disabled	open	open
45	42s	Enabled	open	REF
66	42s	Disabled	open	V+
66	42s	Enobled	open	BATT-
90	84s	Disabled	REF	open
90	84s	Enabled	REF	REF
132	84s	Disabled	REF	V+ ·
132	84s	Enabled	REF	BATT-
180	168s	Disabled	BATT-	open
180	168s	Enabled	BATT-	REF
264	168s	Disabled	BATT-	V+
264	168s	Enabled	BATT-	BATT-

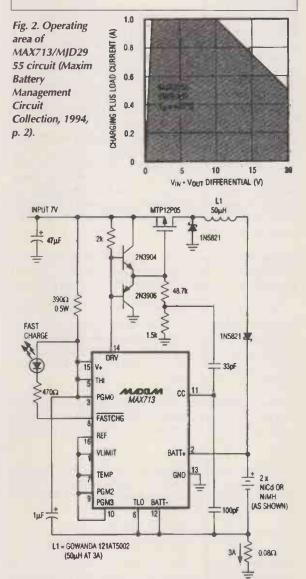


Fig. 3. NiCd/NiMH charger with step-down regulator (Maxim Battery Management Circuit Collection, 1994, p. 3).

#### **ANALOGUE DESIGN**

internally generated 250mV threshold. The difference is amplified by a gain of eight, and the resultant error signal appears at the current-sense amplifier output on the CC pin.

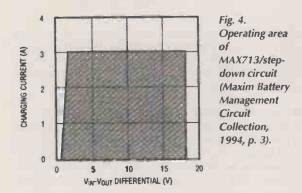
A second high-gain stage between CC and DRV compares the error signal to the MAX713 + 2V reference, switching the MTP12P05 p-channel fet on or off to regulate battery current.

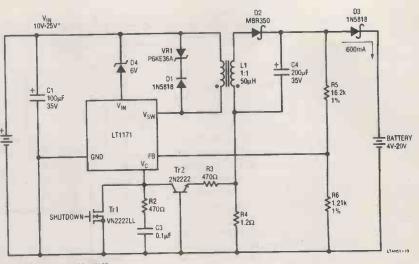
The circuit operates in switch-mode rather than in the linear mode because of hysteresis introduced by the feedback divider and 33pF capacitor connected to CC. The capacitor injects charge into the CC node each time the p-channel fet turns on or off. This raises the error signal slightly above or below the +2V reference, and overdrives the second gain stage to ensure a fast-switching drive signal to the fet.

Current available for charging is 3A. This is determined by the value of  $R_{\text{SENSE}}$  connected at the BATT- pin (0.25/3A=0.08 $\Omega$ ).

Lower currents allow smaller external components. For example, for a 1A charger,  $R_{\text{SENSE}}=0.25/1\text{A}=0.25\Omega$ . A 1A Schottky such as the *1N5818s* can be substituted for the *1N5821s*, and a Sumida *CD75470* surface-mount inductor can be substituted for the Gowanda part. The Sumida inductor has a value of 47µH and is capable of carrying 1A,

Also, higher input voltage can be accommodated by adding a level-shifter between DRV and the fet driver transistors (2N3904/2N3906) and changing the  $390\Omega$  shunt resistor value.





LOWER INPUT VOLTAGES MAY BE USED BY REDUCING D4 VOLTAGE.

#### **Constant-current battery charger**

A Linear Technology LT1171 can be connected for fly-back operation to provide a constant-current battery charger, Fig. 5. Note that this circuit can be used for either NiCd or NiMH technologies. It does not detect when full battery charge is reached. Nor does the circuit indicate a full charge. However, it does have an important advantage – battery voltage can be higher or lower than the input voltage. This is because of the fly-back configuration.

For example, a 16V battery stack may be charged from a 12V automobile battery. Charge current is sensed by  $R_4$  and set at about 600mA. Resistors  $R_5$  and  $R_6$  limit the peak output voltage when no battery is connected.

Diode  $D_3$  prevents the battery from discharging through the divider network when the charger is off. Transistor  $Tr_1$  provides for electronic shutdown of the charger (if needed).

#### **Dual-rate battery charger**

The *1171* can also be connected to provide a dual rate battery charger, Fig. 6. Again, the circuit can be used for either NiCd or NiMH cells, but is it does not detect when full battery charge is reached. Also, the input voltage must be higher than

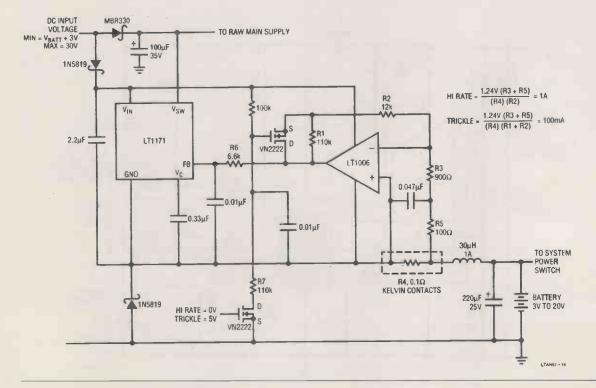
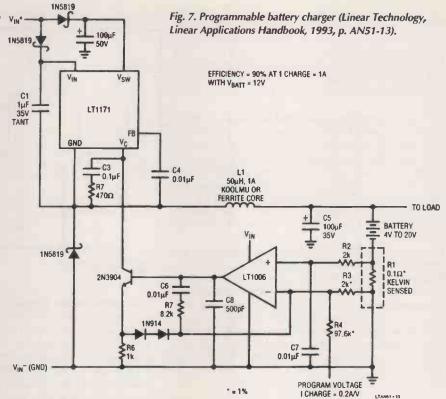


Fig. 6. Dual-rate battery charger (Linear Technology, Linear Applications Handbook, 1993, p. AN51-12).

Fig. 5. Constantcurrent battery charger (Linear Technology, Linear Applications Handbook, 1993, p. AN51-11). DC INPUT VOLTAGE MINIMUM TO START =  $V_{BATT}$  + 3V MINIMUM TO RUN =  $V_{BATT}$  + 2V MAXIMUM = 35V

the battery voltage for charging to occur. The primary advantage of this charger is efficiency – at around 90% when charging at maximum output current. Because of this efficiency, no heat sinks are needed on either the LT1171 or the diodes.

A logic signal causes toggling between a highcharge rate, up to 2A, or a trickle rate. An *LT1006* amplifier senses the current in the battery and drives the feedback pin of the *LT1171*. The entire control circuit is bootstrapped to the *1171* and floats at the switching frequency. This means that stray capacitances must be minimised in component layout.



A transistor sets the gain on the LT1006 by shorting or opening resistor  $R_1$ . For the values shown, this changes the charge rate between 100mA and 1A.

#### Programmable battery charger

The *LT1171* can be connected to provide a programmable charger for use with either NiCd or NiMH batteries, Fig. 7. This circuit does not detect when full battery charge is reached, and the input voltage must be higher than the battery voltage.

But the charging current is directly proportional to the program voltage, which can be controlled digitally via d-to-a converters if desired. A small sense resistor between the bottom side of the battery and its ground senses battery charging current. This is compared with the program voltage. From this comparison, a feedback signal is developed to drive the LT1171 V<sub>C</sub> pin, thus controlling the charge current. Typical efficiency during high charge is 90%, thus eliminating the need for heat sinks in most applications.

#### Four-cell regulator/charger for NiCd cells

It is possible to connect the LTC1155 dual power-mosfet as a four cell charger/regulator, Fig. 8. The 1155 has the ability to deliver 12V of gate drive to two n-channel power mosfets when powered from a 5V supply with no external components. This ability, coupled with micropower current demands, makes the LTC1155 well suited for high-side

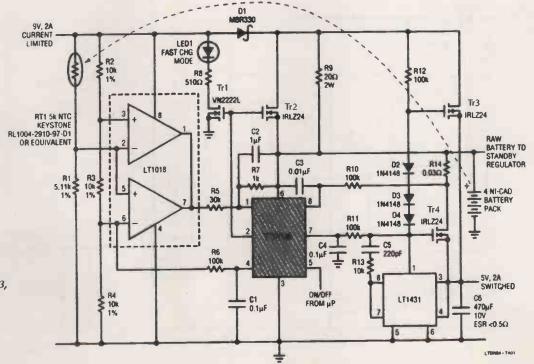


Fig. 8. Four-cell NiCd regulator/charger (Linear Technology, Linear Applications Handbook, 1993, p. DN51-1).

Fig. 10. Charge

**Applications** 

AN37-2).

characteristics for

NiCd charger (Linear

Technology, Linear

Handbook, 1990, p.

Fig. 11. Low resistance

shunts for Kelvin

Technology, Linear

Handbook, 1990, p.

sensing (Linear

**Applications** 

Fig. 12. NiCd

grounded batteries

(Linear Technology,

Linear Applications

Handbook, 1990, p.

charger for

AN37-2).

AN37-4).

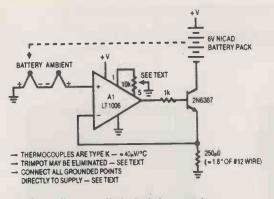


Fig. 9. Thermally-controlled NiCd charger (Linear

Technology, Linear Applications Handbook, 1990, p. AN51-11).

switching applications. These generally require more expensive p-channel mosfets.

The circuit is well suited for a notebook-computer powersupply system powered by a four-cell nickel-cadmium battery pack. Such a charger consumes very little board space when the LTC1155 and three power mosfets are housed in SO packages. But  $Tr_3$  and  $Tr_4$  must be provided with proper heat sinks.

One-half of the LTC1155 is controls the battery-pack charging. The 9V, 2A current-limited wall unit is switched directly into the battery pack through an extremely low-resistance mosfet switch,  $Tr_2$ . Gate-drive output pin 2 from the 1155 generates about 13V of drive to fully switch both  $Tr_1$ and  $Tr_2$ . Voltage drop across  $Tr_2$  is about 170mV at 2A, so it can be surface mounted to save board space.

Inexpensive thermistor  $RT_1$  measures the battery temperature and latches the LTC1155 off when the temperature rises to 40°C. This is done through operation of the LT1018 window comparator.

Input to the LT1018 is determined by the  $RT_1$  resistance, which, in turn, is controlled by battery temperature. When the temperature rises to 40°C, drain-sense input of the 1155, pin 1, goes low. Use of a window comparator between the RT<sub>1</sub> thermistor and the 1155 also ensures that very cold battery packs below 10°C are not quick-charged.

Transistor  $Tr_1$  drives an indicator lamp during quick-charge to let the computer user know that the battery pack is being charged. When the battery temperature rises to 40°C, the 1155 latches off, and the battery-charge current flowing through  $R_9$  drops to 150mA.

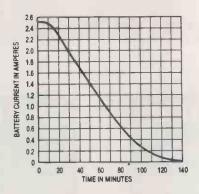
A four-cell NiCd battery pack produces about 6V when fully charged, dropping to about 4.5V when the batteries are nearly discharged.

The second half of the 1155 provides gate-voltage drive, pin 7, for a low-voltage drop mosfet regulator. The LT1431 controls the gate of  $Tr_4$  and provides a regulated 5V output when the battery is above 5V. When battery voltage drops below 5V,  $Tr_4$  acts as a low-resistance switch between the battery and the regulator output.

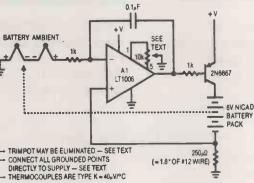
A second power mosfet,  $Tr_3$ , connected between the 9V supply and the regulator output, by-passes the main regulator when the 9V supply is connected. This means that the computer power is taken directly from the ac line while the charger wall unit is connected.

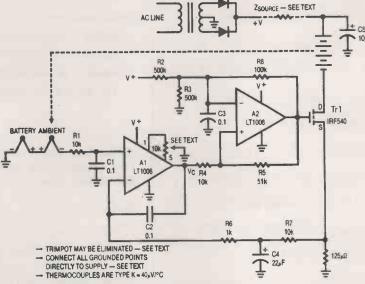
Regulation for both  $Tr_3$  and  $Tr_4$  is provided by LT1431 which also maintains a constant 5V at the regulator output. Diode string  $D_{2.4}$  ensures that  $Tr_3$  conducts all of the regulator current when the wall unit is plugged in by separating the two gate voltages by about 2V.

Resistor  $R_{14}$  acts as current sensor for the regulator. When voltage drop between the second drain-sense input, pin 8, and the supply, pin 6, rises above 100mV, the regulator latches off at 3A. Resistor  $R_{10}$  with  $C_3$  provides a short delay, and



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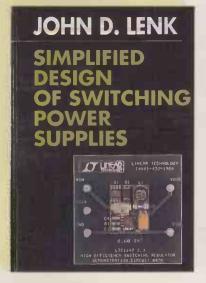


the microprocessor can restart the regulator by turning the second input, pin 5, off and then back on.

When the battery voltage drops below 4.6V, the regulator is switched off by the microprocessor. Stand-by current for the 5V 2A regulator is less than 10µA, and the regulator is switched on again when the battery voltage rises during charging.

Fig. 13. Switch-mode thermal NiCd charger (Linear Technology, Linear Applications Handbook, 1990s, p. AN37-3).

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Power dissipation within the notebook computer is generally quite low. As a result of fast-charging the battery pack, the current-limited wall unit dissipates most of the power. Transistor  $Tr_2$  dissipates less than 500mW, while resistor  $R_9$ dissipates about 700mW.

Transistor  $Tr_4$  dissipates about 2W for a very short period when the batteries are fully charged but dissipates less than 500mW as soon as the battery voltage drops to 5V. The three ICs dissipate little power, though  $Tr_3$  can dissipate as much as 7W if the full 2A output current is required and the unit is powered from the wall unit.

#### Thermally-based NiCd-cell charger

Thermocouples can be used to sense cell and ambient temperatures simultaneously. Figure 9, shows such an arrangement and Fig. 10 its charge characteristics. The LT1006 amplifier,  $A_1$ , furnishes the amplification necessary for microvolt-level thermocouple signals.

To understand operation of the circuit, assume that the battery pack is discharged. The battery thermocouple is directly mounted on one of the cells in the pack, while the ambient thermocouple is thermally insulated and mounted on a mass. This mass may be a frame or other part of the equipment. Both thermocouples are at the same temperature, and both produce the same voltage.

Under these conditions, the thermocouples are phasematched, negative to negative, as shown. Their outputs cancel, and A<sub>1</sub> sees an input of OV.

The  $10k\Omega$  offset-adjustment trimmer is set to introduce enough input-offset so that the  $A_1$  output swings positive, turning on the transistor. Current flows from the supply, through the battery pack, and to ground via the  $250\mu\Omega$  shunt. The low-impedance shunt minimises losses, cost, and complexity.

Voltage across the shunt rises to about 625µV, which is the amount of off-set set by the potentiometer. This voltage is fed back to inverting input minus of  $A_1$  and forms a basic amplifier-servo loop. The loop controls about 2.5A through the battery pack.

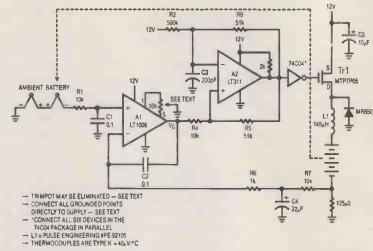
INPUT

10V-25V

Low-resistance shunts can be constructed in a simple, inexpensive way using a small length of wire or a cir- VOLTAGE cuit-board trace, Fig. 11. The type and length of wire determines the shunt resistance, which can be altered to produce the desired charging characteristics. Figure 11 also shows the details for wire and circuit-board shunts. In both wire and pcb-track cases, the shunt should have separate Kelvin style connections for sensing so that the high current does not affect the readings.

The battery heats as it charges and this heat is picked up by the batterymounted thermocouple. Temperature difference between the two thermocouples determines the voltage, appearing at the  $A_1$  non-inverting input. As battery temperature rises, this small negative voltage becomes larger. Note that a 1°C difference between the thermocouples equals  $40\mu$  V. Amplifier  $A_1$ gradually reduces the current through the battery pack to maintain a balance between the inverting and non-inverting inputs.

The effect of this action over time, Fig. 10, is that the battery charges at a high rate until heating occurs, and then the circuit tapers or slopes the charge.



Circuit values given in Fig. 9 limit the battery surface-temperature rise over ambient to about 15°C.

In a thermally based NiCd charger for use with batteries committed to ground, Fig. 12, the transistor is connected as a common emitter, so the inputs to amplifier  $A_1$  are reversed. However, operation is the same as for the thermally controlled NiCd charger circuit.

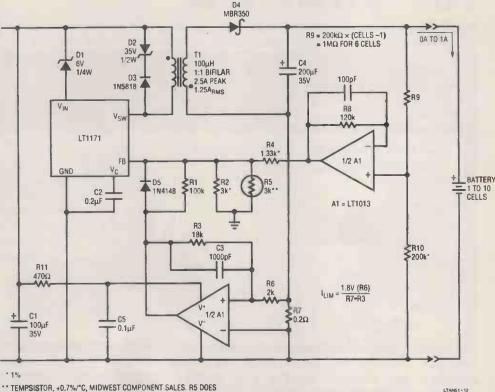
Note that in Figs 9 and 12, the trimmer may be eliminated by specifying an LT1006 set at manufacture to the desired offset value. The small shunt-sense voltage, of a few hundred microvolts at most, requires a high-quality ground for accurate results. This ensures that the large current flow through the transistor does not combine with ground-return impedances to create errors. The servo cannot tell the difference between voltages developed across a poor ground and those produced by the shunt.

In practice, all returns should be brought directly back to the supply common terminal.

Figures 9 and 12 both force the transistor to dissipate some power, particularly in the middle of the charge curve, and

Fig. 14. Switchmode thermal NiCd charger, lowimpedance source (Linear Technology, Linear Applications Handbook, 1990, p. AN37-4).

Fig. 15. Lead-acid battery charger (Linear Technology, Linear **Applications** Handbook, 1993, p. AN51-10).



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heat may be a problem in very small enclosures. This is typical of many micropower circuits.

A circuit can be designed to eliminate this problem – though requiring a much more elaborate configuration, **Fig.** 13. This circuit is similar than the other circuits, except that an additional IC,  $A_2$ , is placed between  $A_1$  and the output transistor  $Tr_1$ .

Op-amp  $A_2$  functions as a duty-cycle modulator. Transistor  $Tr_1$  – a power fet in this case – operates in the switched mode, delivering duty-cycle modulated-current pulses to the battery pack.

The *RC* network of  $R_7/C_4$  filters the switching waveform to dc. Resistors  $R_6$  and  $R_7$  present a balanced source impedance to  $A_{11}$  and capacitor  $C_2$  sets gain roll-off.

The circuit relies on the source impedance of the wall transformer to limit current through  $Tr_1$  and the battery pack. This parameter may be set when specifying the transformer.

If the charging source has low impedance, a circuit can be used where the output is essentially a step-down switching regulator, **Fig. 14**. The 74C04s provide phase inversion, and drive, for  $Tr_1$ , which is a p-channel mosfet.

#### Lead-acid battery charging

Lead-acid rechargeable gel cells are attractive because of their high energy-density-per-unit volume. They have a long life expectancy when treated properly, but often suffer premature failure because of improper charging.

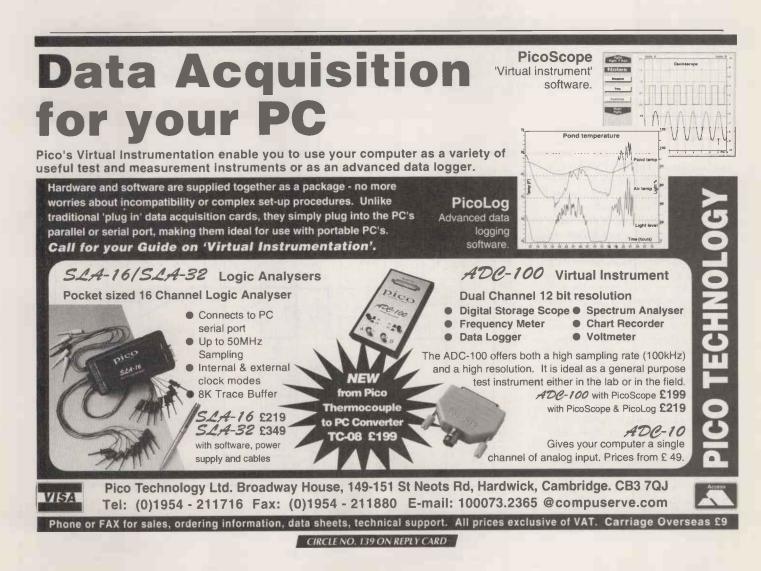
A charging circuit, **Fig. 15**, needs precise non-linear temperature compensation, constant-voltage charging with constant-current over-ride, and high efficiency over a wide range of input and battery voltage.

The basic charger is a fly-back design to allow operation with input voltages above or below battery voltage. Switching IC *LT1171* operates at 100kHz and can deliver up to 15W into the battery. A dual op-amp is used to control constant voltage and constant current modes.

Acting as a current limiter,  $A_1$  turns on when charging-current through  $R_7$  exceeds a present limit determined by  $R_3$ ,  $R_6$ , and  $R_7$ . This current limit is included to prevent excess charge current for heavily discharged batteries. Losses in  $R_7$ are kept low because the voltage drop across  $R_7$  is kept to several hundred millivolts.

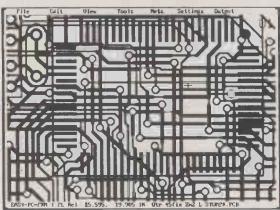
Lead-acid batteries have a non-linear negative temperature coefficient, which must be accurately compensated to ensure long battery life and full charge capacity. Resistor  $R_5$  is a linear positive-temperature-coefficient thermistor. This characteristic is converted to the required non-linear characteristic by parallel connection with  $R_2$ . Combination  $R_2$ ,  $R_3$ , and  $R_4$  multiplies the 1.244V feedback level of the *LT1171* to the proper 2.35V level required by one cell at 25°C.

One-half of  $A_1$  is used as a buffer to drive the resistor network. This allows large resistors,  $R_9$  and  $R_{10}$ , to be used for the cell-multiplier string. Resistor  $R_9$  is set at 200k $\Omega$  for each series cell over one. Current through  $R_9$  is only 12µA, so  $R_9$ can be left permanently connected to the battery. Resistor  $R_{10}$ is added to give the charger a finite output resistance of about 25m $\Omega$  per cell in a constant-voltage mode to prevent low-frequency hunting.



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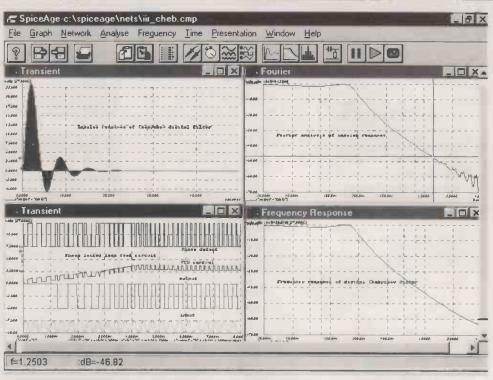
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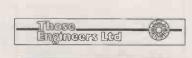
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ANNIE SO ME YOA TOOM2 THICFOWAVE REquency cou	£1500
BRUEL & KJAER 1023 sine generator	£1250
BRUEL & KJAER 1027 sine random generator	£1750
BRUEL & KJAER 2033 single channel audio spectri	
analyser	£2500
BRUEL & KJAER 2619 preamplifier	£250
BRUEL & KJAER 2511 vibration meter (field set will	th
1621 filter)	£1500
BRUEL & KJAER 2307 level recorder	£1000
BRUEL & KJAER 2317 portable level recorder	£1500
BRUEL & KJAER 2607 measuring amplifier	£600
BRUEL & KJAER 2609 measuring amplifier	£750
BRUEL & KJAER 2308 analogue X-Y pen recorder	
CHASE LFR 1000 interference measuring receiver	
150kHz	£1000
DATRON 1061 & 1061A - various, digital multimeter	
1065 - call from DATRON 1065 digital multimeter all ranges plus IEE	n £500
DATHON 1005 digital multimeter all ranges plus ice	£500
FARNELL 2081/100 100W RF power meter DC-500	
(1GHz)	£200
JJ INSTRUMENTS CR600 2-channel pen recorder	£250
FARNELL PSG2400A signal generator 100KHz-2,4GHz	£3500
0 0	
TEKTRONIX 2232 100MHz 100MS/2 digital storage oscilloscope	£2000
TEKTRONIX 2245A 100MHz oscilloscope	£1100
PHILIPS PM5167 1mHz-10MHz function generator	£275
PHILIPS PM8272 X-Y & Y-t dual-channel pen record	
DACAL DOOR outematic modulation mater	£850 £350
RACAL 9008 automatic modulation meter RACAL-DANA 9300 milli-voltmeter	£350 £400
RACAL-DANA 9301A true RMS RF milli-voltmeter	£350
SYSTRON DONNER 1300 synthesized signal gene	
100Hz-1GHz GPIB	£1350
TEKTRONIX AA501 / SG505 distortion analyser	
(complete with TM503)	£1250
TEKTRONIX P6303 o'scope probes NEW 250MHz	
X1/X10 with readout pin	£50ea
TEKTRONIX 2465 option CTS oscilloscope	£2000
TEKTRONIX P6201 FET PROBE	£350
WANDEL & GOLTERMANN WM30 level tracer	£500
WANDEL & GOLTERMANN PJM-4S jitter meter for	05500
SONET & SDH	£5500
WAVETEK 23 synthesized function generator 0.01H	
12MHz WAVETEK 1067 opt 522 1-500MHz sweep generate	£1250
WAYNE KERR 3220 20A bias unit (for 3245 inducta	JI 2300
analyser)	£1250
WAYNE KERR 3245 inductance analyser	£3000
TEKTRONIX 1502B/03/04 short-range metal-cable 1	
tester	£3500
TEKTRONIX 1503 tdr metallic-cable tester with opts	03/04
	£1000

#### HEWLETT PACKARD



90254		
	1640B serial data generator	£500
	3561A dynamics signal analyser (opt 01	) £5500
3764A	digital transmission analyser	£2000
3335A	synthesizer/level generator	£2000
3400A	voltmeter, analogue 10Hz-10MHz	£250
3235A	switch/test unit	£1000
3324A	synthesized function generator	£2000
3456A	digital multimeter	£750
3580A	audio frequency spectrum analyser £750	to £1250
3581C	selective voltmeter	£1250
358 <b>2A</b>	dual-channel spectrum analyser 0.02Hz-2	5.5kHz
		£2000
3779D	primary multiplex analyser	£3000
	pA/meter, DC voltage source	£4000
4339A	high resistance meter c/w lead set 16117E	\$ £2000
4275A	multi-frequency lcr meter	£3500
435B n	nicrowave power meter, analogue	£400
5334B	frequency counter w option 010 high-stab	&
Chann	el C	£1500
5386A	3GHz frequency counter	£1500
	A 1GHz digitizing oscilloscope	£2250
	power supply 0-60V 0-50A 1000W	£650
	system power supply 0-20V 0-30A	£1000
	dual power supply 0-20V 0-1A twice	£250
	power supply 0-120V 0-2.5A	£400
6825A	bipolar power supply/amplifier -20V to +20	
		£350
	pulse generator 100MHz	£950
	serial date generator	£1000
	pulse generator 250MHz	£2000
	pulse generator 20MHz	£1250
816A s	lotted line 1.8-18GHz with 809C & 447B p	
		£500
	tracking generator with option 059	£1250
	spectrum analyser 100Hz-1.5GHz	£7500
	synthesized signal generator to 990MHz	£3000 £7500
	2-18GHz synthesized signal generator A gain-phase analyser 100kHz-300MHz	£7500 £6500
	modulation analyser with option 02/010	£3500
	audio analyser	£2000
	A FDDI portable multimode test set	£1500
	A 486-based, colour option main-frame	£1000
	VJ2171A 486-based colour screen option	
advisor		£4000
	A ethernet/token ring interface (for J2302A	
020007		£3000

#### TOP OF THE RANGE EQUIPMENT ALWAYS WANTED FOR STOCK AND STANDING ORDER REQUIREMENTS. TOP OF THE RANGE PRICES PAID



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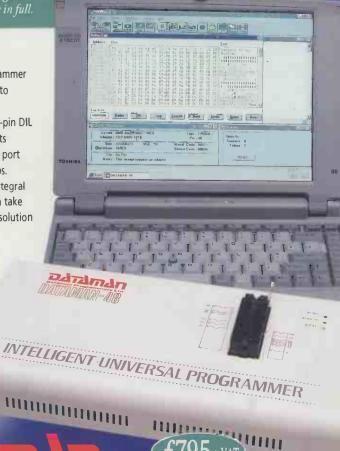
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